# Projection theorems for linear-fractional families of projections

Joint work with A. Lukyanenko (GMU Fairfax)

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### Orthogonal projections

Let  $L \subset \mathbb{R}^2$  be a line (i.e. one-dimensional linear subspace) and  $P_L : \mathbb{R}^2 \to L$  the orthogonal projection onto *L*.

Given a Borel set  $A \subset \mathbb{R}^2$  Borel with dim A = s $\rightarrow$  dim  $P_L(A) = ?$ 

Trivially:

- dim  $P_L A \leq 1$
- dim  $P_L A \leq s$

Are these good bounds?

 $\rightarrow$  Yes!



### Marstrand's theorem (in $\mathbb{R}^2$ )

**Theorem** [Marstrand 1954]. Given a Borel set  $A \subset \mathbb{R}^2$ , then for  $\mathscr{H}^1$ -almost every  $\theta \in [0, \pi)$ 

 $\dim P_{\theta}A = \min\left\{1, \dim A\right\}$ 

equivalently ...

$$\mathscr{H}^{1}\left\{\underbrace{\theta \in [0,\pi) : \dim P_{\theta}A < \min\left\{1, \dim A\right\}}_{:=E}\right\} = 0$$

Note the *exceptional set E* depends on the choice of Borel set *A*.

This result generalizes to higher dimensions...

#### The Grassmannian of *m*-planes

Let G(n, m) be the family of *m*-planes in  $\mathbb{R}^n$  (called the *Grassmannian*)

- G(n,m) is a smooth manifold of dimension k := (n-m)m.
- The notion of ℋ<sup>s</sup>-zero sets on G(n, m) is well-defined (for all s ≥ 0)
- Hence the notion of Hausdorff dimension is well-defined.
- $\mathscr{H}^k$ -zero sets in G(n, m) are also zero sets of the measure  $\sigma_{n,m}$  on G(n, m) that is induced by the Haar-measure of O(n), and vice-versa.)

#### Projection theorems for orthogonal projections

 $P_V: \mathbb{R}^n \to V$  orthogonal projection,  $V \in G(n, m)$ .

Let  $A \subset \mathbb{R}^n$  a Borel set, dim A = s > 0.

• Marstrand 1954, Mattila 1975:

$$\begin{split} & \text{If } s \leq m, \ \mathscr{H}^k \{ V \in G(n,m) : \dim P_V A < s \} = 0 \\ & \text{If } s > m, \ \mathscr{H}^k \{ V \in G(n,m) : \mathscr{H}^m(P_V(A)) = 0 \} = 0 \end{split}$$

- Kaufman 1968, Mattila 1975:
   If s ≤ m, dim{V ∈ G(n, m) : dim P<sub>V</sub>A < s} < s. (In fact, this works for 0 < α ≤ s by later results.)</li>
- Falconer 1982:

If s > m, dim $\{V : \mathscr{H}^m(P_L(A)) = 0\} \le (n-m)m + m - s$ 

• Besicovich 1939, Federer 1945:

If  $\mathscr{H}^m(A) < \infty$ , then A is purely *m*-unrectifiable if and only if  $\mathscr{H}^m(P_V(A)) = 0$  for  $\mathscr{H}^k$ -a.e.  $V \in G(n,m)$ 

### Projection theorems for various spaces

There are analogs of the results on the previous slides in various settings...

- horizontal resp. vertical projections in the Heisenberg group
- families of radial or point-source projections
- orthogonal projections in Hyperbolic space and on the (half-) sphere
- closest point projections induced by norms in  $\mathbb{R}^n$
- projections theorems for different notions of dimension
- sharpness results for many of the above
- special families of projections ("what is the structure of E?")

• ...

Many(!) authors have worked on the above.

-> see e.g. the great survey articles by Mattila from 2004 and 2015.

#### A more general framework...

Let  $k, m \in \mathbb{N}, k \geq m$ .

Let  $\Omega$  be a compact metric space and  $\Lambda \subset \mathbb{R}^k$  a open.

Consider a continuous mapping  $\Pi : \Lambda \times \Omega \to \mathbb{R}^m$ .

We think of  $\Pi$  as a family of mappings (*projections*)

$$\Pi_{\lambda} := \Pi(\lambda, \cdot) : \Omega \to \mathbb{R}^m, \ \lambda \in \Lambda$$

with parameter space  $\Lambda$ .

**Example**: Orthogonal projections onto *m*-planes in  $\mathbb{R}^n$ .

(Choose  $\Lambda$  to be a coordinate chart of G(n, m) and identify *m*-planes *V* with  $\mathbb{R}^m$  by an isometric isomorphism smootly in G(n, m).)

Theorem [Peres and Schlag, 2000].

If the mapping  $\Pi$  is sufficiently *regular* and (locally) *transversal*, then the family of mappings  $\Pi_{\lambda}$ ,  $\lambda \in \Lambda$  satisfies all the projection theorems of the previous slide. (The Bes-Fed theorem is due to Hovila 2014.)

Regularity: We assume that  $\Pi$  is  $C^L$ -smooth for some  $L \ge 2$ . (This assumption is stronger than necessary but will simplify things.)

<u>Transversality</u>: For all  $v \neq w \in \Omega$  and  $\lambda \in \Lambda$ , define:

$$\Phi(\lambda, v, w) := \frac{\Pi(\lambda, v) - \Pi(\lambda, w)}{|v - w|}$$

The family  $\Pi$  is transversal if there exists C > 0 so that for all  $\lambda, v, w$ :

$$|\Phi(\lambda, v, w)| \leq C \Rightarrow \left| \det[\mathsf{D}_{\lambda} \Phi(\lambda, v, w) (\mathsf{D}_{\lambda} \Phi(\lambda, v, w))^{\mathsf{T}}] \right| \geq C^{2}$$

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Special case k = m = 1

$$|\Phi(\lambda, v, w)| \le C \implies |\mathsf{d}_{\lambda} \Phi(\lambda, v, w)| \ge C$$

 $\rightarrow$  <u>Intuition</u>: if *v* and *w* are (close to) collapsed into one point by  $\Pi_{\lambda}$ . Then as  $\lambda$  is varied, the images of *v* and *w* under  $\Pi_{\lambda}$  separate quickly.

For a family of projections  $\Pi : \Lambda \times \Omega \to \mathbb{R}^m$ :

<u>Lemma 1</u>: Local transversality is preserved quantitatively under  $C^2$ -smooth change of coordinates:



(This can be considered a folklore Lemma. We prove a formal version in I.-Lukyanenko, Arxiv2021.)

#### A different perspective on Marstrand...

Let us restate Marstrand's theorem in  $\mathbb{R}^2$ :

instead of projecting a set A onto a varying line L, rotate the set A and project onto a fixed line, that is, ...

Let  $\pi : \mathbb{C} \to \mathbb{R}$  be defined by  $\pi(x) = \operatorname{Re}(x)$  (the base projection) Let  $R_{\lambda} : \mathbb{R}^2 \to \mathbb{R}^2$  be the counterclockwise (family of motions) rotation by angle  $\lambda \in \Lambda = (0, \pi)$ .

Define the projection family  $\Pi_{\lambda} : \mathbb{C} \to \mathbb{R}$  by  $\Pi_{\lambda}(x) = \pi(R_{\lambda}(x))$ .

Then Marstrand's theorem states as follows: for every Borel set  $A \subset \mathbb{R}^2$ ,

$$\mathscr{H}^{1}\{\lambda \in \Lambda : \dim \Pi_{\lambda}(A) < \min\{1, \dim A\}\}) = 0$$

**Question:** What if we move *A* around by a different group of motions that occur naturally in a geometric context?

#### Families induced by Möbius transformations

Consider the family of projections  $\Pi : M\ddot{o}b \times \hat{\mathbb{C}} \to \mathbb{R}$  given by

 $\Pi(g,z) = \operatorname{Re}(g(z)).$ 

Its domain is  $\operatorname{M\"ob} \times \hat{\mathbb{C}} \setminus \{(g, g^{-1}(\infty)) : g \in \operatorname{M\"ob}\}$ 

**Theorem 1.** (I.-Lukyanenko, Arxiv2021)  $\Pi$  :  $M\ddot{o}b \times \hat{\mathbb{C}} \to \mathbb{R}$  is locally transversal and therefore satisfies projection theorems on its domain.

<u>Lemma 2</u>: transversality is preserved if enlarging the family (as a product) <u>Proof:</u> write  $D_{\lambda}\Phi$  in the definition of transversality as block matrices.

Theorem 1 now follows from the fact that transversality holds for the family induced by O(2) since  $O(2) \subset M\ddot{o}b$  a Lie subgroup.

**Question:** What about Lie subgroups  $\Gamma \subset \text{M\"ob}$ ?

#### Families induced by Möbius transformations

Let  $\Gamma \subset \text{M\"ob}$  be a Lie subgroup.

Consider the family of projections  $\Pi: \Gamma \times \hat{\mathbb{C}} \to \mathbb{R}$  given by

 $\Pi(g,z) = \operatorname{Re}(g(z)).$ 

Its domain is  $\Gamma \times \hat{\mathbb{C}} \setminus \{(g, g^{-1}(\infty)) : g \in \Gamma\}$ 

<u>Note</u>: transversality is in general not preserved when passing to smaller families -> We have to actually do some work here!

Assume  $\Gamma$  is <u>1-dimensional</u>.

Let us write  $\Gamma$  in terms of an element  $A = (a_{ij})$  in the Lie algebra  $\mathfrak{sl}(2, \mathbb{C})$ :

$$\Gamma = \{\gamma_t = \exp(At) : t \in \mathbb{R}\}\$$

Two examples





 $\Gamma \sim_{SL(2,\mathbb{C})} O(2)$ 



 $\Gamma$  is a loxodromic motion (non-compact)  $\Gamma \sim_{\text{M\"ob}} \{ z \mapsto e^{(a+ib)t} z : t \in \mathbb{R} \}$ 

For  $\Gamma = \{\gamma_t = \exp(At) : t \in \mathbb{R}\}$  1-dim Lie subgroup of Möb, and  $\Pi : \Gamma \times \hat{\mathbb{C}} \to \mathbb{R}$  the projection family given by  $(\gamma, z) \mapsto \operatorname{Re}(\gamma(z))$ wherever  $\gamma(z) \neq \infty$ ,

Theorem 2. (I.-Lukyanenko, Arxiv2021)

 $\Pi$  is locally transversal precisely away from the closure S of the set

$$\{(\gamma_t, z) : \operatorname{Im}(a_{11} - a_{21}\gamma_t(z)) = 0, \ t \in \mathbb{R}, \ z \in \widehat{\mathbb{C}}\},\$$

Proof:

- Lemma 3: the nice geometry of our setting implies: it suffices to check transversality for  $\gamma_t = id$  (i.e. at t = 0).
- Linearize  $t \mapsto \Pi(\gamma_t, x)$  using Taylor expansion of exp
- Establish transversality at t = 0 (hands-on estimates)

Question: What about projection theorems?

Combining Theorem 2 with Peres and Schlag's Theorem yields: projection theorems hold wherever we have  $\text{Im}(a_{11} - a_{21}\gamma_t(z)) \neq 0$ , where  $A = (a_{ij})$  is the Lie algebra element generating  $\Gamma$  by  $t \mapsto \exp(At)$ .

If  $a_{21} = 0$ , then  $\Gamma$  preserves  $\infty$  and:

- if Im(a<sub>11</sub>) = 0, then (S = Γ × Ĉ and more importantly) Γ consists of translations and dilations. projection theorems fail completely.
- if  $\text{Im}(a_{11}) \neq 0$ , then  $\Gamma = O(2)$  and projection theorems hold.

If  $\underline{a_{21} \neq 0}$ , consider the compactified line  $L = \{z : \text{Im}(a_{11} - a_{21}z) = 0\}$  in  $\widehat{\mathbb{C}}$ , that is, the portion of the closure or *S* that comes from t = 0.

Note that  $\gamma_t(\infty) \in L$  and *L* is tangent to the orbit  $\Gamma(\infty) = \{\gamma_t(\infty) : t \in \mathbb{R}\}$  at  $\gamma_0(\infty) = \infty$ .





There are three cases:

- (bad case) *L* is a vertical line and *L* = Γ(∞): projection thms fail for subsets of *L* (*L* is projected to a single point) but hold elsewhere.
- (good case) L is non-vertical and equals the orbit Γ(∞): the restriction
  of the projection to L is a similarity mapping, so Hausdorff measure and
  dimension is preserved along L.
- (artifact case) L ≠ Γ(∞): any sufficiently small set inside L will be moved away from L by γ<sub>t</sub> after some time. Thus projection thms hold.

This proves the following theorem...

#### Theorem 3. (I.-Lukyanenko, Arxiv2021)

Let  $\Gamma \subset \text{M\"ob}$  be a one-dimensional Lie subgroup, and  $\Pi : \Gamma \times \hat{\mathbb{C}} \to \mathbb{R}$  the family given by  $\Pi(\gamma, z) = \text{Re}(\gamma(z))$ . Then  $\Pi$  satisfies projection theorems, with the following natural exceptions:

- If  $\Gamma$  consists of Euclidean dilations and translations, then projection theorems fail globally.
- If the orbit  $\Gamma(\infty)$  is a vertical line, then projection theorems fail along this line.

### More results and final remarks

In our paper (I.-Lukyanenko, Arxiv2021), we also cover:

- Analogs of Theorems 1, 2, and 3 for real-linear fractional transformations:  $\Pi : PSL(3, \mathbb{R}) \times \mathbb{RP}^2 \to \mathbb{RP}^1$
- Lemmas 2 and 3 hold in a more general framework:  $\Pi : G \times M \to N$  (*M*, *N* manifolds, *G* a Lie group acting on *M*).
- Transversality and projection thms for closest point projections in hyperbolic *n*-space and *n*-sphere (improving results by Balogh-I.)

Further directions:

- 2-dim subgroups? Respectively, are 1-dim subgroups the only minimal transversal subgroups?
- Other groups acting on surfaces? E.g. focussing on properties of group actions.
- Higher dimensions?
- Similar considerations in Sub-Riemannian setting?

# Thank you for listening!

#### My research interests

#### Geometric measure theory

Projection theorems

How well are sets generically preserved under families of projections?



#### IFS fractal curves

When are two IFS curves bi-Lipschitz or quasisymmetrically equivalent?



#### The dynamics of Thurston maps

- · Thurston's characterizations of rational
- · The curve attractor problem



· Visual spheres of Thurston maps

