

Lecture 3

Euler eq: $u_t + u \cdot \nabla u = -\nabla p - g e_y$
 $\Rightarrow \mathbb{R}^2 \subset \mathbb{R}^2$
 + bdd conds $\left\{ \begin{array}{l} \nabla \cdot u = 0 \\ \nabla \times u = 0 \\ u_0 = u(t_0, x) \\ D_t u \text{ is tangent to the free surface } \Gamma(t) \\ p = 0 \quad -2\sigma H \end{array} \right.$

$\sigma = \text{surface tension coeff.}$
 $H = \text{div} \left(\frac{\eta_x}{\sqrt{1 + \eta_x^2}} \right)$

$y = \eta(t, x)$
 $\phi |_{\Gamma(t)}$

Last time we wrote Zakharov system:

$$\begin{cases} \eta_t - G(\eta)\psi = 0 \\ \psi_t + g\eta - \frac{\sigma}{2} \nabla \psi^2 - \frac{1}{2} \frac{(\nabla \eta \cdot \nabla \psi + G(\eta)\psi)^2}{H|\nabla \eta|^2} = 0 \end{cases}$$

The kinematic bdd cond: particle on the free surface, stays on the free surface.

$D_t = \frac{D}{Dt} = \partial_t + u \cdot \nabla$ is tangent to the free surface at all times

$D_t (y - \eta(t, x)) = 0$

(x, y) Eulerian setting.

- location of a fixed fluid parcel $\rightarrow x(t) = (x(t), y(t))$ this is position at some time t .

- velocity of the fluid parcel

$$u(x, t) = (u(t, x), v(t, x)) \\ = (D_t x(t), D_t y(t))$$

$$\text{Recall } D_t = \partial_t + (u, v) \cdot (\partial_x, \partial_y) \\ = \partial_t + u \partial_x + v \partial_y.$$

$$\text{Hence } D_t (y(t) - \eta(t, x)) = 0$$

$$\text{implies } v = D_t \eta \rightarrow \text{and we use } \boxed{\begin{matrix} \mu = \nabla \phi \\ (u, v) = (\phi_x, \phi_y) \end{matrix}}$$

$$\begin{aligned} \parallel \\ \phi_y = D_t \eta &\Leftrightarrow \eta_t + u \cdot \nabla \eta = \phi_y \\ &\eta_t + \nabla \phi \cdot \nabla \eta = \phi_y \end{aligned}$$

$$\otimes \quad \boxed{\begin{matrix} \eta_t + \phi_x \eta_x = \phi_y \text{ on } \eta(t, x) = y \\ \text{this is the kinematic bdd. cond} \end{matrix}}$$

The dynamic boundary condition

On the free surface $y = \eta(t, x)$ we require the continuity of the pressure field p :

$$\boxed{p = p_{air} - \nabla H, \quad \textcircled{A}}$$

Now we couple this boundary condition to the momentum equation

$$u_t + u \cdot \nabla u + \nabla p + g e_y = 0, \quad \text{in } \Omega(t)$$

where $e_y = (0, 1)$ unit vector

To do so we recall $u = \nabla \phi$, where ϕ is the velocity potential function that solves a Laplace eq in $\Omega(t)$ + bdd cond. Plug in $u = \nabla \phi$ in the momentum-eq and integrate in x and y

get $\int_{\mathbb{R}^2}^{\eta(t,x)} \nabla \phi_t + \nabla \phi \cdot \nabla (\nabla \phi) + \nabla p + g e_y \, dx \, dy = \int_{-\infty}^{\eta(t,x)} 0 \, dx \, dy$. Integrate to get

$$\boxed{\phi_t + \frac{1}{2} |\nabla \phi|^2 + p - g \eta = 0} \quad \textcircled{2}$$

Bernoulli's equation follows

Plug in eq ① in ② gives

we have zero because any constant ($F(t)$) form will be included in p

$$\boxed{\phi_t + \frac{1}{2} |\nabla \phi|^2 - g \eta = \nabla \cdot H}$$

Still we are not at Zhakharov's formulation but we will work towards that.

Recall

$$G(\eta) \psi = \sqrt{1 + \eta_x^2} \nabla \phi \cdot n \quad \text{and use this towards Zhakharov's formulation}$$

Now the normal to the surface given by $\eta(t, x) = \eta$,

$F(x, y, t) = \eta - \eta(t, x)$ is given by

$$n_\eta = \frac{\nabla F}{|\nabla F|} = \frac{(-\eta_x, 1)}{\sqrt{1 + \eta_x^2}}$$

(unit normal to the surface pointing upwards)

Then the velocity normal to the surface is given by

$$\nabla \phi \cdot n_\eta = \frac{-\phi_x \eta_x + \phi_y}{\sqrt{1 + \eta_x^2}}$$

Rewrite this relation $\Rightarrow \sqrt{1 + \eta_x^2} \nabla \phi \cdot n_\eta = -\phi_x \eta_x + \phi_y$. From eq ② we can replace ϕ_y and get

$$\underbrace{\sqrt{1 + \eta_x^2}}_{G(\eta) \psi} \nabla \phi \cdot n_\eta = \cancel{-\phi_x \eta_x} + \eta_t + \cancel{\phi_x \eta_x} = \eta_t$$

This now reads as $\eta_t = G(\eta)\Psi$ which is the first eq we aimed for.

Now to get the second eq we need to use Bernoulli's eq and restrict it further to $P(t)$, the issue here is that $|\nabla\phi|^2$ needs to be expressed in terms of Ψ and for this we need to solve the following system

$$\begin{cases} G(\eta)\Psi = \sqrt{1+\eta_x^2} \nabla\phi \cdot \eta = -\phi_x \eta_x + \phi_y \eta_y & \text{and solve for } \phi_x \text{ and } \phi_y \text{ as functions} \\ \Psi_x = \nabla\phi \cdot (1, \eta_x) = \phi_x + \phi_y \eta_x & \text{of } \Psi, \text{ and you arrive at the second} \\ & \text{eq} \end{cases}$$

Hence the Zakharov's system is nonlinear, nonlocal but Δ in our case. Now, we write down some conserved quantities

$$\textcircled{1} \mathcal{H} = \frac{g}{2} \int_{\mathbb{R}} \eta^2 dx + \int_{\mathbb{R}} (\sqrt{1+\eta_x^2} - 1) dx + \frac{1}{2} \iint_{\Omega(t)} |\nabla_{(x,y)} \phi|^2 x dy$$

↑ Energy, and it is conserved along the flow!

② Conservation of the horizontal momentum

$$M = \int_{\mathbb{R}} \eta \Psi_x dx \rightarrow \text{(invariance in space (translations))}$$

Noether's theorem: for every symmetry you can associate a conserved quantity.

• Scaling law $\rightarrow g > 0$ ($\Gamma = 0$)

$$\begin{cases} \Psi(\lambda t, \lambda x) = \lambda^{-3/2} \Psi(\sqrt{\lambda} t, \lambda x) \\ \eta(\lambda t, \lambda x) = \lambda^{-1} \eta(\sqrt{\lambda} t, \lambda x) \end{cases}$$

$\eta \in \dot{H}^{3/2}(\mathbb{R})$, $\Psi \in \dot{H}^2(\mathbb{R})$

$$\downarrow g=0 (\Gamma > 0) \quad \begin{cases} \psi_\lambda(t,x) = \lambda^{-\frac{1}{2}} \psi(\lambda^{3/2}t, \lambda x) \\ \eta_\lambda(t,x) = \lambda^{-1} \eta(\lambda^{3/2}t, \lambda x) \end{cases}$$

$$\eta \in \dot{H}^{3/2}(\mathbb{R}) \\ \psi \in \dot{H}^1(\mathbb{R})$$

- $\Gamma, g, h = \text{depth}, w = 0! \quad w = \text{constant}$
- Potential problems are
 - 1) $h = \infty, g, \Gamma = 0, w = 0$ gravity water waves
 - 2) $\Gamma > 0, g = 0, h = \infty, w = 0$ capillary water waves.
 - 3) $h = \text{finite}, g, w = 0$

$G(\eta)\psi$ = we do not want to work with this operator, we want to diagonalize it meaning we would like to get something like $G(\eta)\psi \approx |\mathcal{D}| = H \circ \mathcal{D}$.

Linearization = around zero solution.

$$(\eta, \psi) = 0 \rightarrow \eta \text{ is flat.} \\ \text{velocity } \psi = 0$$

The linearization is dispersive which implies that the nonlinear problem is dispersive.

$$G(\eta)\psi = |\mathcal{D}| = H \circ \mathcal{D}$$

$$\begin{cases} \eta_t - |\mathcal{D}| \psi = 0 \\ \psi_t - \Gamma \eta_{xx} + g\eta = 0 \end{cases} \rightarrow \text{here we discarded the quadratic and higher order terms in the linearization}$$

$$\eta_{tt} = -(\nu |\Delta|^2 + |\Delta|) \eta \quad ** \quad H \cdot H = -I.$$

(ν, g)

$\nu^2 = \nu |\xi|^2 + g |\xi|$: principle symbol associated to the equation **

Discussion of the symbol.

- the roots real. real. \rightarrow eq is dispersive time, because the ξ part in the symbol is not linear.
- if the roots are not real \rightarrow ill posed. problem
- $\nu \geq 0$
- $\nu = 0$, g (sing becomes important!)
- $\nu = 0 = g$.

We assume $\nu \geq 0$ either $\nu = 0, g \geq 0$, and this assumption remains valid for this course

Normal derivative of the pressure

$\frac{\partial p}{\partial n}$ its sign matters! ie. $-\frac{\partial p}{\partial n} > 0$. \rightarrow this is our convention
 \hookrightarrow Taylor sign condition

in the linearization around (η, ψ) , we get that

$$\underline{-g|\xi|}, \quad \frac{\partial p}{\partial n} = g\eta \leftarrow$$