

MANIFOLDS WITH SPECIAL HOLONOMY

LECTURE 4:

G_2 AND $\text{Spin}(7)$

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We are now ready to consider the exceptional cases, starting with the one in dimension 7.

n	$\mathfrak{h} \subseteq \mathfrak{so}(n)$	$K(\mathfrak{h})$ as an \mathfrak{h} -module
n	$\mathfrak{so}(n)$	$\mathbb{R} \oplus S_0^2(\mathbb{R}^n) \oplus W_n(\mathbb{R}^n)$
$n = 2m > 2$	$\mathfrak{u}(m)$	$\mathbb{R} \oplus S_0^{1,1}(\mathbb{C}^m)^{\mathbb{R}} \oplus S_0^{2,2}(\mathbb{C}^m)^{\mathbb{R}}$
$n = 2m > 2$	$\mathfrak{su}(m)$	$S_0^{2,2}(\mathbb{C}^m)^{\mathbb{R}}$
$n = 4m > 4$	$\mathfrak{sp}(m) \oplus \mathfrak{sp}(1)$	$\mathbb{R} \oplus S^4(\mathbb{C}^{2m})^{\mathbb{R}}$
$n = 4m > 4$	$\mathfrak{sp}(m)$	$S^4(\mathbb{C}^{2m})^{\mathbb{R}}$
$n = 7$	\mathfrak{g}_2	$V^{0,2} \simeq \mathbb{R}^{77}$
$n = 8$	$\mathfrak{spin}(7)$	$V^{0,2,0} \simeq \mathbb{R}^{168}$

5. The exceptional holonomy G_2 . As usual, we'll start with linear algebra. Consider the 3-form ϕ_0 defined on \mathbb{R}^7 by the formula

$$\phi_0 = dx^{123} + dx^{145} + dx^{167} + dx^{246} - dx^{257} - dx^{356} - dx^{347}$$

where dx^{ijk} means $dx^i \wedge dx^j \wedge dx^k$. Now define

$$G_2 = \{ A \in GL(7, \mathbb{R}) \mid A^*(\phi_0) = \phi_0 \}.$$

It is not obvious from this what sort of group G_2 is (though it is a closed subgroup, by definition). A few subgroups can be discerned, though:

Writing $\mathbb{R}^7 = \mathbb{R} \cdot e_1 \oplus e_1^\perp = \mathbb{R} \cdot e_1 \oplus \mathbb{R}^6 = \mathbb{R} \cdot e_1 \oplus \mathbb{C}^3$ and setting

$$z^1 = x^2 + ix^3, \quad z^2 = x^4 + ix^5, \quad z^3 = x^6 + ix^7$$

allows us to express ϕ_0 in the form

$$\phi_0 = dx^1 \wedge \frac{i}{2} (dz^1 \wedge d\bar{z}^1 + dz^2 \wedge d\bar{z}^2 + dz^3 \wedge d\bar{z}^3) + \text{Re}(dz^1 \wedge dz^2 \wedge dz^3).$$

Thus, $G_2 \supset \{1\} \times SU(3)$. Similarly $G_2 \supset SU(3) \times \{1\}$. (Exercise.) As a result, $G_2 \cdot e_1 \supset S^6 \subset \mathbb{R}^7$. In fact, $G_2 \cdot e_1 = S^6$.

Moreover, the subgroup of G_2 that fixes e_1 is $\{1\} \times \text{SU}(3)$. This makes G_2 into a principal $\text{SU}(3)$ -bundle over S^6 :

$$\begin{array}{ccc} \text{SU}(3) & \rightarrow & G_2 \\ & & \downarrow \\ & & S^6 \end{array}$$

Thus G_2 is compact and of dimension 14. By the long exact seq. in homotopy, it is 2-connected and $\pi_3(G_2) = \pi_3(\text{SU}(3)) = \mathbb{Z}$, so it is simple. It is the first of the five exceptional compact simple Lie groups, realized here as a subgroup of $\text{SO}(7)$.

Define

$$\Lambda_+^3(\mathbb{R}^7)^* = \{A^* \phi_0 \mid A \in \text{GL}(7, \mathbb{R})\} \simeq \text{GL}(7, \mathbb{R}) / G_2.$$

This orbit has dimension $49 - 14 = 35 = \dim \Lambda^3(\mathbb{R}^7)^*$, so it's an open subset of this vector space. More generally, if V is a vector space of dimension 7, define the *positive 3-forms* on V as

$$\Lambda_+^3(V^*) = \{A^* \phi_0 \mid A : V \rightarrow \mathbb{R}^7 \text{ is an isomorphism}\}.$$

Because G_2 lies in $SO(7)$, to each positive form $\phi = A^*\phi_0$ on V there are a well-defined inner product and orientation on V defined by

$$g_\phi = A^*g_0, \quad *_\phi 1 = A^*(dx^1 \wedge \cdots \wedge dx^7).$$

Given a 7-dimensional vector space V , a G_2 -*structure* on V is a positive 3-form ϕ on V . The inner product g_ϕ and orientation $*_\phi 1 \in \Lambda^7(V^*)$ are said to be *associated* to ϕ .

It is not difficult to prove that ϕ_0 and its dual 4-form $*_{\phi_0}\phi_0$ generate the ring of G_2 -invariant forms on \mathbb{R}^7 . Harvey and Lawson proved that they are calibrations (more on this below).

Historical Remark: This was not the original definition of G_2 , nor the most common. Nowadays, G_2 is most commonly defined as the group of automorphisms of the *octonions* \mathbb{O} , the unique normed division algebra of dimension 8 (Cartan, 1908). The definition given here is due to Schouten (ca. 1928), and is, in a certain sense, optimal.

The comass of ϕ_0 . We can use the fact that G_2 stabilizes ϕ_0 to prove that it is a calibration and to compute $G(\phi_0)$:

Use the fact that G_2 acts transitively on S^6 with stabilizer of e_1 equal to $\{1\} \times \mathrm{SU}(3)$ to see that, for any triple of orthonormal vectors (v_1, v_2, v_3) in \mathbb{R}^7 , there is an element $A \in G_2$ and a constant θ such that

$$A(v_1) = e_1, \quad A(v_2) = e_2, \quad A(v_3) = \cos \theta e_3 + \sin \theta e_4.$$

Then

$$\phi_0(v_1, v_2, v_3) = \phi_0(e_1, e_2, \cos \theta e_3 + \sin \theta e_4) = \cos \theta \leq 1.$$

Moreover, $v_1 \wedge v_2 \wedge v_3 \in \mathrm{Gr}_3^+(\mathbb{R}^7)$ is ϕ_0 -calibrated if and only if it is equivalent to $e_1 \wedge e_2 \wedge e_3$ via G_2 . Thus,

$$G(\phi_0) = G_2 \cdot (e_1 \wedge e_2 \wedge e_3) = G_2 / \mathrm{SO}(4).$$

These calibrated 3-planes were dubbed *associative* by Harvey and Lawson because, regarding \mathbb{R}^7 as $\mathrm{Im} \mathbb{O}$, these planes generate associative subalgebras of \mathbb{O} .

Harvey and Lawson also showed that every 2-plane $E \subset \mathbb{R}^7$ lies in a unique associative 3-plane $E^+ \in \mathbf{G}(\phi_0)$.

In fact, they prove that every real analytic surface $S \subset \mathbb{R}^7$ lies in a unique analytically irreducible ϕ_0 -calibrated 3-fold $\Sigma \subset \mathbb{R}^7$.

Thus, there are lots of ‘associative’ 3-manifolds in \mathbb{R}^7 . These have become the focus of intense interest by \mathcal{M} -theorists as of late.

Of course, the Hodge dual 4-form $*_0\phi_0$ is also a calibration, calibrating the oriented orthogonals to the associative 3-planes:

$$\mathbf{G}(*_0\phi_0) = \mathbf{G}_2 \cdot (e_4 \wedge e_5 \wedge e_6 \wedge e_7) = \mathbf{G}_2 / \mathrm{SO}(4).$$

It follows that ϕ_0 vanishes on any ‘coassociative’ 4-plane in \mathbb{R}^7 . In fact, Harvey and Lawson show that a 3-plane $E \in \mathrm{Gr}_3(\mathbb{R}^7)$ lies in a coassociative 4-plane if and only iff ϕ_0 vanishes on E .

Correspondingly, they show that any real analytic 3-fold $S \subset \mathbb{R}^7$ to which ϕ_0 pulls back to zero lies in a unique analytically irreducible $*_0\phi_0$ -calibrated 4-fold $\Sigma \subset \mathbb{R}^7$.

Manifolds. Let M^7 be a 7-manifold. A G_2 -structure on M is a 3-form ϕ on M such that ϕ_x is a positive 3-form on $T_x M$ for all $x \in M$. Such a ϕ exists on M iff M is orientable and spinnable.

A G_2 -structure ϕ on M defines an associated Riemannian metric g_ϕ and an orientation (i.e., volume form) $*_\phi 1 \in \Omega^7(M)$.

If (M^7, g) is a Riemannian manifold with holonomy conjugate to a subgroup of G_2 , then M supports a g -parallel 3-form ϕ that is positive and so defines a G_2 -structure on M . Of course, this 3-form is both closed and co-closed.

Conversely, if M supports a g -parallel positive 3-form, then the holonomy of g is conjugate to a subgroup of G_2 .

Theorem: (Fernandez–Gray) Let M be a 7-manifold and let ϕ be a G_2 -structure on M , with associated metric g_ϕ and orientation $*_\phi 1$. If ϕ is closed and co-closed (with respect to g_ϕ and $*_\phi 1$), then ϕ is g_ϕ -parallel. (In particular, g_ϕ has holonomy conjugate to a subgroup of G_2 .)

Calibrations. If $\phi \in \Omega_+^3(M^7)$ is a closed G_2 -structure, then it is a calibration for M endowed with its associated metric g_ϕ . This defines a distinguished family of minimizing submanifolds of (M, g_ϕ) .

In the case that ϕ is closed and real analytic in local coordinates, Harvey and Lawson's arguments for (\mathbb{R}^7, ϕ_0) generalize to (M^7, ϕ) , showing that every real analytic surface $S \subset M^7$ lies in a unique analytically irreducible ϕ -calibrated 3-fold $\Sigma \subset M^7$.

Similarly, if $\phi \in \Omega_+^3(M^7)$ satisfies $d\phi = d(*_\phi\phi) = 0$, then $*_\phi\phi$ is a calibration on (M, g_ϕ) .

Again, Harvey and Lawson's arguments generalize in this case without change to show that any real analytic 3-fold $S \subset M^7$ to which ϕ pulls back to zero lies in a unique analytically irreducible $*_\phi\phi$ -calibrated 4-fold $\Sigma \subset M^7$.

Local Existence. Now, we are ‘reduced’ to studying the equations

$$d\phi = d(*_{\phi}\phi) = 0$$

for positive 3-forms $\phi \in \Omega_+^3(M)$. *A priori*, this is $35 + 21 = 56$ equations for the 35 unknown coefficients of the 3-form ϕ , but, in fact, these equations overlap by 7, so it’s only 49 (quasi-linear, first order) partial differential equations.

These equations aren’t elliptic because they are invariant under the diffeomorphism group.

Remember (from the table), that $K(\mathfrak{g}_2) \simeq \mathbb{R}^{77}$ and is irreducible as a G_2 -module. It follows that if ϕ solves these equations, then g_{ϕ} is Ricci-flat (Bonan) and hence real analytic in g_{ϕ} -harmonic coordinates (DeTurck-Kazdan). In particular, ϕ will also be real analytic in g_{ϕ} -harmonic coordinates.

This suggests the augmented (coordinate-dependent) system

$$d\phi = d(*_{\phi}\phi) = d(*_{\phi}dx^i) = 0$$

for $\phi \in \Omega_+^3(\mathbb{R}^7)$. This system is (overdetermined and) elliptic.

I can now state the ‘local generality’ analogs for G_2 of the results that we found for the various complex cases:

Theorem: (B—) The system $d\phi = d(*_\phi\phi) = 0$ for $\phi \in \Omega_+^3(M)$ is involutive. Modulo diffeomorphism, the general solution depends on six arbitrary functions of 6 variables.

Moreover, for the ‘generic’ solution ϕ , the values of the curvature form at a ‘generic’ point generate the entire holonomy algebra \mathfrak{g}_2 . Thus, for the ‘generic’ solution, the holonomy of g_ϕ is all of G_2 .

It is useful to have a test for reduced holonomy in the G_2 case:

Proposition: If M^7 is simply connected g is a metric on M that has holonomy a subgroup of G_2 , then the holonomy is a proper subgroup of G_2 iff M supports a nonzero g -parallel 1-form.

Proof: By Berger’s classification and the de Rham splitting theorem, the only connected proper subgroups of G_2 that can be holonomy groups in dimension 7 are $\mathbf{1}_1 \times \mathrm{SU}(3)$, $\mathbf{1}_3 \times \mathrm{SU}(2)$, and $\mathbf{1}_7$.

Explicit examples: Once we knew they were there, finding explicit examples wasn't so hard:

A conical example: The first known example was the cone metric on the flag manifold $SU(3)/T^2$, endowed with its natural metric. In fact, write the left-invariant form on $SU(3)$ in the form

$$g^{-1} dg = \begin{pmatrix} -i\theta_3 & -\bar{\omega}_1 & i\omega_2 \\ \omega_1 & -i\theta_2 & -\bar{\omega}_3 \\ i\bar{\omega}_2 & \omega_3 & -i\theta_1 \end{pmatrix}$$

Then the quadratic form $d\sigma^2 = \omega_1 \circ \bar{\omega}_1 + \omega_2 \circ \bar{\omega}_2 + \omega_3 \circ \bar{\omega}_3$ defines a Riemannian metric on $SU(3)/T^2$, where T^2 is the maximal torus in $SU(3)$ consisting of diagonal matrices. Setting

$$\Omega = \frac{i}{2} (\omega_1 \wedge \bar{\omega}_1 + \omega_2 \wedge \bar{\omega}_2 + \omega_3 \wedge \bar{\omega}_3), \quad \Psi = \omega_1 \wedge \omega_2 \wedge \omega_3,$$

these two forms also drop to $SU(3)/T^2$ and satisfy

$$d\Omega = 3 \operatorname{Re}(\Psi), \quad d\Psi = -2i\Omega^2.$$

Now, on $M = (0, \infty) \times \text{SU}(3)/T^2$, consider the (obviously closed) 3-form

$$\phi = \frac{1}{3} d(t^3 \Omega) = t^2 dt \wedge \Omega + t^3 \text{Re}(\Psi).$$

This is a positive 3-form. One computes that its associated metric is the ‘cone’ metric

$$g_\phi = dt^2 + t^2 d\sigma^2.$$

Moreover, the g_ϕ -dual of ϕ is found to be

$$*_\phi \phi = -\frac{1}{4} d(t^4 \text{Im}(\Psi))$$

and this is obviously closed as well. Thus, the holonomy of g_ϕ is conjugate to a subgroup of G_2 .

One can now compute that there are no g_ϕ -parallel 1-forms, so the holonomy must be all of G_2 .

Later, Bryant and Salamon constructed complete G_2 -holonomy metrics on $\Lambda_+^2(\mathbb{C}\mathbb{P}^2)$ and on $S^3 \times \mathbb{R}^4$.

These G_2 -metrics have cohomogeneity 1 and Gukov, *et al* and Page, *et al* have now constructed many more examples of such.

Compact examples? On the other hand, a compact example cannot have any continuous symmetries (because it's Ricci-flat), so it's truly a 7-dimensional problem.

Here are a few of the known easy necessary conditions if a compact M is to support a metric g with holonomy G_2 :

- (1) M must be orientable and spinnable.
- (2) $b_1(M) = 0$. (Ricci flat \Rightarrow harmonic 1-forms parallel.)
- (3) $\pi_1(M)$ must be finite. (Cheeger-Gromoll)
- (4) $b_3(M) = b_4(M) > 0$. ($\phi, *_{\phi}\phi$ are parallel forms)
- (5) $p_1(M) \neq 0$. ($\int_M \phi \wedge p_1 = c \int_M \|R\|^2 * 1$, where $c \neq 0$.)
- (6) M cannot be a nontrivial product. (Donaldson)

There is also a relatively easy 'Torelli theorem':

Theorem: Suppose that (M^7, g) is a compact Riemannian manifold with holonomy G_2 . Then the marked moduli space of G_2 -holonomy metrics near g modulo the diffeomorphisms of M near the identity is a smooth manifold near g whose tangent space is canonically isomorphic to $H_{dR}^3(M, \mathbb{R})$.

In the early 1990's Dominic Joyce produced the first examples of compact Riemannian manifolds with holonomy G_2 . There were two aspects to his methods:

Analytic: Joyce proved that, if one has a compact M^7 that supports a *closed* positive 3-form ϕ with the property that its associated metric g_ϕ satisfies a combination of

- (1) a upper bound on its curvature and volume,
- (2) a lower bound on its injectivity radius, and
- (3) a upper bound on the size of $\|d * \phi\|$,

then one can perturb ϕ by adding a small exact 3-form so as to get a new $\hat{\phi}$ that is positive, closed, and co-closed with respect to its associated metric.

Geometric: Joyce constructed examples of (M^7, ϕ) that satisfy the above hypotheses by starting with a flat metric on the 7-torus $T^7 = \mathbb{R}^7 / \mathbb{Z}^7$, dividing by a discrete group to get a manifold with singularities, resolving those singularities to get the manifold M^7 and a ϕ on M^7 satisfying the above conditions.

Finally, we are ready to consider the last case, which only occurs in dimension 8.

n	$\mathfrak{h} \subseteq \mathfrak{so}(n)$	$K(\mathfrak{h})$ as an \mathfrak{h} -module
n	$\mathfrak{so}(n)$	$\mathbb{R} \oplus S_0^2(\mathbb{R}^n) \oplus W_n(\mathbb{R}^n)$
$n = 2m > 2$	$\mathfrak{u}(m)$	$\mathbb{R} \oplus S_0^{1,1}(\mathbb{C}^m)^{\mathbb{R}} \oplus S_0^{2,2}(\mathbb{C}^m)^{\mathbb{R}}$
$n = 2m > 2$	$\mathfrak{su}(m)$	$S_0^{2,2}(\mathbb{C}^m)^{\mathbb{R}}$
$n = 4m > 4$	$\mathfrak{sp}(m) \oplus \mathfrak{sp}(1)$	$\mathbb{R} \oplus S^4(\mathbb{C}^{2m})^{\mathbb{R}}$
$n = 4m > 4$	$\mathfrak{sp}(m)$	$S^4(\mathbb{C}^{2m})^{\mathbb{R}}$
$n = 7$	\mathfrak{g}_2	$V^{0,2} \simeq \mathbb{R}^{77}$
$n = 8$	$\mathfrak{spin}(7)$	$V^{0,2,0} \simeq \mathbb{R}^{168}$

6. The exceptional holonomy Spin(7). As usual, we begin with linear algebra. Let $\mathbb{R}^8 = \mathbb{R} \cdot e_0 \oplus \mathbb{R}^7$ and consider the 4-form

$$\Phi_0 = dx^0 \wedge \phi_0 + * \phi_0.$$

Now ‘define’

$$\text{Spin}(7) = \{ A \in \text{GL}(8, \mathbb{R}) \mid A^* \Phi_0 = \Phi_0 \}.$$

The definition and previous discussion $\Rightarrow \text{Spin}(7) \supset \{1\} \times G_2$.
Moreover, if we identify \mathbb{R}^8 with \mathbb{C}^4 by setting

$$z^0 = x^0 + i x^1, \quad z^1 = x^2 + i x^3, \quad z^2 = x^4 + i x^5, \quad z^3 = x^6 + i x^7,$$

then you can check that

$$\begin{aligned} \Phi_0 = & \frac{1}{2} \left(\frac{i}{2} (dz^0 \wedge d\bar{z}^0 + dz^1 \wedge d\bar{z}^1 + dz^2 \wedge d\bar{z}^2 + dz^3 \wedge d\bar{z}^3) \right)^2 \\ & + \text{Re}(dz^0 \wedge dz^1 \wedge dz^2 \wedge dz^3), \end{aligned}$$

so $\text{Spin}(7) \supset \text{SU}(4)$. Finally, can show that $\text{Spin}(7) \subset \text{SO}(8)$ and that the subgroup of $\text{Spin}(7)$ that fixes e_0 is exactly $\{1\} \times G_2$.

This makes $\text{Spin}(7)$ into a principal G_2 -bundle over S^7 :

$$\begin{array}{ccc} G_2 & \rightarrow & \text{Spin}(7) \\ & & \downarrow \\ & & S^7 \end{array}$$

Thus $\text{Spin}(7)$ is compact and of dimension 21. By the long exact seq. in homotopy, it is 2-connected and $\pi_3(\text{Spin}(7)) = \pi_3(G_2) = \mathbb{Z}$, so it is simple. By the classification, there are only two possibilities: $\text{Spin}(7)$ is $\text{Sp}(3)$ or the universal cover of $\text{SO}(7)$. The former has no 8-dimensional irreducible representation, so $\text{Spin}(7)$ must be the universal cover of $\text{SO}(7)$. Define

$$\Lambda_+^4(\mathbb{R}^8)^* = \{ A^* \Phi_0 \mid A \in \text{GL}(7, \mathbb{R}) \} \simeq \text{GL}(8, \mathbb{R}) / \text{Spin}(7).$$

This orbit has dimension $64 - 21 = 43 < \dim \Lambda_+^4(\mathbb{R}^8)^*$, so it's *not* an open subset of this vector space. More generally, if V is a vector space of dimension 8, define the *Cayley forms* on V to be

$$\Lambda_+^4(V^*) = \{ A^* \Phi_0 \mid A : V \rightarrow \mathbb{R}^8 \text{ is an isomorphism} \}.$$

Because $\text{Spin}(7)$ lies in $\text{SO}(8)$, to each Cayley form $\Phi = A^*\Phi_0$ on V there are a well-defined inner product and orientation on V defined by

$$g_\Phi = A^*g_0, \quad *_\Phi 1 = A^*(dx^0 \wedge \cdots \wedge dx^7).$$

Given an 8-dimensional vector space V , a $\text{Spin}(7)$ -*structure* on V is a Cayley form $\Phi \in \Lambda_+^4(V^*)$. The inner product g_Φ and orientation $*_\Phi 1 \in \Lambda^8(V^*)$ are said to be *associated* to Φ .

It is not difficult to prove that $\Phi_0 = *_{\Phi_0}\Phi_0$ generates the ring of $\text{Spin}(7)$ -invariant forms on \mathbb{R}^8 . Harvey and Lawson proved that it is a calibration (more on this below).

Historical Remark: This is a very idiosyncratic definition of $\text{Spin}(7)$. Usually, $\text{Spin}(7)$ is defined abstractly as the universal cover of $\text{SO}(7)$. Its embedding into $\text{SO}(8)$ is derived via Clifford constructions or by using the octonions, e.g., $\text{Spin}(7)$ is the subgroup of the rotations in \mathbb{O} that is generated by right multiplications by unit imaginary octonions.

Manifolds. Let M^8 be an 8-manifold. A $\text{Spin}(7)$ -structure on M is a 4-form Φ on M such that Φ_x is a Cayley form on $T_x M$ for all $x \in M$.

A $\text{Spin}(7)$ -structure on M defines an associated Riemannian metric g_Φ and orientation (i.e., volume form) $*_\Phi 1 \in \Omega^8(M)$ with respect to which Φ is self-dual, i.e., $*_\Phi \Phi = \Phi$.

If (M^8, g) is a Riemannian manifold with holonomy conjugate to a subgroup of $\text{Spin}(7)$, then M supports a g -parallel Cayley form Φ and this defines a $\text{Spin}(7)$ -structure on M . This 4-form is closed (and co-closed, of course).

Conversely, if M supports a g -parallel Cayley form, then the holonomy of g is conjugate to a subgroup of $\text{Spin}(7)$.

Theorem: (Fernandez–Gray) Let M be a 8-manifold and let Φ be a $\text{Spin}(7)$ -structure on M , with associated metric g_Φ and orientation $*_\Phi 1$. If Φ is closed, then Φ is g_Φ -parallel. (In particular, g_Φ has holonomy conjugate to a subgroup of $\text{Spin}(7)$.)

Thus, we are ‘reduced’ to studying the equations

$$d\Phi = 0$$

for Cayley forms $\Phi \in \Omega_+^4(M)$. This is 56 (quasi-linear, first order) partial differential equations for the 43 unknown coefficients of the form Φ .

These equations aren’t elliptic because they are invariant under the diffeomorphism group.

Remember (from the table), that $K(\mathfrak{spin}(7)) \simeq \mathbb{R}^{168}$ and is irreducible as a $\text{Spin}(7)$ -module. It follows that if Φ solves these equations, then g_Φ is Ricci-flat (Bonan) and hence real analytic in g_Φ -harmonic coordinates (DeTurck-Kazdan). In particular, Φ will also be real analytic in g_Φ -harmonic coordinates.

This suggests the augmented (coordinate-dependent) system

$$d\Phi = d(*_\Phi dx^i) = 0$$

for $\Phi \in \Omega_+^4(\mathbb{R}^8)$. This system of $56 + 8 = 64$ equations is (over-determined and) elliptic.

I can now state the ‘local generality’ analogs for Spin(7):

Theorem: (B—) The system $d\Phi = 0$ for $\Phi \in \Omega_+^4(M)$ is involutive and, modulo diffeomorphism, the general solution depends on twelve arbitrary functions of 7 variables.

Moreover, for the ‘generic’ solution Φ , the values of the curvature form at a ‘generic’ point generate the entire holonomy algebra $\mathfrak{spin}(7)$. Thus, for the ‘generic’ solution, the holonomy of g_Φ is all of Spin(7).

Proposition: If M^8 is simply connected and g is a metric on M that has holonomy a subgroup of Spin(7), then the holonomy is a proper subgroup of Spin(7) iff M supports a nonzero g -parallel 1-form or 2-form.

Proof: By Berger’s classification and the de Rham splitting theorem, the only connected proper subgroups of Spin(7) that can be holonomy groups in dimension 7 are subgroups of either $\mathbf{1}_1 \times \mathbf{G}_2$ or SU(4).

Explicit examples: Again, constructing cohomogeneity 1 examples isn't hard:

A conical example: The first known example was the cone metric on the homogeneous space $Y^7 = \mathrm{SO}(5)/H_5$, where $H_5 \subset \mathrm{SO}(5)$ is a subgroup isomorphic to $\mathrm{SO}(3)$ and acting irreducibly on \mathbb{R}^5 . Up to constant multiples, there is a unique $\mathrm{SO}(5)$ -invariant metric on Y^7 .

I won't give the full details, but the basic point is that Y^7 is a rational homology 7-sphere that has a unique (up to constant multiples) $\mathrm{SO}(5)$ invariant 3-form ϕ . (This follows from the representation theory of $\mathrm{SO}(3)$.)

Now, this form ϕ is actually a positive 3-form, so it defines a G_2 -structure on Y , with associated metric g_ϕ and orientation $*_\phi 1$.

Now, it is not difficult to show that $d\phi = \lambda *_\phi \phi$ for some constant $\lambda \neq 0$. By scaling ϕ , we can assume that

$$d\phi = 4 *_\phi \phi.$$

Now, on $M^8 = (0, \infty) \times Y^7$, consider the (obviously closed) 4-form

$$\Phi = \frac{1}{4} d(t^4 \phi) = t^3 dt \wedge \phi + t^4 *_{\phi} \phi.$$

This is clearly a Cayley form. One computes that its associated metric is the ‘cone’ metric

$$g_{\Phi} = dt^2 + t^2 g_{\phi}.$$

Thus, the holonomy of g_{Φ} is conjugate to a subgroup of $\text{Spin}(7)$.

One can now compute that there are no g_{Φ} -parallel 1-forms or 2-forms so the holonomy must be all of $\text{Spin}(7)$.

Later, Bryant and Salamon constructed a complete $\text{Spin}(7)$ -holonomy metric on $\mathbb{S}_+(S^4)$, the semi-spinor bundle over S^4 .

These $\text{Spin}(7)$ -metrics have cohomogeneity 1 and Gukov, *et al* and Page, *et al* have now constructed many more examples of such.

Compact examples? On the other hand, a compact example cannot have any continuous symmetries (because it's Ricci-flat), so it's truly an 8-dimensional problem.

Here are a few of the known easy necessary conditions if a compact M^8 is to support a metric g with holonomy $\text{Spin}(7)$:

- (1) M must be orientable and spinnable.
- (2) The Euler class of a spinor bundle of M must be zero.
- (3) The \hat{A} -genus of M must be 1.
- (4) $b_1(M) = 0$. (Ricci flat \Rightarrow harmonic 1-forms parallel.)
- (5) $\pi_1(M)$ must be finite. (Cheeger-Gromoll)
- (6) $b_4(M) > 0$. (Φ is g -parallel)
- (7) $p_1(M) \neq 0$. ($\int_M \Phi \wedge p_1 = c \int_M \|R\|^2 * 1$, where $c \neq 0$.)

Theorem: Suppose that (M^8, g) is a compact Riemannian manifold with holonomy $\text{Spin}(7)$. Then the marked moduli space of $\text{Spin}(7)$ -holonomy metrics near g modulo the diffeomorphism of M near the identity is a smooth manifold near g whose tangent space is canonically isomorphic to $H_+^4(M, \mathbb{R})$.

It may seem that $\text{Spin}(7)$ metrics are hopelessly hard to come by. However, here's a sample of the kind of minimal conditions that can produce such a metric:

Proposition: Let M^8 be a compact oriented spin manifold with $\hat{A}(M) = 1$. Suppose that g is a metric on M with $\text{Scal}(g) \geq 0$. Then $\text{Scal}(g) \equiv 0$ and the holonomy of g is $\text{Spin}(7)$.

In the early 1990's Dominic Joyce produced the first examples of compact Riemannian manifolds with holonomy $\text{Spin}(7)$. Again, there were two aspects to his methods, an analytic aspect and a geometric aspect.

It would take me too long to describe these here, so I'll just refer you to his beautiful book, "Compact manifolds with special holonomy" for further details.