

# Some applications of moments and SDP-relaxations

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- global optimization (with polynomials)
- systems of polynomial equations
- bounds on measures with moment conditions
- invariant measures

Consider the **global optimization** problem

$$\mathbb{P} \mapsto p^* := \min\{g_0(x) \mid g_i(x) \geq 0, i = 1, \dots, m\},$$

where  $g_i(x) : \mathbf{R}^n \rightarrow \mathbf{R}$  are all real-valued polynomials. Let

$$\mathbb{K} := \{x \in \mathbf{R}^n \mid g_i(x) \geq 0, i = 1, \dots, m\},$$

be the feasible set. Let

$$1, x_1, x_2, \dots, x_n, x_1^2, x_1x_2, \dots, x_n^r,$$

be a basis (of dimension  $s(r)$ ) of the vector space of real-valued polynomials of degree at most  $r$ , and in this basis write

$$p(x) = \sum_{\alpha \leq r} p_\alpha x^\alpha = p_\alpha [x_1^{\alpha_1} \dots x_n^{\alpha_n}],$$

with  $\alpha = \sum_{i=1}^n \alpha_i$ , and  $p \in \mathbf{R}^{s(r)}$  its vector of coefficients.

## The univariate case

In this case one considers

$$\mathbb{P} \rightarrow p^* = \min_{x \in \mathbb{K}} g_0(x), \text{ with } \begin{cases} \mathbb{K} \equiv \mathbf{R} \\ \mathbb{K} \equiv \mathbf{R}_+ \\ \mathbb{K} \equiv [a, b] \end{cases}$$

With  $\mathbb{K} \equiv \mathbf{R}$ , Shor (1987) was the first to show that  $\mathbb{P}$  is a convex problem. Later Nesterov (1997) proposed an LMI formulation for the three cases.

The multivariate case is NP-hard in general.

Recent approaches (Lasserre, Nesterov, Parrilo,...) use results from

- (real) algebraic geometry (**positive polynomials**)
- functional analysis (**moments**),
- convex analysis (**SDP**)

## Two dual points of view

$p^*$  global minimum  $\Leftrightarrow g_0(x) - p^* \geq 0 \forall x \in \mathbb{K}$ , i.e.,

$g_0(x) - p^*$  **is a nonnegative polynomial on  $\mathbb{K}$ .**

$\Rightarrow$  Characterize these polynomials ....

$\rightarrow$  (real) algebraic geometry

But we also have

$$p^* = \min_{\mu} \left\{ \int g_0(x) \mu(dx) \mid \mu \in \mathcal{P}(\mathbb{K}) \right\},$$

where  $\mathcal{P}(\mathbb{K})$  is the space of probability measures with support contained in  $\mathbb{K}$ . Indeed,

$$(0.1) \quad \int g_0(x) \mu(dx) \geq p^*, \quad \forall \mu \in \mathcal{P}(\mathbb{K}),$$

and with  $\mu := \delta_{x^*}$  at a global minimizer  $x^*$ ,

$$\int g_0(x) \delta_{x^*}(dx) = p^*.$$

Observe that both properties are valid for global optima only. Moreover, (0.1) is a linear optimization problem.

$$\min_{\mu} \{ \langle g_0, \mu \rangle \mid \langle 1_{\mathbb{K}}, \mu \rangle = 1; \langle 1_{\mathbb{K}^c}, \mu \rangle = 0; \mu \geq 0 \}.$$

$\Rightarrow$  characterize these measures  $\mu$  .... (functional analysis)

## II. The point of view of moments

The dual linear program of (0.1) is

$$\max_{\gamma, \lambda} \{ \gamma \mid \lambda 1_{\mathbb{K}^c} + \gamma 1_{\mathbb{K}} \leq g_0(x), \forall x \in \mathbf{R}^n \},$$

or, equivalently,  $\max_{\gamma} \{ \gamma \mid g_0(x) - \gamma \geq 0 \text{ on } \mathbb{K} \}$ .

Writing

$$\int g_0(x) \mu(dx) = \sum_{\alpha} (g_0)_{\alpha} \int x^{\alpha} \mu(dx) = \sum_{\alpha} (g_0)_{\alpha} y_{\alpha},$$

with  $y_{\alpha}$  being a moment of order  $\alpha$  of  $\mu$ , (0.1) reads

$$\begin{cases} \min_y \sum_{\alpha} (g_0)_{\alpha} y_{\alpha} \\ y_{\alpha} = \int x^{\alpha} \mu(dx) \quad \forall \alpha \text{ for some probability } \mu \text{ on } \mathbb{K} \end{cases}$$

Hence, translate the condition

*there is some probability  $\mu$  on  $\mathbb{K}$  such that*

$$y_{\alpha} = \int x^{\alpha} \mu(dx), \quad \forall \alpha \leq r,$$

into a condition on the vector  $y$ . This the  **$\mathbb{K}$ -moment problem**, which dates back to Hausdorff, Markov, Stieltjes, Hamburger, etc ...

- $\mathbb{K} = \mathbf{R}$  (truncated) **Hamburger problem**
- $\mathbb{K} = (\mathbf{R})^+$  (truncated) **Stieltjes problem**
- $\mathbb{K} = [a, b]$  (truncated) **Hausdorff problem**

In the one-dimensional case, there exist **Necessary and sufficient conditions** in terms of **positive semidefinite constraints** on related Hankel matrices  $H(y)$ ...

**Particular case of  $\mathbb{K} = [0, 1]^n$**

### **Hausdorff moment conditions**

Ex:  $n = 2$ ; Given a measure  $\mu(d(x, z))$  on  $\mathbf{R}^2$ , let

$$\int x^i (1-x)^m z^j (1-z)^p d\mu = \sum_{k=0}^m \sum_{l=0}^p \binom{m}{k} \binom{p}{l} x^{i+k} y^{j+l} d\mu.$$

Then, given a vector  $y \in \mathbf{R}^\infty$ , there exists a measure  $\mu$  on  $[0, 1]^2$  with

$$\int x^i z^j d\mu = y_{i,j} \quad \forall i, j = 0, 1, \dots$$

if and only if

$$\sum_{k=0}^m \sum_{l=0}^p \binom{m}{k} \binom{p}{l} y_{i+k, j+l} \geq 0,$$

for all  $m, p = 1, 2, \dots$  and all  $i, j = 0, 1, \dots$

(due to Hausdorff, Bernstein).

Hence, the Hausdorff moment conditions are linear constraints on the  $y_\alpha$ 's.

... BUT ... notice the **large binomial coefficients** involved ....



## II. The point of view of positive polynomials

=**Hilbert's 17th problem** on the representation of positive polynomials. In the one dimensional case,

$$p(x) \geq 0 \Leftrightarrow p(x) = \sum_{k=1}^s q_k(x)^2.$$

Not true anymore in  $\mathbf{R}^n$  ....

### Representation of polynomials,

positive on  $\mathbb{K} := \{x \in \mathbf{R}^n \mid g_k(x) \geq 0, k = 1, \dots, m\}$

**Theorem :** [Schmüdgen, Putinar, Jacobi and Prestel]

*Assume there is a polynomial  $u(x) : \mathbf{R}^n \rightarrow \mathbf{R}$  such that*

$$u(x) = q(x) + \sum_{k=1}^m g_k(x)v(x),$$

*for some polynomials  $q(x), v(x)$  both sums of squares, and such that  $\{u(x) \geq 0\}$  is compact. Then:*

*Every polynomial,  $p(x) : \mathbf{R}^n \rightarrow \mathbf{R}$ , strictly positive on  $\mathbb{K}$  has the representation:*

$$(0.2) \quad p(x) = \sum_{j=1}^{r_0} q_j(x)^2 + \sum_{k=1}^m g_k(x) \sum_{j=1}^{r_k} t_{kj}(x)^2,$$

*for some (finite) family of polynomials  $\{q_j(x)\}, \{t_{kj}(x)\}$ .*

For instance, the representation (0.2) holds whenever  $\{g_k(x) \geq 0\}$  is compact for some  $k$ , when all the  $g_k(x)$  are linear and  $\mathbb{K}$  is compact, etc... In practice, one may also add the redundant constraint  $M - \sum_i x_i^2 \geq 0$  for  $M$  large enough. This is also the case when one has integrality constraints  $x_i^2 = x$  for all  $i$ .  $\Rightarrow$  **very general result!**

### The case of a convex polytope

$$\mathbb{K} := \{x \in \mathbf{R}^n \mid Ax \leq b\}$$

for some matrix  $A \in \mathbf{R}^{m \times n}$ .

#### Theorem : [Cassier (1984), Handelman]

*Every polynomial,  $p(x) : \mathbf{R}^n \rightarrow \mathbf{R}$ , strictly positive on  $\mathbb{K}$  has the representation:*

$$p(x) = \sum_{|\alpha| \leq s} c_\alpha (b - Ax)_1^{\alpha_1} (b - Ax)_2^{\alpha_2} \cdots (b - Ax)_m^{\alpha_m}$$

*for some integer  $s$  and nonnegative coefficients  $\{c_\alpha\}$ .*

Notice the **exponential** number of terms, in contrast to the “linear” Schmüdgen-Putinar representation in terms of squares.

## SDP-relaxations

### Moment matrix.

Let  $(1, \{y\}) \in \mathbf{R}^{s(2r)}$ . With  $\alpha \in \mathbb{N}^n$ , and  $|\alpha| = \sum_i \alpha_i$ ,

$$y_{\alpha_1, \dots, \alpha_n} \rightsquigarrow \int x_1^{\alpha_1} \cdots x_n^{\alpha_n} d\mu.$$

For instance, in  $\mathbf{R}^2$  and with  $r = 2$ , and in the basis of monomials, the **moment matrix**  $M_r(y)$  reads

$$M_2(y) = \begin{bmatrix} 1 & | & y_{1,0} & y_{0,1} & | & y_{2,0} & y_{1,1} & y_{0,2} \\ \hline & & \hline y_{1,0} & | & y_{2,0} & y_{1,1} & | & y_{3,0} & y_{2,1} & y_{1,2} \\ y_{0,1} & | & y_{1,1} & y_{0,2} & | & y_{2,1} & y_{1,2} & y_{0,3} \\ \hline & & \hline y_{2,0} & | & y_{3,0} & y_{2,1} & | & y_{4,0} & y_{3,1} & y_{2,2} \\ y_{1,1} & | & y_{2,1} & y_{1,2} & | & y_{3,1} & y_{2,2} & y_{1,3} \\ y_{0,2} & | & y_{1,2} & y_{0,3} & | & y_{2,2} & y_{1,3} & y_{0,4} \end{bmatrix}$$

In general, if  $M_r(y)(i, 1) = y_\alpha$  and  $M_r(y)(1, j) = y_\beta$  then

$$M_r(y)(i, j) = y_{\alpha+\beta} = y_{\alpha_1+\beta_1, \dots, \alpha_n+\beta_n}$$

## Localizing matrix.

Given a polynomial  $\theta : \mathbf{R}^n \rightarrow \mathbf{R}$  of degree  $w$ , with coefficient vector  $\theta \in \mathbf{R}^{s(w)}$ , let  $M_r(\theta y)$  be the **localizing matrix**

$$M_r(\theta y)(i, j) := \sum_{\alpha} \theta_{\alpha} y_{\{\alpha(i, j) + \alpha\}}.$$

For instance, with  $x \mapsto \theta(x) = 1 - x_1^2 - x_2^2$ ,  $M_2(\theta y) =$

$$\begin{bmatrix} 1 - y_{20} - y_{02}, & y_{10} - y_{30} - y_{12}, & y_{01} - y_{21} - y_{03} \\ y_{10} - y_{30} - y_{12}, & y_{20} - y_{40} - y_{22}, & y_{11} - y_{21} - y_{12} \\ y_{01} - y_{21} - y_{03}, & y_{11} - y_{21} - y_{12}, & y_{02} - y_{22} - y_{04} \end{bmatrix}.$$

If  $M_r(y)(i, j) = y_{\beta}$  then

$$M_r(\theta y)(i, j) = \sum_{\alpha} \theta_{\alpha} y_{\beta + \alpha}$$

that is,

$$M_r(\theta y)(i, j) \rightsquigarrow \int x^{\beta} \theta(x) \mu(dx)$$

If  $(1, \mathbf{y})$  is the vector of moments up to order  $2r$  of some probability measure  $\mu$  on the Borel sets of  $\mathbf{R}^n$ , then for every polynomial  $q(x) : \mathbf{R}^n \rightarrow \mathbf{R}$  of degree at most  $r$ ,

$$\langle q, M_r(\mathbf{y})q \rangle = \int q(x)^2 \mu(dx),$$

so that  $M_r(\mathbf{y}) \succeq 0$ . Similarly,

$$\langle q, M_r(\theta \mathbf{y})q \rangle = \int \theta(x)q(x)^2 \mu(dx),$$

and thus  $M_r(\theta \mathbf{y}) \succeq 0$  whenever  $\mu$  is supported on  $\{\theta(x) \geq 0\}$ .

The theory of moments identifies those vectors  $\mathbf{y}$  with  $M_r(\mathbf{y}) \succeq 0$  that are the moments of some measure  $\mu$ .

The  $\mathbb{K}$ -moment problem identifies those vectors  $\mathbf{y}$  with  $M_r(\mathbf{y}) \succeq 0$  that are moment of a measure  $\mu$  with support contained in  $\mathbb{K}$ .

Dual theory in algebraic geometry of representation of polynomials, positive on a semi-algebraic set  $\mathbb{K}$

Introduce the family  $\{\mathbb{Q}_i\}$  of SDP-relaxations

$$\mathbb{Q}_i \begin{cases} \min_y \sum_{\alpha} (g_0)_{\alpha} y_{\alpha} \\ M_i(y) \succeq 0 \\ M_{i-v_k}(g_k y) \succeq 0, \quad k = 1, \dots, m. \end{cases}$$

and the family  $\{(\mathbb{Q}_i)^*\}$  of their dual

$$\mathbb{Q}_i^* \begin{cases} \max_{X, Z_1, \dots, Z_m \succeq 0} -X(1, 1) - \sum_{k=1}^m g_k(0) Z_k(1, 1) \\ \text{s.t. } \langle X, B_{\alpha} \rangle + \sum_{k=1}^m \langle Z_k, C_{\alpha}^k \rangle = (g_0)_{\alpha}, \quad \forall \alpha. \end{cases}$$

where we write

$$M_i(y) = \sum_{\alpha} y_{\alpha} B_{\alpha}$$

$$M_{i-v_k}(g_k y) = \sum_{\alpha} y_{\alpha} C_{\alpha}^k, \quad k = 1, \dots, m,$$

### Interpretation :

From the dual,  $\max \mathbb{Q}_i^* \leq p^*$  and

$$p(x) - \max \mathbb{Q}_i^* = \sum_{j=1}^s q_j(x)^2 + \sum_{k=1}^m g_k(x) \left[ \sum_{l=1}^{s_k} q_{kl}(x)^2 \right],$$

with  $\text{degree}(q_i) \leq i$  and  $\text{degree}(q_{kl}) \leq i - v_k$ .

**SDP-relaxation**  $\longleftrightarrow$  **Schmüdgen-Putinar representation** of  $p(x) - p^*$ .

**Theorem 1.** *Assume that there exists a polynomial  $u(x) : \mathbf{R}^n \rightarrow \mathbf{R}$  of the form (0.2) with  $\{u(x) \geq 0\}$  compact. Then:*

$$(0.3) \quad \inf \mathbb{Q}_i \uparrow p^* = \min \mathbb{P}.$$

*In addition, if  $p(x) - p^*$  has the representation (0.2) for polynomials  $\{q_j(x)\}$  et  $\{t_{kj}(x)\}$ , of degree at most  $N$ , then*

$$(0.4) \quad p^* = \min \mathbb{Q}_i, \quad \forall i \geq N,$$

*and for every optimal solution  $x^*$  of  $\mathbb{P}$ , the vector*

$$(0.5) \quad y^* := (x_1^*, \dots, x_n^*, \dots, (x_1^*)^{2i}, \dots, (x_n^*)^{2i})$$

*is an optimal solution of  $\mathbb{Q}_i$ .*

## Karush-Kuhn-Tucker Global optimality conditions

**Proposition 2.** *Assume that there exists a polynomial  $u(x) : \mathbf{R}^n \rightarrow \mathbf{R}$  of the form (0.2) with  $\{u(x) \geq 0\}$  compact, and let  $x^*$  be an optimal solution of  $\mathbb{P}$ . If  $p(x) - p^*$  has the representation (0.2), then*

$$(0.6) \quad g_k(x^*) \left[ \sum_{j=1}^{r_k} t_{kj}(x^*)^2 \right] = 0, \quad k = 1, \dots, m$$

$$(0.7) \quad \nabla g_0(x^*) = \sum_{k=1}^m \nabla g_k(x^*) \left[ \sum_{j=1}^{r_k} t_{kj}(x^*)^2 \right]$$

Thus, we may interpret the representation (0.2) of  $p(x) - p^*$  as a **global optimality condition** à la Karush-Kuhn-Tucker, with **polynomials multipliers**  $\sum_{j=1}^{r_k} t_{kj}(x)^2$  in lieu of the usual scalars  $\lambda_k^*$ ,  $k = 1, \dots, m$ .

Moreover, if  $(x^*, \lambda^*)$  is KKT optimal point of  $\mathbb{P}$ , and the gradients  $\{\nabla g_k(x^*)\}$  are linearly independent, then

$$\sum_{j=1}^{r_k} t_{kj}(x)^2 = \lambda_k^*, \quad \forall k = 1, \dots, m.$$



## LP-Relaxations

**Basic idea:** [Shor, Serali and Adams]

(1) add **redundant** constraints of the form

$$g_1(x)^{\alpha_1} g_2(x)^{\alpha_2} \cdots g_m(x)^{\alpha_m} \geq 0,$$

with  $|\alpha| \leq \delta$ , fixed.

(2) **linearize** all the terms

$$y \mapsto y_\beta := x_1^{\beta_1} x_2^{\beta_2} \cdots x_n^{\beta_n},$$

to replace the nonlinear constraint

$$g_1(x)^{\alpha_1} \cdots g_m(x)^{\alpha_m} \geq 0,$$

by the linear constraint

$$\sum_{\beta} c_{\beta} y_{\beta} \geq b$$

The LP-Relaxation of order  $\delta$  is the LP program

$$\mathbb{P}_{\delta} \rightarrow \min_{y_{\beta}} \{ c'_{\beta} y_{\beta} \mid A_{\delta} y \geq b_{\delta} \},$$

with dual

$$\mathbb{P}_{\delta}^* \rightarrow \max_{\lambda \geq 0} \{ b'_{\delta} \lambda \mid A'_{\delta} \lambda = c_{\delta} \}$$

## Interpretation

Let  $\rho_\delta := \min \mathbb{P}_\delta = \max \mathbb{P}_\delta^*$ . Then :  $\rho_\delta \leq p^*$  and :

$$g_0(x) - \rho_\delta = \sum_{|\alpha| \leq \delta} \lambda_\alpha g_1(x)^{\alpha_1} g_2(x)^{\alpha_2} \cdots g_m(x)^{\alpha_m}, \quad x \in \mathbf{R}^n$$

The dual aims at representing  $g_0(x) - p^*$  as in **Cassier**, **Handelman**'s representation, which in principle is valid only when the  $g_k$  are linear and define a polytope  $\mathbb{K}$ .

**Corollary :** *Let  $\mathbb{K}$  be a convex polytope, i.e., the  $g_k$ 's are linear : Then*

$$\rho_\delta \uparrow p^* \quad \text{as } |\delta| \rightarrow \infty,$$

*that is, the LP-relaxations converge.*

**Remarks:** (i) ill-conditioned when  $\delta$  large.

**Example :**  $\mathbb{K} = [0, 1]^n$ . From the constraints  $x \geq 0$  and  $(1 - x_i) \geq 0$ , the linear constraints coming from the linearization of  $\prod_{i \in I} x_i^{\alpha_i} \prod_{j \in J} (1 - x_j)^{\alpha_j}$  contains **large binomial coefficients**.

They are in fact the **Hausdorff moment conditions** on  $y$  to be the vector of moments of a probability measure on  $[0, 1]^n$ .

Let  $I(x)$  be the set of active constraints at a feasible point  $x$ , i.e.,  $i \in I(x) \Rightarrow g_i(x) = 0$ .

(ii) No relaxation can be exact if a global minimum is in the interior of  $\mathbb{K}$  or if there is a nonoptimal feasible point  $x$  with  $I(x) = I(x^*)$ .

## Conclusion

**SDP-relaxations**  $\mathbb{Q}_i$

**LMI constraints**

$$p(x) - \min \mathbb{Q}_i = \Sigma^2 + \sum_{k=1}^m g_k(x) \Sigma^2$$

**Schmüdgen-Putinar**

$$0 - 1 \rightarrow \min \mathbb{Q}_{n+v} = p^*$$

$\mathbb{K}$  **compact**.  $\min \mathbb{Q}_i \uparrow p^*$

$n = 1$ ; a single relaxation

SDP-packages : limited

**LP-relaxations**  $\mathbb{P}_i$

**Linear constraints**

$$p(x) - \min \mathbb{P}_i = \sum_{\alpha} g_1^{\alpha_1} \cdots g_m^{\alpha_m}$$

**Cassier, Handelman** (polytope)

$$0 - 1 \rightarrow \min \mathbb{P}_n = p^*$$

$\mathbb{K}$  **polytope**.  $\min \mathbb{P}_i \uparrow p^*$

$$n = 1; \min \mathbb{P}_i \uparrow p^*$$

LP-packages : unlimited

ill-conditionning; binomial coeff.

## Bounds on measures with moment conditions

[Lasserre (2002)], *Annals Appl. Prob.*

Let  $\Gamma \subset \mathbb{N}^n$  and let  $\{\gamma_\alpha\}_{\alpha \in \Gamma}$  be a given finite sequence of scalars. **Problem:** Given a semi-algebraic set

$$\mathbb{K} := \{x \in \mathbf{R}^n \mid g_i(x) \geq 0, \quad i = 1, \dots, m\}$$

we want to find, or approximate

$$\rho^* := \sup_{\mu \in \mathcal{P}(\mathbf{R}^n)} \left\{ \mu(\mathbb{K}) \mid \int x^\alpha d\mu = \gamma_\alpha \quad \alpha \in \Gamma \right\}$$

Applications in Probability, Finance, Queuing, ...

Work motivated by nice results from **Bertsimas and Popescu** (1999)-(2002) for the case  $\mathbb{K}$  convex, and first- and second order moment conditions (see also further extensions).

Write  $\mu = \varphi + \psi$  with  $\varphi(K^c) = 0$  and let  $\{y_\alpha, z_\alpha\}$  be the respective moments of  $\varphi, \psi$ , so that

$$\int x^\alpha d\mu = y_\alpha + z_\alpha \quad \alpha \in \mathbb{N}^n.$$

$$\rho^* = \begin{cases} \sup y_0 \\ \text{s.t. } y_\alpha + z_\alpha = \gamma_\alpha \quad \alpha \in \Gamma \end{cases}$$

## SDP-relaxation

$$\mathbb{Q}_r \left\{ \begin{array}{ll} \sup y_0 & \\ \text{s.t. } M_r(\mathbf{y}), M_r(\mathbf{z}) & \succeq 0 \\ M_{r-v_i}(g_i \mathbf{y}) & \succeq 0 \quad i = 1, \dots, m \\ y_\alpha + z_\alpha & = \gamma_\alpha \quad \alpha \in \Gamma \end{array} \right.$$

**Theorem:** (a) As  $r \rightarrow \infty$

$$\sup \mathbb{Q}_r \downarrow \delta \geq \rho^*.$$

(b) If in addition,  $\mathbb{Q}_r$  is solvable and an optimal solution  $\mathbf{y}^*, \mathbf{z}^*$  satisfies

$$\text{rank} M_r(\mathbf{y}^*) = \text{rank} M_{r-d}(\mathbf{y}^*); \quad \text{rank} M_r(\mathbf{z}^*) = \text{rank} M_{r-1}(\mathbf{z}^*),$$

then

$$\max \mathbb{Q}_r = \rho^* = \max_{\mu \in \mathcal{P}(\mathbf{R}^n)} \left\{ \mu(\mathbb{K}) \mid \int x^\alpha d\mu = \gamma_\alpha, \quad \alpha \in \Gamma. \right.$$

## Invariant prob. measures of Markov chains

Let  $(X, \mathcal{B}, Q)$  be a time-homogeneous Markov chain  $\Phi_\bullet = (\Phi_0, \Phi_1, \dots)$  with **state space**  $X$ , and **t.p.f.**  $Q$ .

- $Q(x, \cdot)$  is a **prob. measure** on  $\mathcal{B}$  for all  $x \in X$ .
- $x \mapsto Q(x, B)$  is **measurable** for all  $B \in \mathcal{B}$ .

$$\text{Prob}(\Phi_t \in B \mid \Phi_{t-1} = x) = Q(x, B) \quad B \in \mathcal{B}, x \in X.$$

$\mu \in \mathcal{P}(X)$  is an invariant prob. measure for the MC  $\Phi_\bullet$  if

$$\mu(B) = \int_X P(x, B) \mu(dx) \quad \forall B \in \mathcal{B}.$$

If  $\mu$  is unique and  $f \in L_1(\mu)$  then :

$$\lim_{T \rightarrow \infty} E_x \frac{1}{T} \sum_{t=0}^{T-1} f(\Phi_t) = \int_X f d\mu \quad \mu\text{-a.e.},$$

and for  $\mu$ -a.a.  $x \in X$ ,

$$\lim_{T \rightarrow \infty} \frac{1}{T} \sum_{t=0}^{T-1} f(\Phi_t) = \int_X f d\mu \quad P_x\text{-a.s.}$$

**Simulation** gives only an **estimate** of  $\int_X f d\mu$ .

**Remark:**  $X \equiv \mathbf{R}^n$ . If  $Qf \in \mathbf{R}[x]$  when  $f \in \mathbf{R}[x]$  then

$$y_\alpha = \int x^\alpha d\mu = \int (Qx^\alpha) d\mu = \langle A_\alpha, y \rangle$$

**SDP-relaxations:** Let  $f = \sum_{\alpha} f_{\alpha} x^{\alpha} \in \mathbf{R}[x]$ .

$$\mathbb{Q}_r \begin{cases} \max_y \text{ (or } \min_y) & \sum_{\alpha} f_{\alpha} y_{\alpha} \\ \text{s.t. } M_r(y) & \succeq 0 \\ y_{\alpha} - \langle A_{\alpha}, y \rangle & = 0, \quad \forall |\alpha| \leq r \end{cases}$$

$$\min \mathbb{Q}_r \leq \int_X f d\mu \leq \max \mathbb{Q}_r \quad \forall r$$

so that

$$\sup_r \min \mathbb{Q}_r = \underline{\rho} \leq \int_X f d\mu \leq \bar{\rho} = \inf_r \max \mathbb{Q}_r$$

If  $\mu$  is the unique inv. prob. measure then one gets upper and lower bounds on  $\int f d\mu$ . If not, then :

$$\sup_r \min \mathbb{Q}_r = \underline{\rho} \leq \inf_{\mu \in \mathcal{Q}} \int_X f d\mu$$

and

$$\sup_{\mu \in \mathcal{Q}} \int_X f d\mu \leq \bar{\rho} = \inf_r \max \mathbb{Q}_r$$

**LP-relaxations: Stockbridge, Helmes**

$$\text{LP}_r \begin{cases} \max_y \text{ (or } \min_y) & \sum_{\alpha} f_{\alpha} y_{\alpha} \\ \text{s.t. Hausdorff moment conditions} & \\ y_{\alpha} - \langle A_{\alpha}, y \rangle & = 0, \quad \forall |\alpha| \leq r \end{cases}$$

SDP-relaxations better than LP-relaxations



## I. Barnsley Iterated function systems:

$$x_{t+1} = f_{\xi_t}(x_{t-1}), \quad t = 1, \dots,$$

- $X \equiv \mathbf{R}^n$ ,  $\xi_{\bullet}$  is a Markov chain on a finite set  $S = \{1, \dots, m\}$  with **t.p.f.**  $P(\xi_t = j | \xi_{t-1} = i) = p_{ij}$  and unique invariant prob. distribution  $\gamma = (\gamma_1, \dots, \gamma_m)$ .
- $f_{\xi} : \mathbf{R}^n \rightarrow \mathbf{R}$  is a polynomial

Evaluate or approximate

$$\rho^* := \lim_{T \rightarrow \infty} E_{\nu} \left[ \frac{1}{T} \sum_{t=0}^{T-1} h(x_t) \right],$$

when  $h := \mathbb{1}_{\mathbb{K}}$  or  $h \in \mathbf{R}[x_1, \dots, x_n]$ , and  $\nu \in \mathcal{P}(\mathbf{R}^n)$  is the initial prob. distribution of  $x_0 \in \mathbf{R}^n$ .

$\{X_t\}$  is a time-homogeneous,  $\mathbf{R}^n$ -valued Markov chain.

Usually  $\rho^*$  is **estimated** via **Simulation**. The result depends on the initial distribution if there are several invariant prob. distributions.

Let  $\mu$  be an invariant prob. distribution and assume that all its moments  $\{y_\alpha\}$  are finite.

$$y_\alpha = \int_{\mathbf{R}^n} x^\alpha d\mu = \int_{\mathbf{R}^n} \sum_{j \in S} \gamma_j f_j(x)^\alpha d\mu = \langle A_\alpha, y \rangle$$

**Example: Logistic map:**

$X \equiv [0, 1]$  and  $x_{t+1} = 4x_t(1 - x_t)$ .

$$y_n = \int_0^1 x^n d\mu = [4x(1 - x)]^n d\mu = \sum_{j=0}^{2n} \beta_{jn} y_j$$

**Invariant prob. measures:**

- Uncountably many inv. prob. measures with support, all cycles of order 1, 2, etc ...

- 1 inv. prob. measure, absolutely continuous w.r.t.  $\lambda$ , with density  $x \mapsto [\pi \sqrt{x(1 - x)}]^{-1}$

## II. Diffusions

**Exit times.** Consider a continuous Markov process on  $\Phi = \{\Phi_t, t \geq 0\}$  on  $\mathbf{R}^n$ , with infinitesimal generator  $\mathcal{A}$  (with domain  $\mathcal{D}$ ).

Let  $E_0 \subset \mathbf{R}^n$  be a bounded open set and  $E_0^c$  its complement. Let  $\tau$  be the **first time** the process  $\Phi$  **hits**  $E_0^c$ .

**Problem: Evaluate or approximate the distribution of  $\tau$ , e.g., its moments  $E[\tau]$ ,  $E[\tau^n], \dots$**

Let  $\mu_0, \mu_1$  be the occupation measure and the exit time distribution,

$$\mu_0(B) = E \int_0^\tau \mathbb{1}_B(\Phi_s) ds; \quad \mu_1(B) = \text{Prob}(X_\tau \in B) \quad B \in \mathcal{B}.$$

It follows that

$$** \quad f(x_0) + \int_{E_0} \mathcal{A}f(x) \mu_0(dx) - \int_{E_0^c} f(x) \mu_1(dx) = 0.$$

In general, we have  $\mathcal{A} = \partial/\partial x_i, \partial^2/\partial x_i \partial x_j, \dots$  so that  $\mathcal{A}f \in \mathbf{R}[x]$  if  $f \in \mathbf{R}[x]$ .

Then (\*\*\*) generates **linear constraints** on the **moments** of  $\mu_0, \mu_1$ !

**Example:** Cox-Ingersoll-Ross interest rate model (Stockbridge and Helmes).

$$dY_t = (aY_t + \beta)dt + \sigma\sqrt{Y_t}dW_t,$$

with  $Y(0) \in (r, 1)$ ,  $\alpha \in \mathbf{R}$ ,  $\beta, \sigma \geq 0$  and  $0 < r < 1$ .

$$\mathcal{A}f(x) = \frac{\sigma^2}{2}x f''(x) + (\alpha x + \beta)f'(x),$$

with  $f$  twice continuously differentiable.

Let  $\tau$  be the first exit time of  $\{Y_t\}$  from  $(r, 1)$ , so that  $E_0 = (r, 1)$  and  $E_0^c = \{r\} \cup \{1\}$ . So  $\mu_0$  has support on  $(r, 1)$  and  $\mu_1 = (\mu_1(\{r\}), \mu_1(\{1\})) = (p, q)$  with  $p + q = 1$ .

Let  $\{y_\alpha\}$  and  $\{z_\alpha\}$  be the moments of  $\mu_0$  and  $\mu_1$ .

$$z^\alpha = pr^\alpha + q \quad \alpha \in \mathbb{N}.$$

When  $f = x^\alpha$ , the equation

$$f(x_0) + \int_{E_0} \mathcal{A}f(x)\mu_0(dx) - \int_{E_0^c} f(x)\mu_1(dx) = 0.$$

define **linear constraints**

$$\langle U_\alpha, y \rangle + pr^\alpha + q = 0, \quad \alpha \in \mathbb{N},$$

on the moments  $y$  and the scalars  $p, q$

As  $E[\tau] = \mu_0(X)$ , the SDP-relaxation reads:

$$\mathbb{Q}_m \begin{cases} \max \text{ (or, min) } y_0 \\ M_r(y) \succeq 0 \\ \langle U_\alpha, y \rangle - pr^\alpha - q = 0 \\ p, q \geq 0, p + q = 1 \end{cases} \quad \forall |\alpha| \leq m$$

Again

$$\sup_m \min \mathbb{Q}_m \leq E[\tau] \leq \inf_m \max \mathbb{Q}_m,$$

and very good results are reported by Stockbridge and Helmes for the LP-relaxations (which are less efficient than SDP-relaxations)

Extension to higher moments  $E[\tau^n]$  easy by using an extended generator for the joint process  $\{(X_t, t), t \geq 0\}$ .