

Distinguishing separable and entangled states in quantum mechanics

Pablo A. Parrilo
ETH Zürich

Joint work with
A. Doherty and F. Spedalieri
IQI - Caltech



Eidgenössische Technische Hochschule Zürich
Swiss Federal Institute of Technology Zurich

Quantum entanglement

- Entanglement is one of the most distinctive features of quantum physics.
- A strong “linkage” between two systems, that cannot be explained through probability.
- If two systems have interacted in the past, it may not be possible to assign independent states.
- EPR “paradox”, Bell inequalities.

Verified experimentally.

Hidden variable theories must be non-local.

Entanglement as a resource

- Quantum computation: some computational problems have lower complexity if entangled states are available.
- Quantum key distribution in cryptography.
- Teleportation: entanglement + classical communication.

All require entangled states. How?

EX: Quantum teleportation

(Bennett et al., 1993)

- Prepare an entangled pair of particles.
- Give one to Alice, other one to Bob.
- Alice performs a joint measurement on the data and her entangled particle.
- Alice sends the “random” result to Bob using a classical channel.
- Bob performs a measurement according to Alice’s instructions.
- Bob obtains Alice’s data. Alice’s data is destroyed.

Entanglement as a resource

- Teleportation: entanglement + classical communication.
- Quantum key distribution in cryptography.
- Quantum computing: some computational problems may have lower complexity if entangled states are available.

Q: How to determine whether or not a given quantum state is entangled ?

Outline

- Entangled vs. separable states
- Characterizations
- Positive maps and bihermitian forms
- Entanglement witnesses
- State extensions
- SDP approach
- Conclusions

Mathematical description

QM state described by PSD Hermitian matrices ρ
(density matrix, mixed states)

- States of multipartite systems are described by operators on the tensor product of vector spaces

$$\rho = \sigma_1 \otimes \omega_1$$


The diagram shows two circles representing subsystems. The left circle is teal and labeled 'A', containing the symbol σ_1 . The right circle is yellow and labeled 'B', containing the symbol ω_1 .

- Product states: each subsystem is in a definite state

Separable states:

convex combination of product states.

$$\rho = \sum p_i \sigma_i \otimes \omega_i, \quad p_i \geq 0, \quad \sum p_i = 1$$

Interpretation: statistical ensemble of locally prepared states.

Entangled states: those that cannot be written as a convex combination of product states.

Deciding entanglement

Decision problem: find a **decomposition** of the state ρ as a convex combination of product states or **prove** that no such decomposition exists.

Semialgebraic, thus decidable.

But NP-hard (Gurvits 2002).

Not clear how to proceed. In particular, how to *certify* entanglement?

Starting point: necessary conditions for separability.

The PPT criterion

(Peres-Horodecki 1996)

Consider the map (“partial transpose”) defined by:

$$PT(\sigma \otimes \omega) = \sigma \otimes \omega^T$$

Extend by linearity. Two-block example:

$$PT\left(\begin{bmatrix} M_{11} & M_{12} \\ M_{12} & M_{22} \end{bmatrix}\right) = \begin{bmatrix} M_{11} & M_{12}^T \\ M_{12}^T & M_{22} \end{bmatrix}$$

If ρ is separable, then $PT(\rho)$ is PSD.

A necessary condition for separability.

Entangled states exist!

If $PT(\rho)$ is *not* PSD , then ρ has to be entangled!

A sufficient condition for entanglement.

$$\rho = \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 1 \end{bmatrix}, \quad PT(\rho) = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

NOT PSD

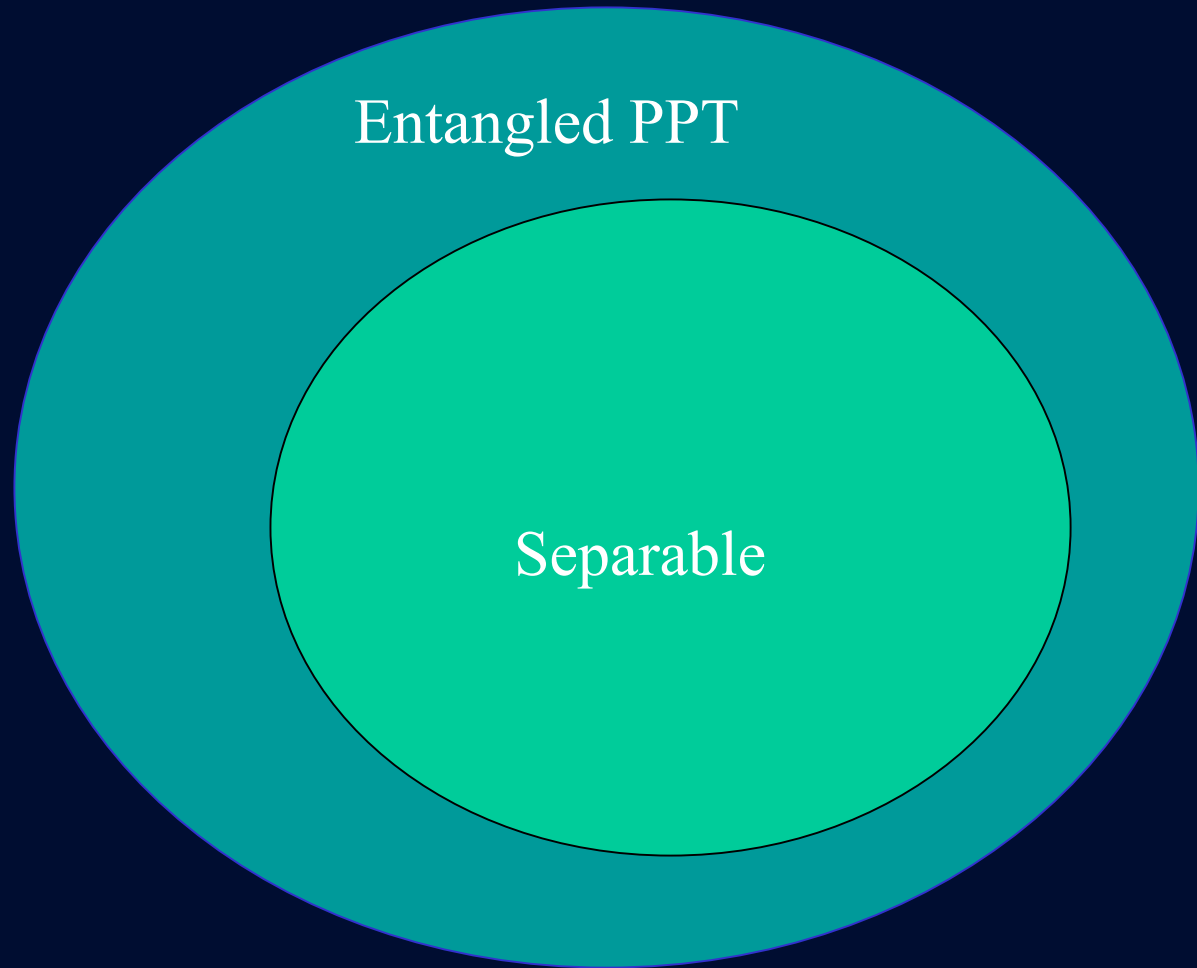
Therefore, ρ cannot be separable. It is entangled.

PPT is easy to verify. Correct solution for 2×2 , 2×3 .
But, not the whole story.

In general, *not* necessary and sufficient.

There exist entangled states, with positive PT.

Entangled not-PPT



Entangled PPT

Separable

PPT is easy to verify. Correct solution for 2×2 , 2×3 .
But, not the whole story.

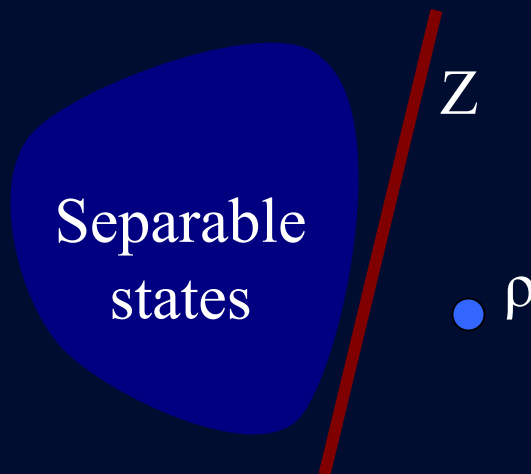
In general, *not* necessary and sufficient.

There exist entangled states, with positive PT.

How can we obtain sharper characterizations of entangled states?

Better "operational criteria" to classify states?

Separability and convexity



(Hahn-Banach Theorem)

Z is an “entanglement witness,”
a generalization of Bell’s
inequalities

Theorem (Horodecki 1996): a state ρ is entangled if and only if there exists a Hermitian Z such that:

$$\text{Tr}[\rho Z] < 0$$

$$\forall x, y \text{ Tr} \left[\left(x x^* \otimes y y^* \right) Z \right] = \sum Z_{ij;kl} x_i x_j^* y_k y_l^* \geq 0 \quad \text{Hard!}$$

An aside: positive maps

- A matrix map is *positive* if

$$\rho \geq 0 \Rightarrow L(\rho) \geq 0$$

i.e., takes the PSD cone into itself.

- There is a bijection between matrix maps and bihermitian forms:

$$p(x, y) = y^* L(xx^*) y$$

- Therefore, checking positivity of a matrix map is equivalent to nonnegativity of bihermitian forms. Also equivalent to characterization of EWs.

Our approach

(Phys. Rev. Lett., May 2002)

Complementary interpretations.

- Finding state extensions.
- Search for specific classes of EWs.

The underlying theme:

To replace **polynomial nonnegativity** by something more tractable, **sum of squares decompositions**.

State extensions

- More consequences of separability:
state extensions.

If $\rho \in H_A \otimes H_B$ is separable, then

$$\rho = \sum p_i x_i x_i^* \otimes y_i y_i^*$$

We can always **extend** it to $\tilde{\rho} \in H_A \otimes H_B \otimes H_A$

$$\tilde{\rho} = \sum p_i x_i x_i^* \otimes y_i y_i^* \otimes x_i x_i^*$$

- The extended tripartite state is separable for all partitions $(A|BA), (AA|B)$.

$$\tilde{\rho} \in H_A \otimes H_B \otimes H_A$$

- In particular, should be PPT wrt to all partitions.

If ρ is separable then there is an extension:

- Reduces to ρ under projection on first two components.
- Is symmetric in the 1st and 3rd components.
- Is PPT for all partitions.

If ρ is separable then there is an extension:

- Reduces to ρ under projection on first two components.
- Is symmetric in the 1st and 3rd components.
- Is PPT for all partitions.

Searching for such extension is an SDP. Why?

Take a generic matrix $\tilde{\rho} \in H_A \otimes H_B \otimes H_A$

- The first two conditions are **affine** equations.
- The third one gives two PSD constraints.

If such extension does not exist, ρ is entangled.

Infeasibility certificates for this SDP provide entanglement witnesses!

Going to the other side...

- Do these witnesses have “easy” interpretations?
- How does all this relate (if at all) with PPT?

Recall: To find witnesses, look for Z

$$\text{Tr}[\rho Z] < 0$$

$$\forall x, y \text{Tr} \left[\left(xx^* \otimes yy^* \right) Z \right] = \sum Z_{ij;kl} x_i x_j^* y_k y_l^* \geq 0$$

First Relaxation

Restrict attention to a special type of Z :

The bihermitian form Z is a sum of squared magnitudes.

$$\begin{aligned}\text{Tr}[\rho Z] &= \sum Z_{ij,kl} x_i x_j^* y_k y_l^* = \sum |G_{m,ik} x_i y_k|^2 + \sum |H_{m,ik} x_i y_k^*|^2 \\ &= (x \otimes y)^* G (x \otimes y) + (x^* \otimes y^T) H (x \otimes (y^*)^T) \\ &= \text{Tr}[\rho G + \rho^{T_2} H]\end{aligned}$$

$$\begin{array}{l} \text{minimize } \text{Tr}[\rho G + \rho^{T_2} H] \\ \text{subject to } G \geq 0, \quad H \geq 0 \end{array}$$

If minimum is less than zero, ρ is entangled

First Relaxation

- Relax nonnegativity to SOS.
- **Exactly** equivalent to the PPT criterion!
- A reason: when checking SOS for bihermitian forms, the SDP is trivial. Only need to check if two matrices are PSD.
- Corresponds to an easily parameterized class of positive maps: the *decomposable* ones

$$L(X) = \sum_i A_i X A_i^* + \sum_i B_i X^T B_i^*$$

Nice, but we know already that can do better...

Higher relaxations

Broaden the class of allowed Z to those for which

$$\sum |x_i|^2 \sum Z_{ij;kl} x_i x_j^* y_k y_l^*$$

is a sum of squared magnitudes.

Also semidefinite programs.

Strictly stronger than PPT.

Can search directly for the witness Z .

Second Relaxation

$$\sum |x_i|^2 \sum Z_{ij;kl} x_i x_j^* y_k y_l^* = \sum |G_{m;ijk} x_i y_k x_j|^2 + \sum |H_{m;ijk} x_i^* y_k x_j|^2 + \sum |K_{m;ijk} x_i y_k^* x_j|^2$$

minimize $\text{Tr}[\rho Z]$

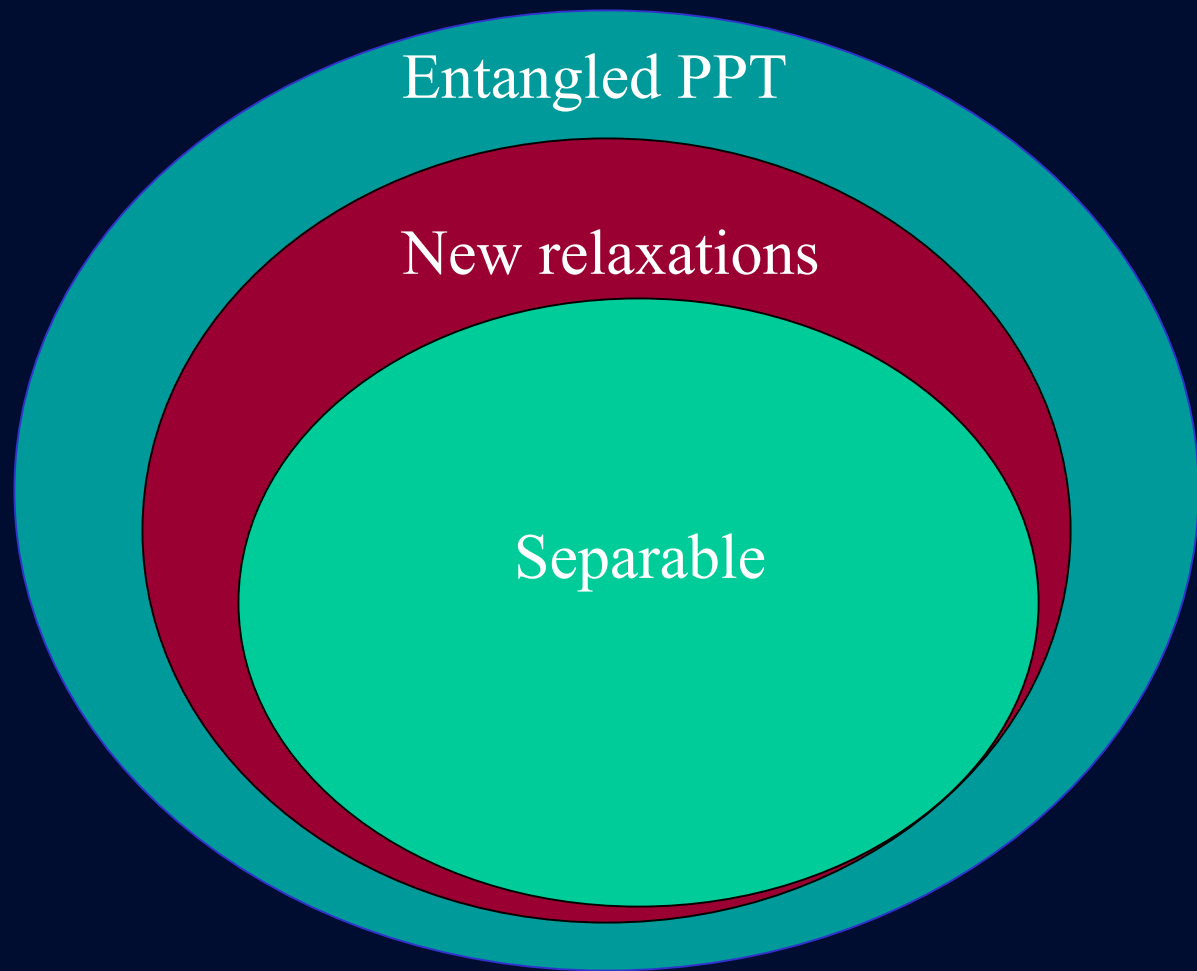
subject to $G \geq 0 \quad H \geq 0 \quad K \geq 0$

$$(x \otimes y \otimes x)^* (Z \otimes I) (x \otimes y \otimes x) = (x \otimes y \otimes x)^* (G + H^{T_1} + K^{T_2}) (x \otimes y \otimes x)$$

If the minimum is less than zero then ρ is **entangled**.

The dual of the state extension SDP.

Entangled not-PPT



Hierarchy of conditions

- Using different factors, obtain a nested family of SDPs.
- A section of the SOS approximations to the cone of nonnegative polynomials.
- Essentially similar procedures for many other NP-hard cones: copositive matrices, etc.
- Special case of more general P-satz approach.
- More general constructions are complete.
- Appealing properties: invariance under LOCC?

Numerical results

- SDPs solved using SeDuMi (Jos Sturm).
- Tested many known families of PPT entangled states.
- These correspond to bihermitian forms that are not SOS.
- For **all** examples tried, the second-level test always succeeded.
- But, counterexamples *must* exist.
- In some cases, can obtain closed-form solutions for witnesses.
- Exploiting symmetry helps a lot.

Summary

- Can decide/certify entanglement via SDP/SOS.
- Hierarchy of tests.
- Dual interpretations
 - State extensions
 - Entanglement witnesses of specific kind
- Simplest case, reduces to PPT criterion.
- Second level, detects all states tried!
- Explicit witnesses, easily verifiable.