

Abelian categories and stability conditions

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1. The basic idea

Let \mathcal{A} be an abelian category. We will define *configurations* (σ, ι, π) in \mathcal{A} , collections of objects and morphisms in \mathcal{A} attached to a *finite poset* (I, \preceq) , satisfying axioms. They are a new tool for describing *how an object in \mathcal{A} breaks up into subobjects*. They are useful for studying *stability conditions* on \mathcal{A} .

Let $Z : K(\mathcal{A}) \rightarrow \mathbb{C}$ be a *slope function* with *phase* θ . Under conditions on \mathcal{A}, Z we can define *moduli spaces* $\mathcal{M}_{\text{ss}}, \mathcal{M}_{\text{st}}(I, \preceq, \kappa, \theta)$ of (I, \preceq) -configurations (σ, ι, π) with $\sigma(\{i\})$ θ -*(semi)stable*, $i \in I$. Let $I_{\text{ss}}, I_{\text{st}}(I, \preceq, \kappa, \theta)$ be their *Euler characteristics*. They are a system of invariants of \mathcal{A}, Z . We prove *identities* for them, and *transformation laws* to change from Z to \tilde{Z} .

2. Abelian categories

A category \mathcal{A} has *objects* X, Y in \mathcal{A} or $\text{Obj}(\mathcal{A})$, *morphisms* f in $\text{Mor}(\mathcal{A})$, or $f : X \rightarrow Y$. Write $\text{Hom}(X, Y) = \{f : X \rightarrow Y\}$.

\mathcal{A} is an *abelian category* if

- $\text{Hom}(X, Y)$ is an *abelian group* for $X, Y \in \mathcal{A}$, and composition is *biadditive*.
- there is a *zero object* $0 \in \mathcal{A}$.
- *direct sums* $X \oplus Y$ exist.
- *kernels* and *cokernels* exist.

Exact sequences make sense.

For \mathbb{K} a field, \mathcal{A} is \mathbb{K} -linear if $\text{Hom}(X, Y)$ is a \mathbb{K} -vector space, and composition is bilinear.

Examples

- category of *abelian groups*
- category of \mathbb{K} -vector spaces
- $\text{coh}(P)$, the category of *coherent sheaves* on a *projective variety* P over \mathbb{K} .
- $\text{mod-}A$, the category of representations of a *finite-dimensional algebra* A over \mathbb{K} .

Subobjects

Let $X \in \mathcal{A}$ and $i : S \rightarrow X$, $i' : S' \rightarrow X$ be injective. We call i, i' *equivalent* if there is an isomorphism $h : S \rightarrow S'$ with $i = i' \circ h$. A *subobject* $S \subset X$ is an equivalence class of $i : S \rightarrow X$. Examples:

- subgroups of abelian groups.
- subspaces of a vector space.
- vector subbundles (subsheaves) of a vector bundle (coherent sheaf).

Call \mathcal{A} *noetherian* (*artinian*) if ascending (descending) chains of subobjects must stabilize. Call \mathcal{A} *finite length* if it is noetherian and artinian. Call $0 \neq X \in \mathcal{A}$ *simple* if the only subobjects $S \subset X$ are $0, X$.

Jordan-Hölder Theorem.

For \mathcal{A} of finite length and X in \mathcal{A} , there exist subobjects $0 = A_0 \subset A_1 \subset \cdots \subset A_n = X$ with $S_k = A_k/A_{k-1}$ simple, and n, S_k unique up to order, iso.

Then we call S_1, \dots, S_n the *simple factors* of X , and $0 = A_0 \subset A_1 \subset \dots \subset A_n = X$ a *composition series* for X . Let S_1, \dots, S_n be *pairwise non-isomorphic*. Write $\{S_1, \dots, S_n\} = \{S^i : i \in I\}$, for I a finite *indexing set*, $|I| = n$. Then for each composition series $0 = B_0 \subset B_1 \subset \dots \subset B_n = X$ with $T_k = B_k/B_{k-1}$, there is a unique *bijection* $\phi : I \rightarrow \{1, \dots, n\}$ with $S^i \cong T_{\phi(i)}$, all $i \in I$.

Define a *partial order* \preceq on I by $i \preceq j$ if $\phi(i) \leq \phi(j)$ for all ϕ from composition series as above.

Call $J \subseteq I$ an *s-set* if $i \in I$, $j \in J$ and $i \preceq j \Rightarrow i \in J$.

Call $J \subseteq I$ an *f-set* if $i \in I$, $h, j \in J$ and $h \preceq i \preceq j \Rightarrow i \in J$.

The *finite poset* (I, \preceq) encodes all information on *subobjects* $S \subset X$, and their *inclusions* $S \subset T \subset X$, when X has non-isomorphic simple factors.

There are unique

1-1 correspondences:

- *subobjects* $S \subset X \leftrightarrow$ *s-sets* $J \subseteq I$, where S has simple factors S^j , $j \in J$. If $S, T \leftrightarrow J, K$ then $S \subset T \Leftrightarrow J \subseteq K$.

- *factors* $F = T/S$ for $S \subset T \subset X \leftrightarrow$ *f-sets* $J \subseteq I$, where F has simple factors S^j , $j \in J$.

- *composition series*

$0 = B_0 \subset B_1 \subset \dots \subset B_n = X$
 \leftrightarrow *bijections* $\phi : I \rightarrow \{1, \dots, n\}$
with $i \preceq j \Rightarrow \phi(i) \leq \phi(j)$.

Definition. Let (I, \preceq) be a finite poset. Write $\mathcal{F}_{(I, \preceq)}$ for the set of f-sets of I . Define $\mathcal{G}_{(I, \preceq)}$ to be the subset of $(J, K) \in \mathcal{F}_{(I, \preceq)} \times \mathcal{F}_{(I, \preceq)}$ such that $J \subseteq K$, and if $j \in J$ and $k \in K$ with $k \preceq j$, then $k \in J$. Define $\mathcal{H}_{(I, \preceq)} = \{(K, K \setminus J) : (J, K) \in \mathcal{G}_{(I, \preceq)}\}$.

Define an (I, \preceq) -*configuration* (σ, ι, π) in an abelian category \mathcal{A} to be maps $\sigma : \mathcal{F}_{(I, \preceq)} \rightarrow \text{Obj}(\mathcal{A})$, $\iota : \mathcal{G}_{(I, \preceq)} \rightarrow \text{Mor}(\mathcal{A})$, and $\pi : \mathcal{H}_{(I, \preceq)} \rightarrow \text{Mor}(\mathcal{A})$, where $\iota(J, K), \pi(J, K)$ are morphisms $\sigma(J) \rightarrow \sigma(K)$.

These should satisfy the conditions:

(A) Let $(J, K) \in \mathcal{G}_{(I, \preceq)}$ and set $L = K \setminus J$.

Then the following is exact in \mathcal{A} :

$$0 \longrightarrow \sigma(J) \xrightarrow{\iota(J, K)} \sigma(K) \xrightarrow{\pi(K, L)} \sigma(L) \longrightarrow 0.$$

(B) If $(J, K) \in \mathcal{G}_{(I, \preceq)}$ and $(K, L) \in \mathcal{G}_{(I, \preceq)}$ then $\iota(J, L) = \iota(K, L) \circ \iota(J, K)$.

(C) If $(J, K) \in \mathcal{H}_{(I, \preceq)}$ and $(K, L) \in \mathcal{H}_{(I, \preceq)}$ then $\pi(J, L) = \pi(K, L) \circ \pi(J, K)$.

(D) If $(J, K) \in \mathcal{G}_{(I, \preceq)}$ and $(K, L) \in \mathcal{H}_{(I, \preceq)}$ then

$$\pi(K, L) \circ \iota(J, K) = \iota(J \cap L, L) \circ \pi(J, J \cap L).$$

This encodes the properties of the set of subobjects $S \subset X$ when X has nonisomorphic simple factors.

Theorem 1. *Let \mathcal{A} have finite length, $X \in \mathcal{A}$ have nonisomorphic simple factors $\{S^i : i \in I\}$, and \preceq be as before. Then there exists an (I, \preceq) -configuration (σ, ι, π) with $\sigma(I) = X$, unique up to isomorphism, such that if a subobject $S \subset X$ has simple factors $\{S^j : j \in J\}$, then S is represented by $\iota(J, I) : \sigma(J) \rightarrow X$.*

I derived the idea of configuration for \mathcal{A} of *finite length* and X with *nonisomorphic simple factors*. But it is useful much more generally, as a tool for describing how objects decompose into subobjects.

For example, a *short exact sequence* $0 \rightarrow X \rightarrow Y \rightarrow Z \rightarrow 0$ is the same as a $(\{1, 2\}, \leq)$ -configuration (σ, ι, π) with $\sigma(\{1\}) = X$, $\sigma(\{1, 2\}) = Y$ and $\sigma(\{2\}) = Z$. Essentially this says that Y has a subobject X .

Quotient configurations

Let (I, \preceq) , (K, \trianglelefteq) be finite posets, and $\phi : I \rightarrow K$ surjective with $i \preceq j$ implies $\phi(i) \trianglelefteq \phi(j)$.

Let (σ, ι, π) be an (I, \preceq) -configuration.

Define a (K, \trianglelefteq) -configuration $(\tilde{\sigma}, \tilde{\iota}, \tilde{\pi})$ to

be $(\sigma \circ \phi^*, \iota \circ \phi^*, \pi \circ \phi^*)$, where $\phi^* : \mathcal{F}_{(K, \trianglelefteq)},$

$\mathcal{G}_{(K, \trianglelefteq)}, \mathcal{H}_{(K, \trianglelefteq)} \rightarrow \mathcal{F}_{(I, \preceq)}, \mathcal{G}_{(I, \preceq)}, \mathcal{H}_{(I, \preceq)}$ pulls

back subsets of K to subsets of I .

We call $(\tilde{\sigma}, \tilde{\iota}, \tilde{\pi})$ the *quotient* (K, \trianglelefteq) -*con-*
figuration of (σ, ι, π) . We call (σ, ι, π) a

refinement of $(\tilde{\sigma}, \tilde{\iota}, \tilde{\pi})$. If $I = K$ and $\phi = \text{id}_I$

we call (σ, ι, π) an *improvement* of $(\tilde{\sigma}, \tilde{\iota}, \tilde{\pi})$.

Improvements split short exact sequences.

We call $(\tilde{\sigma}, \tilde{\iota}, \tilde{\pi})$ *best* if it admits no strict improvements.

Slope stability

Let $K(\mathcal{A})$ be the Grothendieck group of \mathcal{A} . A *slope function* on \mathcal{A} is a homomorphism $Z : K(\mathcal{A}) \rightarrow \mathbb{C}$ with $Z([X]) \in \{r e^{i\pi\theta} : r > 0, \theta \in (0, 1]\}$ for all $0 \not\cong X \in \mathcal{A}$.

Define the *phase* $\theta([X]) \in (0, 1]$ by $Z([X]) = r e^{i\pi\theta([X])}$. Define X to be (i) *θ -stable* if $\theta([S]) < \theta([X])$ for all $S \subset X$ with $S \neq 0, X$.

(ii) *θ -semistable* if $\theta([S]) \leq \theta([X])$ for all $0 \neq S \subset X$.

(iii) *θ -unstable* otherwise.

A research programme

Let \mathbb{K} be an algebraically closed field of characteristic zero. Let \mathcal{A} be some interesting abelian category over \mathbb{K} . Let (I, \preceq) be a finite poset and $\kappa : I \rightarrow K(\mathcal{A})$ a map. Define a *moduli space*

$\mathcal{M}_{\text{all}}(I, \preceq, \kappa)$ to be the set of isomorphism classes of (I, \preceq) -configurations (σ, ι, π) with $[\sigma(\{i\})] = \kappa(i)$ in $K(\mathcal{A})$ for all $i \in I$.

Let Z be a slope function with phase θ .

Define *subspaces* $\mathcal{M}_{\text{st}}, \mathcal{M}_{\text{ss}}(I, \preceq, \kappa, \theta)$ of

$[(\sigma, \iota, \pi)]$ in $\mathcal{M}_{\text{all}}(I, \preceq, \kappa)$ with $\sigma(\{i\})$

θ -(semi)stable for all $i \in I$, and $\mathcal{M}_{\text{all}}^{\text{b}},$

$\mathcal{M}_{\text{st}}^{\text{b}}, \mathcal{M}_{\text{ss}}^{\text{b}}(\dots)$ with (σ, ι, π) *best*.

We call (I, \preceq, κ) *A-data*. For the examples I am interested in, $\mathcal{M}_{\text{all}}(I, \preceq, \kappa)$ is an *Artin stack*, and $\mathcal{M}_{\text{st}}, \mathcal{M}_{\text{ss}}, \mathcal{M}_{\text{all}}^{\text{b}}, \mathcal{M}_{\text{st}}^{\text{b}}, \mathcal{M}_{\text{ss}}^{\text{b}}(\dots)$ are *constructible subsets* (finite unions of substacks of finite type over \mathbb{K}), with well-defined *Euler characteristics*. Quotient configurations induce *morphisms* $\mathcal{M}_{\text{all}}(I, \preceq, \kappa) \rightarrow \mathcal{M}_{\text{all}}(K, \trianglelefteq, \mu)$. Define $I_{\text{st}}, I_{\text{ss}}, I_{\text{st}}^{\text{b}}, I_{\text{ss}}^{\text{b}}(I, \preceq, \kappa, \theta)$ to be the *Euler characteristics* of $\mathcal{M}_{\text{st}}, \mathcal{M}_{\text{ss}}, \mathcal{M}_{\text{st}}^{\text{b}}, \mathcal{M}_{\text{ss}}^{\text{b}}(I, \preceq, \kappa, \theta)$.

Universal identities between the invariants

Let \trianglelefteq, \preceq be partial orders on I . We say that \trianglelefteq *dominates* \preceq if $i \preceq j$ implies $i \trianglelefteq j$. Here is how to transform between *best* and *non-best* invariants.

Theorem 2. *Let \mathcal{A} satisfy some assumptions, and Z be a permissible slope function on \mathcal{A} with phase θ . Then for all \mathcal{A} -data $(I, \trianglelefteq, \kappa)$ we have*

$$\sum_{\substack{\text{p.o.s } \preceq \text{ on } I: \\ \trianglelefteq \text{ dominates } \preceq}} I_{\text{st}}^{\text{b}}(I, \preceq, \kappa, \theta) = I_{\text{st}}(I, \trianglelefteq, \kappa, \theta),$$

$$\sum_{\substack{\text{p.o.s } \preceq \text{ on } I: \\ \trianglelefteq \text{ dominates } \preceq}} I_{\text{ss}}^{\text{b}}(I, \preceq, \kappa, \theta) = I_{\text{ss}}(I, \trianglelefteq, \kappa, \theta),$$

$$\sum_{\substack{\text{p.o.s } \preceq \text{ on } I: \\ \trianglelefteq \text{ dominates } \preceq}} n(I, \preceq, \trianglelefteq) I_{\text{st}}(I, \preceq, \kappa, \theta) = I_{\text{st}}^{\text{b}}(I, \trianglelefteq, \kappa, \theta),$$

$$\sum_{\substack{\text{p.o.s } \preceq \text{ on } I: \\ \trianglelefteq \text{ dominates } \preceq}} n(I, \preceq, \trianglelefteq) I_{\text{ss}}(I, \preceq, \kappa, \theta) = I_{\text{ss}}^{\text{b}}(I, \trianglelefteq, \kappa, \theta).$$

Here $n(I, \preceq, \trianglelefteq)$ are explicitly defined constants. The proof of these uses $\chi(\mathbb{K}^l) = 1$.

Theorem 3. *Let \mathcal{A} satisfy some assumptions, and Z be a permissible slope function on \mathcal{A} with phase θ . Then for all \mathcal{A} -data $(K, \trianglelefteq, \mu)$ we have*

$$\sum_{\substack{\text{iso.} \\ \text{classes} \\ \text{of finite} \\ \text{sets } I}} \frac{1}{|I|!} \cdot \sum_{\substack{\preceq, \kappa, \phi: (I, \preceq, \kappa) \text{ is } \mathcal{A}\text{-data,} \\ \phi: I \rightarrow K \text{ is surjective,} \\ i \preceq j \text{ implies } \phi(i) \trianglelefteq \phi(j), \\ \kappa(\phi^{-1}(k)) = \mu(k) \text{ for } k \in K, \\ \theta \circ \mu \circ \phi \equiv \theta \circ \kappa: I \rightarrow (0, 1]}} I_{\text{st}}^{\text{b}}(I, \preceq, \kappa, \theta) = I_{\text{ss}}(K, \trianglelefteq, \mu, \theta),$$

$$\sum_{\substack{\text{iso.} \\ \text{classes} \\ \text{of finite} \\ \text{sets } I}} \frac{1}{|I|!} \cdot \sum_{\substack{\preceq, \kappa, \phi: (I, \preceq, \kappa) \text{ is } \mathcal{A}\text{-data,} \\ (I, \preceq, K, \phi) \text{ is allowable,} \\ \trianglelefteq = \mathcal{P}(I, \preceq, K, \phi), \\ \kappa(\phi^{-1}(k)) = \mu(k) \text{ for } k \in K, \\ \theta \circ \mu \circ \phi \equiv \theta \circ \kappa: I \rightarrow (0, 1]}} I_{\text{st}}^{\text{b}}(I, \preceq, \kappa, \theta) = I_{\text{ss}}^{\text{b}}(K, \trianglelefteq, \mu, \theta),$$

$$\sum_{\substack{\text{iso.} \\ \text{classes} \\ \text{of finite} \\ \text{sets } I}} \frac{1}{|I|!} \cdot \sum_{\substack{\preceq, \kappa, \phi: (I, \preceq, \kappa) \text{ is } \mathcal{A}\text{-data,} \\ (I, \preceq, K, \phi) \text{ is allowable,} \\ \trianglelefteq = \mathcal{P}(I, \preceq, K, \phi), \\ \kappa(\phi^{-1}(k)) = \mu(k) \text{ for } k \in K, \\ \theta \circ \mu \circ \phi \equiv \theta \circ \kappa: I \rightarrow (0, 1]}} N(I, \preceq, K, \phi) \cdot I_{\text{ss}}^{\text{b}}(I, \preceq, \kappa, \theta) = I_{\text{st}}^{\text{b}}(K, \trianglelefteq, \mu, \theta).$$

Here $N(I, \preceq, K, \phi)$ are explicitly defined constants. Theorems 2 and 3 mean that each of the four families $I_{\text{st}}, I_{\text{ss}}, I_{\text{st}}^{\text{b}}, I_{\text{ss}}^{\text{b}}(\dots)$ determines the other three.

Here are the *transformation laws* between the invariants for two different slope functions.

Theorem 4. *Let \mathcal{A} satisfy some assumptions, and Z, \tilde{Z} be permissible slope functions on \mathcal{A} with phases $\theta, \tilde{\theta}$. Then for all \mathcal{A} -data $(K, \trianglelefteq, \mu)$ we have*

$$\sum_{\substack{\text{iso.} \\ \text{classes} \\ \text{of finite} \\ \text{sets } I}} \frac{1}{|I|!} \cdot \sum_{\substack{\preceq, \kappa, \phi: (I, \preceq, \kappa) \text{ is } \mathcal{A}\text{-data, } I_{\text{st}}^{\text{b}}(I, \preceq, \kappa, \theta) = \\ (I, \preceq, K, \phi) \text{ is allowable, } \\ \trianglelefteq = \mathcal{P}(I, \preceq, K, \phi), \\ \kappa(\phi^{-1}(k)) = \mu(k) \text{ for } k \in K}} T_{\text{st}}^{\text{b}}(I, \preceq, \kappa, K, \phi, \theta, \tilde{\theta}) \cdot I_{\text{st}}^{\text{b}}(K, \trianglelefteq, \mu, \tilde{\theta}),$$

$$\sum_{\substack{\text{iso.} \\ \text{classes} \\ \text{of finite} \\ \text{sets } I}} \frac{1}{|I|!} \cdot \sum_{\substack{\preceq, \kappa, \phi: (I, \preceq, \kappa) \text{ is } \mathcal{A}\text{-data, } I_{\text{ss}}^{\text{b}}(I, \preceq, \kappa, \theta) = \\ (I, \preceq, K, \phi) \text{ is allowable, } \\ \trianglelefteq = \mathcal{P}(I, \preceq, K, \phi), \\ \kappa(\phi^{-1}(k)) = \mu(k) \text{ for } k \in K}} T_{\text{ss}}^{\text{b}}(I, \preceq, \kappa, K, \phi, \theta, \tilde{\theta}) \cdot I_{\text{ss}}^{\text{b}}(K, \trianglelefteq, \mu, \tilde{\theta}).$$

There are only finitely many terms in each sum with $T_{\text{st}}^{\text{b}}, T_{\text{ss}}^{\text{b}}(\dots)$ and $I_{\text{st}}^{\text{b}}, I_{\text{ss}}^{\text{b}}(\dots)$ both nonzero.

Here $T_{\text{st}}^{\text{b}}, T_{\text{ss}}^{\text{b}}(\dots)$ are explicitly defined constants. So, if we know the invariants for one slope function Z , we can compute them for all slope functions \tilde{Z} .

Conclusions

Moduli spaces of configurations are the right tools to use to understand how moduli spaces of θ -(semi)stable sheaves, etc., change as we vary the stability condition Z, θ .

For instance, we can compute how the Euler characteristics of moduli spaces of θ -(semi)stable sheaves change using Theorem 4.

There is also an extension of all this to *triangulated categories*, using Bridgeland's notion of stability. This extension should be important in *Homological Mirror Symmetry* of Calabi–Yau m -folds, and Π -*stability* and *branes* in String Theory.

Applied to the derived category of coherent sheaves, the invariants I_{st}, \dots are an extension of the Gromov–Witten invariants, I think.

Applied to the derived category of the Fukaya category, the invariants count configurations of *special Lagrangian m -folds*. This is how I started working on all this.