

Lecture B.10

Applications of PCPs

Summer Graduate School on
Foundations and Frontiers of Probabilistic Proofs
2021.08.05

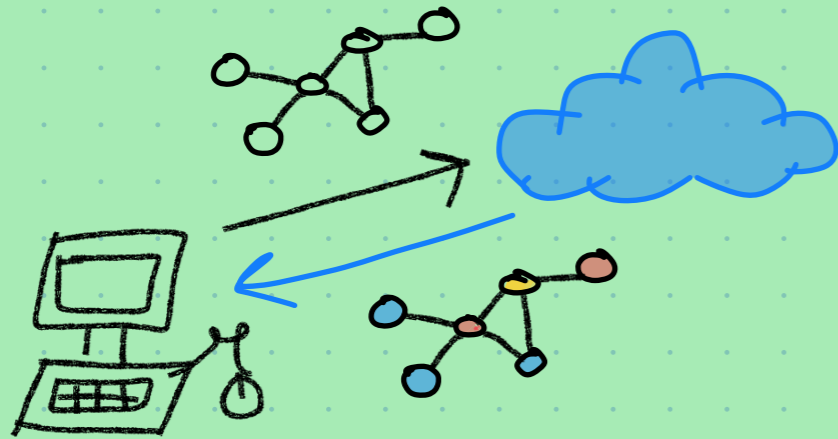
Applications of PCPs

Two main directions:

Delegation of computation



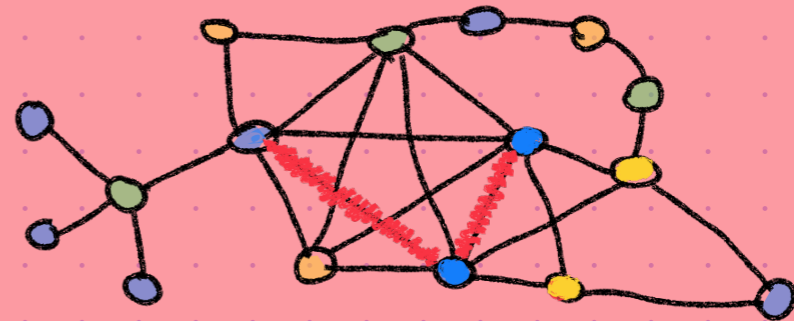
outsource your problem
& efficiently verify the solution!



Hardness of approximation



Which problems remain hard
even if we only require
an approximate solution?



Delegation of Computation via PCPs

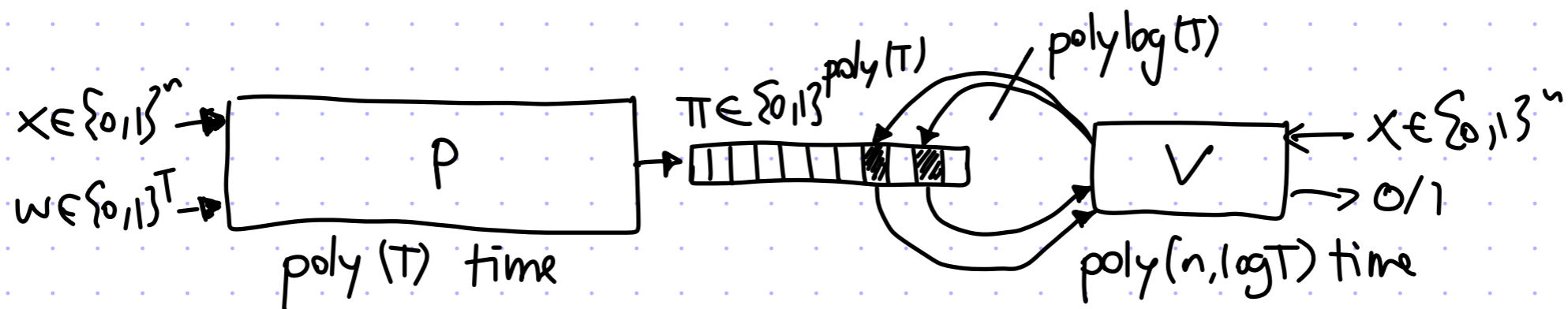


We showed the following result:

theorem: Every language $L \in \text{NTIME}(T)$ has a PCP where:

proof length $\ell = \text{poly}(T)$
prover time $p_t = \text{poly}(T)$

query complexity $q = \text{polylog}(T)$
verifier time $v_t = \text{poly}(n, \log T)$



In this setup, a single reliable PC can monitor the operation of a herd of supercomputers working with possibly extremely powerful but unreliable software and untested hardware.

But how to use this "setup"?

Checking Computations in Polylogarithmic Time

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A Crypto Interlude: From PCP to Interactive Arguments

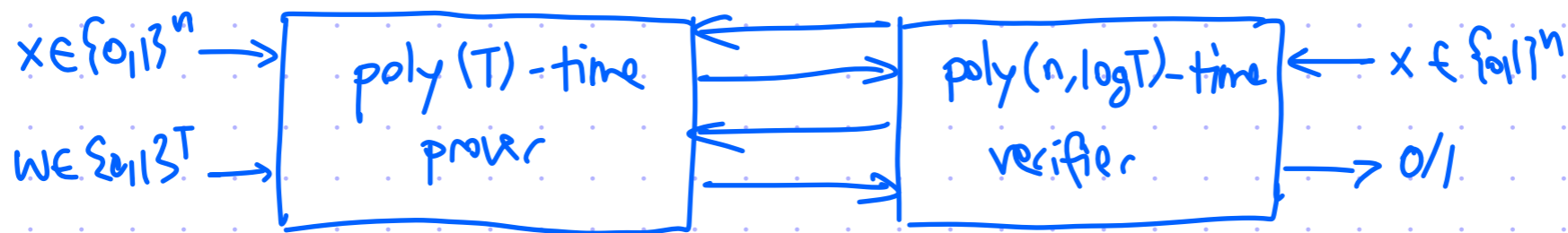
theorem [informal]

Suppose L has a PCP with prover time p_t , verifier time v_t , query complexity q .

Then by using cryptography we can construct an interactive "proof" for L s.t.

prover time $O(p_t)$, verifier time $O(v_t)$, communication $O(q)$.

If we apply this to PCPs in prior slide, we get a powerful result:



Proof attempt:

[does NOT contradict limitations of IPs with small communication!]

$P(x, w)$

- produce PCP string: $\pi := P_{PCP}(x, w)$
- deduce query set Q in $V_{PCP}^{\pi}(x; \rho)$

ρ

$V(x)$

sample PCP randomness ρ

$\pi|_Q$

$V_{PCP}^{\pi|_Q}(x; \rho) \stackrel{?}{=} 1$

Problem: prover can pick π based on Q .

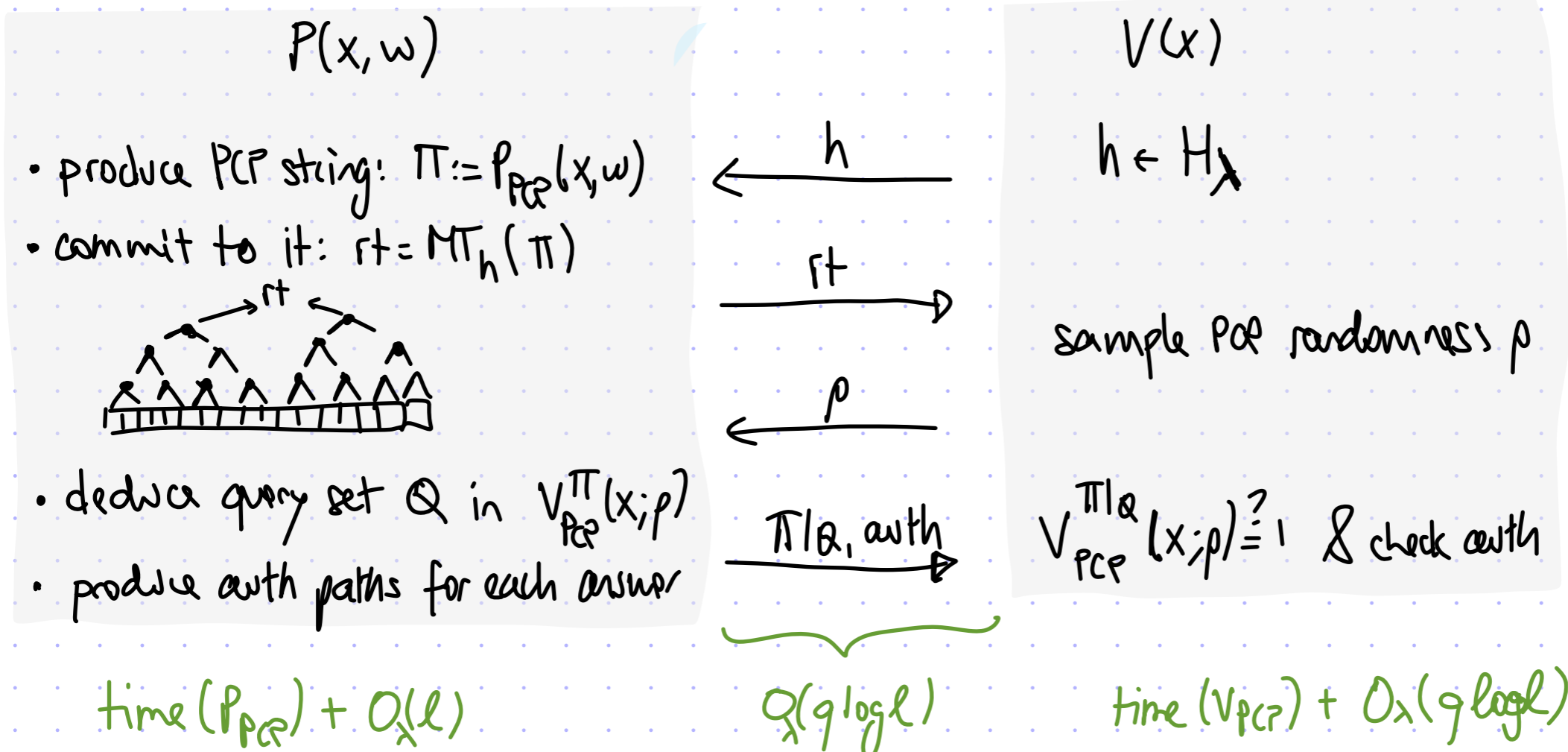
[Also, where is the crypto??]

A Crypto Interlude: Kilian's Protocol

Idea: commit to PCP string first then locally open locations of it

Def: A function family $H_\lambda = \{h_x: \{0,1\}^{2\lambda} \rightarrow \{0,1\}^\lambda\}$ is collision-resistant if
 \forall efficient adversary A $\Pr_{h \leftarrow H_\lambda} [A(h) \text{ outputs } x \neq y \text{ s.t. } h(x) = h(y)]$ is negligible in λ .

The new protocol is as follows:



Security analysis involves cryptography and so we will not discuss it.

From IOP to Interactive Argument

[1/2]

theorem [informal]

Suppose L has a public-coin IOP with prover time p_t , verifier time v_t , query complexity q .
Then by using cryptography we can construct an interactive argument for L with
prover time $O(p_t)$, verifier time $O(v_t)$, communication $O(q)$.

proof attempt:

$P(x)$

- deduce all the oracles:
 $\pi_1 := P_{\text{IOP}}(x)$, $\pi_2 := P_{\text{IOP}}(x, r_1)$, ..., $\pi_k := P_{\text{IOP}}(x, r_1, \dots, r_{k-1})$
- deduce IOP verifier's queries:
 $Q := \text{queries}(V_{\text{IOP}}^{\pi_1, \dots, \pi_k}(x; r_1, \dots, r_k))$

$\leftarrow r_1, \dots, r_k$

$\xrightarrow{[\pi_1, \dots, \pi_k] \mid Q}$

$V(x)$

$V_{\text{IOP}}([\pi_1, \dots, \pi_k] \mid Q)(x; r_1, \dots, r_k) \stackrel{?}{=} 1$

This is NOT secure because the prover can answer queries based on r_1, \dots, r_k !

Idea: extend Kilian's protocol from PCP to IOP by committing to each oracle via a Merkle tree and then locally open the relevant locations.

From IOP to Interactive Argument

[2/2]

As in Kilian's protocol, we rely on collision-resistant functions to build Merkle trees.

$P(x)$

$$\pi_1 := P_{\text{IOP}}(x), r_{t_1} := \text{MT}_h(\pi_1)$$

$$\pi_2 := P_{\text{IOP}}(x, r_1), r_{t_2} := \text{MT}_h(\pi_2)$$

$$\pi_k := P_{\text{IOP}}(x, r_1, \dots, r_{k-1}), r_{t_k} := \text{MT}_h(\pi_k)$$

- deduce IOP verifier's queries:
 $Q := \text{queries}(V_{\text{IOP}}^{\pi_1, \dots, \pi_k}(x; r_1, \dots, r_k))$
- produce auth paths for each answer

$$\text{time}(P) = \text{time}(P_{\text{IOP}}) + O_x(\ell)$$

$$\underbrace{Q(q \log \ell)}_{Q(q \log \ell)} \quad \text{time}(V) = \text{time}(V_{\text{IOP}}) + O_x(q \log \ell)$$

$V(x)$

sample CRH: $h \leftarrow H_x$

$$\begin{array}{c} \leftarrow h \\ \xrightarrow{r_{t_1}} \end{array}$$

$$\begin{array}{c} \leftarrow r_1 \\ \xrightarrow{r_{t_2}} \end{array}$$

$$\begin{array}{c} \leftarrow r_2 \\ \vdots \\ \xrightarrow{r_{t_k}} \end{array}$$

$$\begin{array}{c} \leftarrow r_k \end{array}$$

$$\xrightarrow{\text{ans, paths}}$$

$V_{\text{IOP}}^{\text{ans}}(x; r_1, \dots, r_k) \stackrel{?}{=} 1$ & check paths

Security analysis involves cryptography and so we will not discuss it.

In sum, designing efficient IOPs leads to efficient arguments.

Hardness of approximation



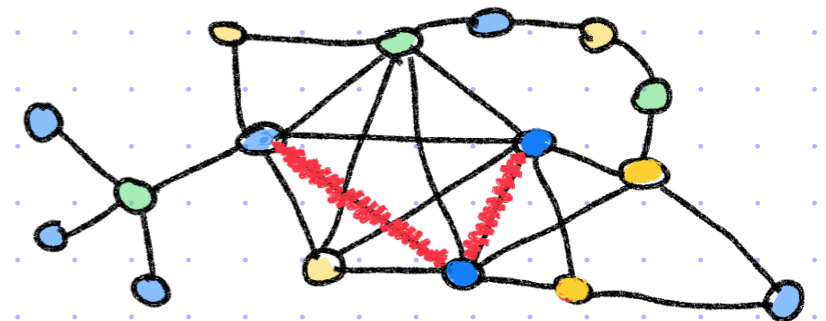
During the 70s and 80s many key optimisation problems were shown to be NP-hard.

E.g., 3SAT, Knapsack, Hamiltonian path, Travelling salesman, 3COL, clique, Super Mario...



It's natural to seek approximate solutions!

Def: An algorithm A is an α -approx alg for a maximisation problem Π if $\forall x \quad \alpha \cdot \Pi(x) \leq A(x) \leq \Pi(x)$



Example: Max-3SAT

Problem: Given a 3CNF formula, find an assignment that maximises the number of satisfied clauses.

$$\text{Ex: } \psi = (x_1 \vee x_2 \vee \bar{x}_3) \wedge (\bar{x}_2 \vee \bar{x}_3 \vee x_1) \wedge (\bar{x}_1 \vee \bar{x}_4 \vee x_3) \\ \wedge (x_1 \vee \bar{x}_2 \vee x_4) \wedge (x_2 \vee x_3 \vee \bar{x}_4)$$

Claim: There exists a $\frac{7}{8}$ -approx poly-time algorithm for Max-3SAT

The main idea is to observe that there must be many $\frac{7}{8}$ -sat assignments, so it suffices to guess some at random! ▽

Example: Max-3SAT

Claim: There exists a $\frac{7}{8}$ -approx poly-time algorithm for Max-3SAT

Proof: Let c_i be the indicator of whether the i 'th clause is sat.

Note that $E[c_i] = \Pr[c_i \text{ is sat}] = \frac{7}{8}$. → only one assignment fail to sat. a disjunction

Thus $E\left[\sum_{i=1}^m c_i\right] = \sum_{i=1}^m E[c_i] = \frac{7}{8}m$.

Hence there exists an assignment satisfying $\frac{7}{8}m$ clauses

Moreover, by Markov, at least $\frac{1}{m+1}$ of the assignment

satisfy at least $\frac{7}{8}m$ clauses.

Thus it suffices to choose and check $O(m)$ random

assignments ■

How to show hardness of approximation?

Recall that NP-hardness is defined for **decision** problems.

Definition: Let Π be an approximation problem.

$\text{Gap}\Pi_{c,s}$ is the problem of deciding whether $\Pi(x) \geq c$ or $\Pi(x) \leq s$.

Claim: If $\text{Gap}\Pi_{c,s}$ is NP-hard, then it is NP-hard to approximate Π to $\frac{s}{c}$ precision

Proof: We reduce the gap problem to the approx. problem.

If $\Pi(x) \geq c$, the approx. is at least $\frac{s}{c} \cdot c = s$

If $\Pi(x) \leq s$, the approx is at most s .

PCP \Leftrightarrow hardness of approximation

We'll illustrate the connection via an example.

Theorem: $\text{Gap3SAT}(1, s)$ is NP-hard for $s < 1$ iff

$3\text{SAT} \in \text{PCP}_{1, s'} [O(\log n), 3]$ for $s' < 1$.

$$s' = \frac{7}{8} + \epsilon$$

\leftarrow we proved this!

Proof: \Rightarrow Apply the reduction from 3SAT to Gap3SAT .

The NP proof corr. to the Gap3SAT instance.

Now sample clauses at random.

\Leftarrow We reduce 3SAT to Gap3SAT .

Express the PCP verifier checks as a 3CNF .

Completeness implies 1 -satisfiability.

Soundness implies at most s' -satisfiability.

Concluding

words