

KASRT : May 8, '03 . P. Deift.

Long-time asymptotics for solutions of the NLS equation with initial data in a weighted Sobolev space.

Joint work with X. Zhou

I will be addressing the question of the long-time

behavior of solutions $d(t) = d(x, t)$ of the defocusing

NLS equation in the limit

(1) $i d_t + q_{xx} - 2|q|^2 d = 0$

$d(x, t=0) = q_0(x) \rightarrow 0$ as $|x| \rightarrow \infty$

I am particularly interested in the case where q_0 has "minimal" smoothness and decay.

Outline of the talk:

- A. What has been done up till now.
- Why we are interested in "minimal" smoothness / decay. Use the oscillations.
- B. Statement of the result
- C. Some key ideas from the proof
- D. Extended result

A: Results

~~Zakharov-Shabatov (76) deduced the asymptotic form~~

Recall that the 1D NLS equation is equivalent to

an Riemann spectral deformation of the operator

$$L(q) = -i\sigma \left(\partial_x - \begin{pmatrix} 0 & q(x) \\ \bar{q}(x) & 0 \end{pmatrix} \right), \quad \sigma = \frac{1}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

Scattering / inv. spect. theory establishes a bijection

$$q \leftrightarrow R(q)$$

$q = q(x) \rightarrow r = R(z) =$ reflection coefficient, $\|r\|_\infty < 1$

and the key fact (Zakharov / Shabat 72) is that if $q = q(t)$ $r(t) = R(q(t))$ evolves simply,

solve NLS then $\left(\frac{d}{dt} + \dots \right) r(t=0)(z)$

$$\left[r(t)(z_0) = e^{-it z_0^2} r(t=0)(z_0) r_0(z_0) \right]$$

where $r_0 = R(q_0) = R(q(t=0))$

In [1976], Zakharov & Shabatov derived the asymptotic form as $t \rightarrow \infty$ in terms of $r = R(q_0)$

$$q(x,t) \sim q_{as}(x,t)$$

$$= t^{-1/2} \alpha(z_0) e^{i x^2/4t - i \nu(z_0) \log t}$$

where $z_0 = x/2t$, $\nu(z) = -\frac{1}{2\pi} \log(1 - |r(z)|^2)$

~~$\alpha(z)$~~

~~$\alpha(z) = \frac{1}{2\pi i}$~~

$|\alpha(z)| = (|z|/2)^2$

$$\arg \alpha(z) = \frac{1}{\pi} \int_{-\infty}^z \log(z-s) d \log(1-|r(s)|^2) + \frac{\pi}{4} + \arg T(i|z|) + \arg r(z)$$

Notice that the form of the solution differs from the form of the solution of the linear Schrödinger equation.

$i q_t^F + q_{xx}^F = 0$

for which

$$q^F(x,t) \sim \frac{1}{\sqrt{x}} \alpha^F(z_0) e^{ix^2/4t}$$

Solutions of all never become free.

Talbot / Akhiezer's derivation was not rigorous. In

particular they provide no estimates for the error. In

1995, using the ~~steepest~~ steepest-descent method for Picman-Walsh

problems (more later) Jéjé - Jéjé - Khan showed that

$$q(x, t) = q_{as}(x, t) + O\left(\frac{\log t}{t}\right)$$

as $t \rightarrow \infty$

↑
uniform in x

In their proof they needed to assume that q_0 had

some high orders of decay & smoothness

In recent work of Jost and Zhou

on perturbations of NLS

$$(2) \quad \left. \begin{aligned} i d_t^2 + q_{xx}^e - 2|q^e|^2 q^e - \varepsilon |q|^2 q &= 0 \\ q^e(x, t=0) &= q_0 \end{aligned} \right\}$$

(2.2) ~~It is not clear how to show~~

whether show that as $t \rightarrow \infty$ solution $q^e(t)$ look

like solutions $q(t)$ of NLS

$$q^e(t; q_0) \sim q(t; \tilde{q}_0)$$

for some $\tilde{q}_0 = \tilde{q}_0(q_0)$. As the authors consider

solutions $q(t)$ in the weighted Sobolev space

$$\{H^{1,1} = \{q \in L^2 : xq, q' \in L^2\}\}$$

it becomes important to know how to evaluate the

asymptotics of NLS with initial data in $H^{1,1}$ of course this problem is also of independent interest.

Whereas the analysis in D-I-7 uses absolute estimates

we now have to use cancellations from oscillations.

(B) To see what we might hope for, note that

if we consider the solution of ψ^F the linear Schrod. equation with

$q_0 \in H^{1,1}$, then a simple stat. phase calc. shows that

$$q^F(x,t) = \frac{d^F(q_0)}{t^{1/4}} e^{ix^2/4t} + O\left(\frac{1}{t^{3/4}}\right)$$

Our result is the following:



Thm (7.6.1 + D)

Let $q(t), t \geq 0$, solve (1) with $q_0 = q(t=0) \in H^{1,1}$. Fix

$0 < k < \frac{1}{4}$. Then as $t \rightarrow \infty$

$$q(x,t) = q_{as}(x,t) + O\left(\frac{1}{t^{2+k}}\right)$$

where q_{as} is given in terms of $r = R(q_0)$ as above. The error

term $O(t^{-\frac{1}{2}+k})$ is uniform $\forall x \in \mathbb{R}$.

So the result is optimal in the sense that the error term is arbitrarily close to that ~~in the~~ in the free case.

(c) Some key ideas of the proof:

The NLS equation with initial data q_0 is

solved via the following Riemann-Hilbert Problem (RHP):

↓ Let $r = R(q_0) =$ reflection coefficient for q_0 : (w/ fix x, t) let

$m = m(z) = \begin{pmatrix} m_{11} & m_{12} \\ m_{21} & m_{22} \end{pmatrix}$ satisfy

- $m = m(z)$ is analytic in $\mathbb{C} \setminus \mathbb{R}$
- $m_+(z) = m_-(z) U_\theta(z)$, $z \in \mathbb{R}$

where $m_\pm(z) = \lim_{\epsilon \downarrow 0} m(z \pm i\epsilon)$

$U_\theta(z) = \begin{pmatrix} 1 - V(z) & re^{i\theta} \\ -\bar{r}e^{-i\theta} & 1 \end{pmatrix}$, $\theta = xz - tz^2$

• $m(z) \rightarrow I$ as $z \rightarrow \infty$.

Then if ~~we~~ we expand.

$$m = I + \frac{m_1(x,t)}{\gamma} + O\left(\frac{1}{\gamma^2}\right) \quad \text{as } \gamma \rightarrow \infty,$$

$$d(x,t) = -i (m_1(x,t))_{,2}$$

So, in order to evaluate $d(x,t)$ as $t \rightarrow \infty$, we evaluate the solution of this ~~problem~~ RHP with

highly oscillatory parameters $r e^{i\theta} = r e^{i(x's - t's')} \quad \text{as } t \rightarrow \infty$

For scalar integrals, ^(which arise, eg, in the solution of linear NLS) such problems are analyzed

using the stationary phase method. This is an analogy

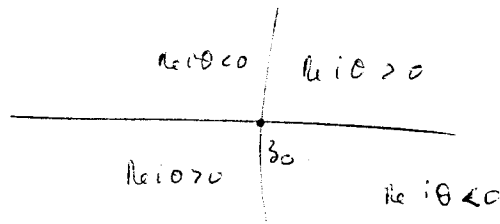
of the method for the non-commutative RHP as above

due to $\theta_{\text{osc}} + \theta$, and this is what we use. This

method ~~has~~ has been developed much further and now has applications to many diff. parts of mathematics & physics.

The method is basically applied as follows:

Key idea is to take advantage of the signature table for $Re\{z\}$



$z_0 = \frac{z}{z^*}$
 = stationary phase pt. for θ
 = $x_3 - t_3^2$

This is done to note that v_0 has an upper/lower irradiation condition

(3)

$$v_0 = \begin{pmatrix} 1 - |r|^2 & re^{i\theta} \\ -\bar{r}e^{-i\theta} & 1 \end{pmatrix} = \begin{pmatrix} 1 & re^{i\theta} \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ -\bar{r}e^{-i\theta} & 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 \\ -\frac{\bar{r}e^{-i\theta}}{1 - |r|^2} & 1 \end{pmatrix} \begin{pmatrix} 1 - |r|^2 & 0 \\ 0 & (1 - |r|^2) - 1 \end{pmatrix} \begin{pmatrix} 1 & \frac{re^{i\theta}}{1 - |r|^2} \\ 0 & 1 \end{pmatrix}$$

The diagonal terms can be removed by

conjugating v_0 by the rotation $\delta = \delta(z)$ of the

following scalar RHP

- $\delta(z)$ analytic in $\mathbb{C} \setminus (-\infty, z_0]$
- $\delta_+(z) = \delta_-(z) (1 - |r(z)|^2)$, $-\infty < z < z_0$
- $\delta(z) \rightarrow 1$ as $z \rightarrow \infty$



Then if we set

$$\vec{v} = \begin{pmatrix} v_+ \\ v_- \end{pmatrix} = \begin{pmatrix} \delta_+^{-\sigma_3} & 0 \\ 0 & \delta_+^{\sigma_3} \end{pmatrix} \vec{v}_0$$

$$\sigma_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$\delta_{\pm}^{\sigma_3} = \begin{pmatrix} \delta_{\pm} & 0 \\ 0 & \delta_{\pm}^{-1} \end{pmatrix}$$

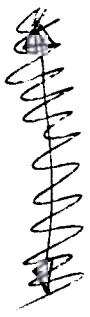
$\delta_+ = \delta_-$ for $z > z_0$.

we obtain for $z \gg z_0$

$$\vec{v}_E = \begin{pmatrix} 1 & re^{i\theta} \delta_+^2 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ -\bar{r}e^{-i\theta} \delta_+^{-2} & 1 \end{pmatrix}$$

and for $z \ll z_0$

$$= \begin{pmatrix} 1 & 0 \\ -\frac{\bar{r}e^{-i\theta}}{1-r^2} \delta_+^{-2} & 1 \end{pmatrix} \begin{pmatrix} 1 & \frac{re^{i\theta}}{1-r^2} \delta_+^{-2} \\ 0 & 1 \end{pmatrix}$$



and

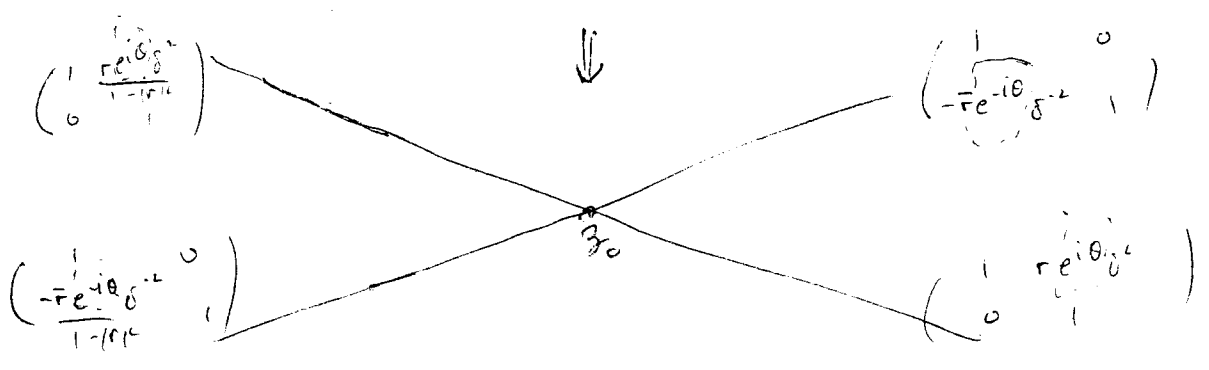
$$\vec{m}(z) \equiv m \delta^{-\sigma_3} = m \begin{pmatrix} \delta & 0 \\ 0 & \delta^{-1} \end{pmatrix}$$

solves ~~the same~~ a similar Riccati to m but with

v_E replaced by \vec{v}_E

$$\vec{m}_+ = \vec{m}_- \begin{pmatrix} 1 & 0 \\ -\frac{\bar{r}e^{-i\theta}}{1-r^2} \delta_+^{-2} & 1 \end{pmatrix} \begin{pmatrix} 1 & \frac{re^{i\theta}}{1-r^2} \delta_+^{-2} \\ 0 & 1 \end{pmatrix} \quad \vec{m}_+ = \vec{m}_- \begin{pmatrix} 1 & re^{i\theta} \delta_+^2 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ -\bar{r}e^{-i\theta} \delta_+^{-2} & 1 \end{pmatrix}$$

z_0



Noticing their ~~local~~ The exponential factors are exponentially all decreasing in their respective sectors, we see

that $-1/4$ $R(z)$ localizes to a neighborhood of z_0 it turns out that this local $R(z)$ can be solved

explicitly giving the z_0 solution + error terms.

The difficulties clearly arise from the fact that $r, F, F/(1-r), \frac{F}{1-r}$

are not analytic so they have to be approximated

appropriately and the real point of this talk is that some

kind of approximations can be done effectively if we just assume

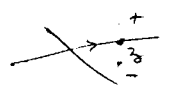
that $q_0 \in H^{(1)}$, or equivalently by the scattering map, $r = H^{(1)}$. But it is so a delicate business!

I want to give some idea of the kind of estimates

that we need. Recall that RHP 's on a contour Σ are equivalent to a set of singular integral equations on Σ . The singular operators in these equations are

the Cauchy operator

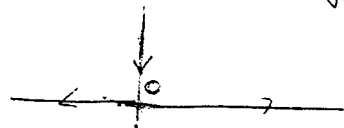
$$(C_T^\pm f)(z) = \lim_{\delta \rightarrow 0} \int_\Sigma \frac{f(s)}{s-z} \frac{ds}{2\pi i}$$



C_T^\pm have the important property that $C_T^+ C_T^- = I$.

One of the key estimates is the following: let

T be the center



Suppose $f \in H^{1,0}$ on $(0, \infty)$, $f=0$ on $\Gamma(0, \infty)$. Then for any $2 \leq p < \infty$ & $t \geq 0$

$$(4) \quad \| C_T^\pm \delta^{\pm 2} f e^{\pm it\Delta^2} \|_{L^p(\mathbb{R})} \leq \frac{c}{(1+t)^{1/p}} \frac{\|f\|_{H^{1,0}(0,\infty)}}{1-p}$$

$$p = \sup_{s \in \mathbb{R}} |s|$$

What is subtle about estimates is that on \mathbb{R} ,

$$\underbrace{C_T^+ \delta^2 f e^{-it\Delta^2}}_{\text{decays in } t} - C_T^- \delta^2 f e^{-it\Delta^2} = \delta^2 f e^{-it\Delta^2}$$

↑
does not decay

↑
clearly does not decay

So the signs have to match $C^+ \dots e^-$ or $C^- \dots e^+$ to make the estimate work

q insert from p (2+, 2++)

Here are many other places in the proof where a delicate cancellation is needed, but I do not have time to describe them.

(D) Extended results

It turns out that the estimates in the theorem only depend on the $H^{0,1}$ norm of q_0 ,

$$\|q_0\|_{H^{0,1}}^2 \equiv \int (1+x^2) |q_0(x)|^2 dx < \infty$$

But ~~it is not clear~~ what do we mean by a solution of NLS with initial data in $H^{0,1}$?

It turns out that ~~it is not clear~~ using Strichartz-type estimates

we can show the following:

Let $q_0 \in L^2$. Then \exists a unique solution of NLS with $q \in C(\mathbb{R}_+, L^2(\mathbb{R})) \cap (L^\infty(\mathbb{R}_+) \otimes L^4_{loc}(\mathbb{R}))$ and $q(t=0) = q_0$.
Moreover, if $q_0 \in H^{0,1}$, then the solution $q(t)$ satisfies $\left(\int_0^T \|q(\cdot, t)\|_{L^\infty(\mathbb{R})}^4 dt \right)^{1/2} < \infty$ for all $T < \infty$.

Another type of cancellation that is needed can be seen from the following:

(corresponding to the u/l factorization in (3) above at $t=0$)

$$(0 = x_3 - t_3^2 |_{t=0} = x_3)$$

$$v_x = \begin{pmatrix} 1 & re^{i3x} \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ -\bar{r}e^{-i3x} & 1 \end{pmatrix} = (v_x^-)^{-1} v_x^+$$

$$v_x^+ - I = \begin{pmatrix} 0 & 0 \\ -\bar{r}e^{-i3x} & 0 \end{pmatrix}, \quad v_x^- - I = \begin{pmatrix} 0 & -re^{i3x} \\ 0 & 0 \end{pmatrix}$$

strictly lower triangular strictly upper triangular

one has analogous to (4) above

$$(5) \quad \|C^+(I - v_x^-)\|_{L^2}, \quad \|C^-(v_x^+ - I)\|_{L^2} \leq \frac{1}{(1+x^2)^{1/2}} \|r\|_{H^1}$$

for $x \leq 0$,

In analyzing the inverse problem one needs to show along the way, in particular that for $x \leq 0$

$$(6) \quad \left| \int_{\mathbb{R}} [C^+(I - v_x^-) + C^-(v_x^+ - I)](z) (v_x^+ - v_x^-)(z) dz \right| \leq \frac{C}{1+x^2}$$

but using the fact that

• $v_x^+ - I$, $v_x^- - I$ are strictly lower / upper triangular, resp

The integral can be rewritten in the form

$$\int_{\mathbb{R}} \left[(C^+ (I - v_x^-)) (v_x^+ - I) + (C^- (v_x^+ - I)) (I - v_x^-) \right] dz$$

and using the facts that

$$C^+ - C^- = I \quad \text{and} \quad C^+ C^- = C^- C^+ = 0$$

The integral can further be rewritten as

$$\int_{\mathbb{R}} \left[-(C^+ (I - v_x^-)) (C^- (v_x^+ - I)) + (C^- (v_x^+ - I)) (C^+ (I - v_x^-)) \right]$$

and the desired estimate (6) now follows from (5).

So the estimates need to be done just right!

constructed via the RHP, is the (unique) Strichartz solution
 and moreover, have the asymptotic form given in Theorem 1
~~the~~ above.
