

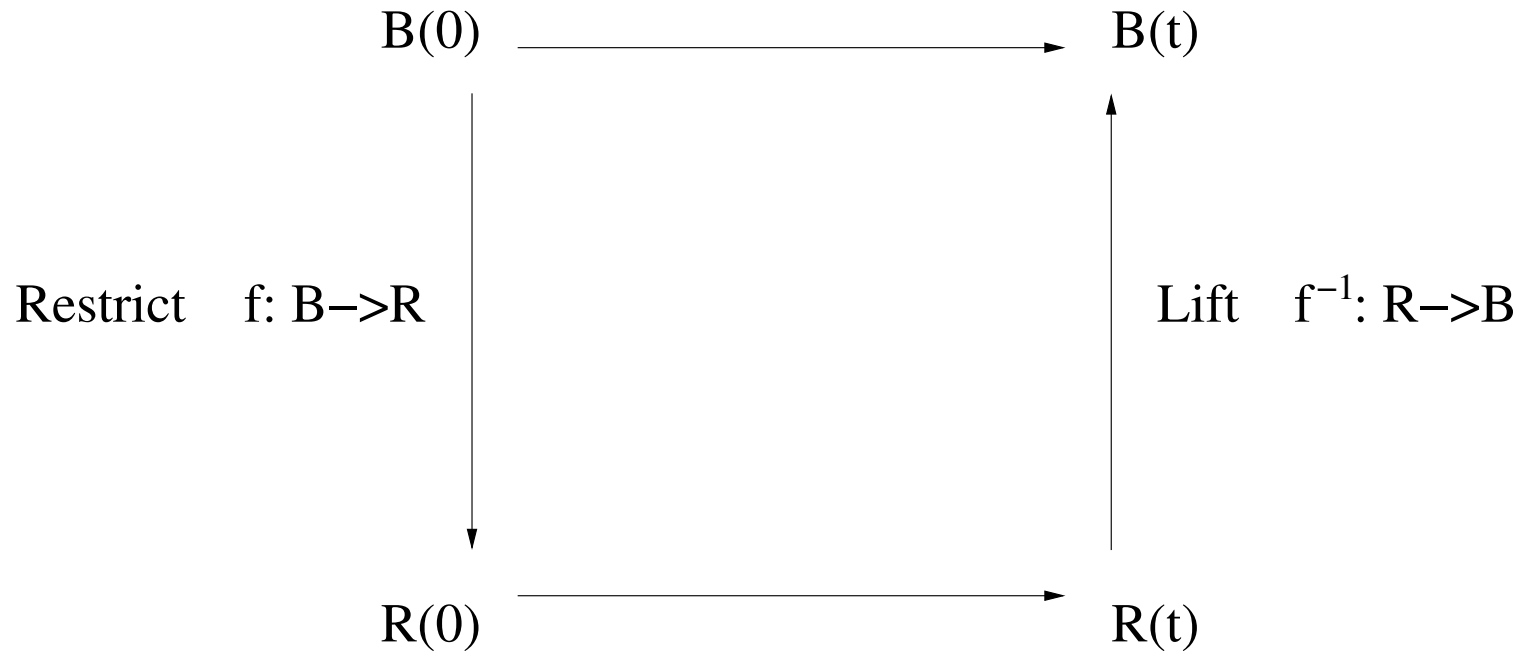
# Localized Pulses in Neural Networks

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NIH

# Program

Biophysical Description  
(Spiking models)



Reduced Description  
(Rate Models)

Time Evolution

# Localized persistent activity

- Short term working memory is correlated to persistent states of neural activity
- Possible analogue in neural network equations are localized self-sustaining 'pulse' or 'bump' solutions.
- Show existence and stability of pulses and find properties
- Compare and contrast bumps in rate models to spiking models

# Integrate-and-Fire Network

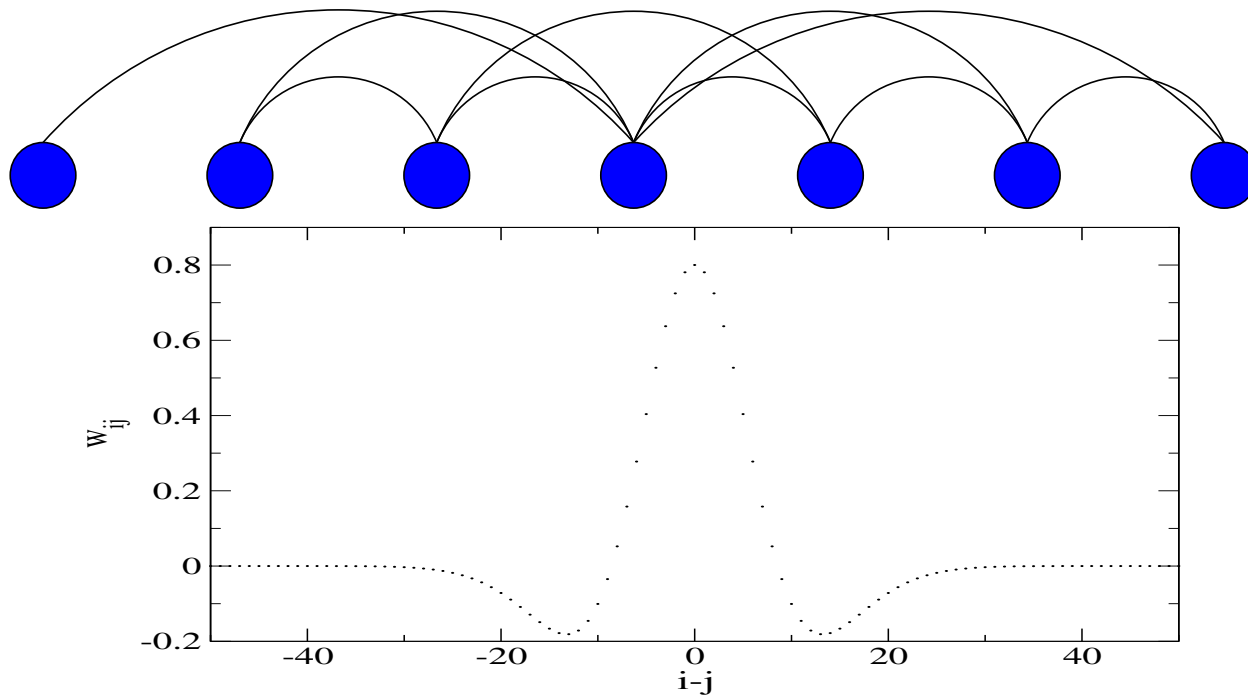
$$\frac{dv_i}{dt} = I - v_i + \sum_j w_{ij} s_j(t), \quad s_j(t) = \beta \exp(-\beta t)$$

Neuron fires and resets when  $v$  reaches threshold

# Integrate-and-Fire Network

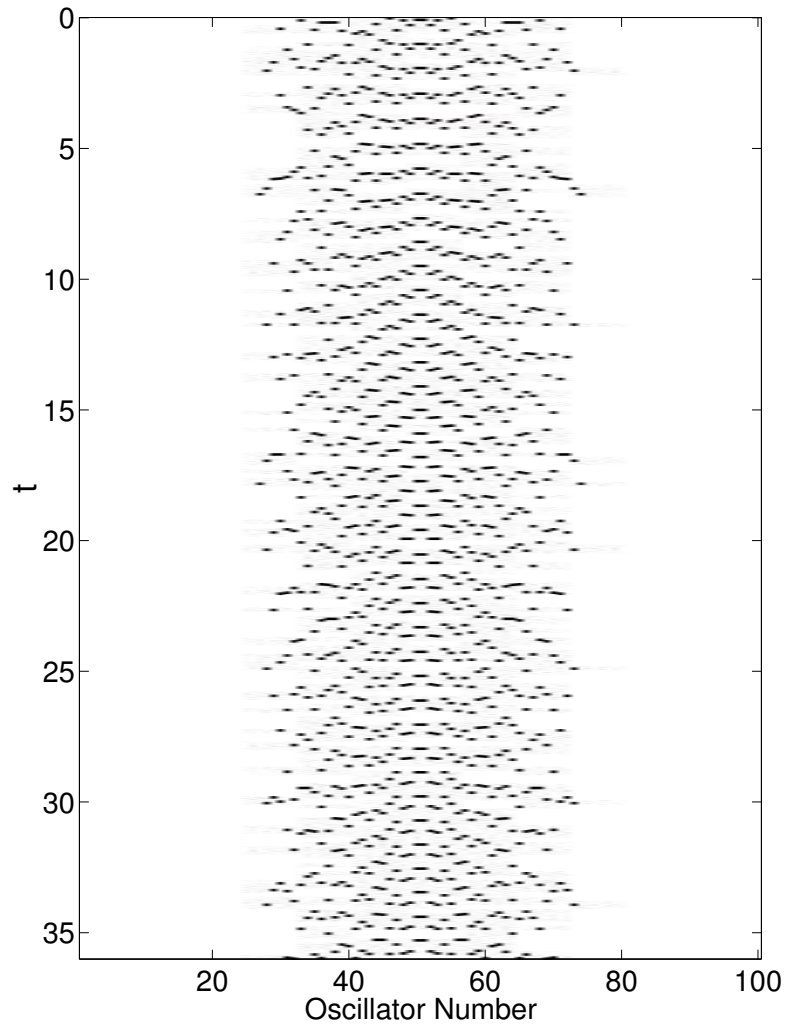
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# Localized persistent state (pulse)

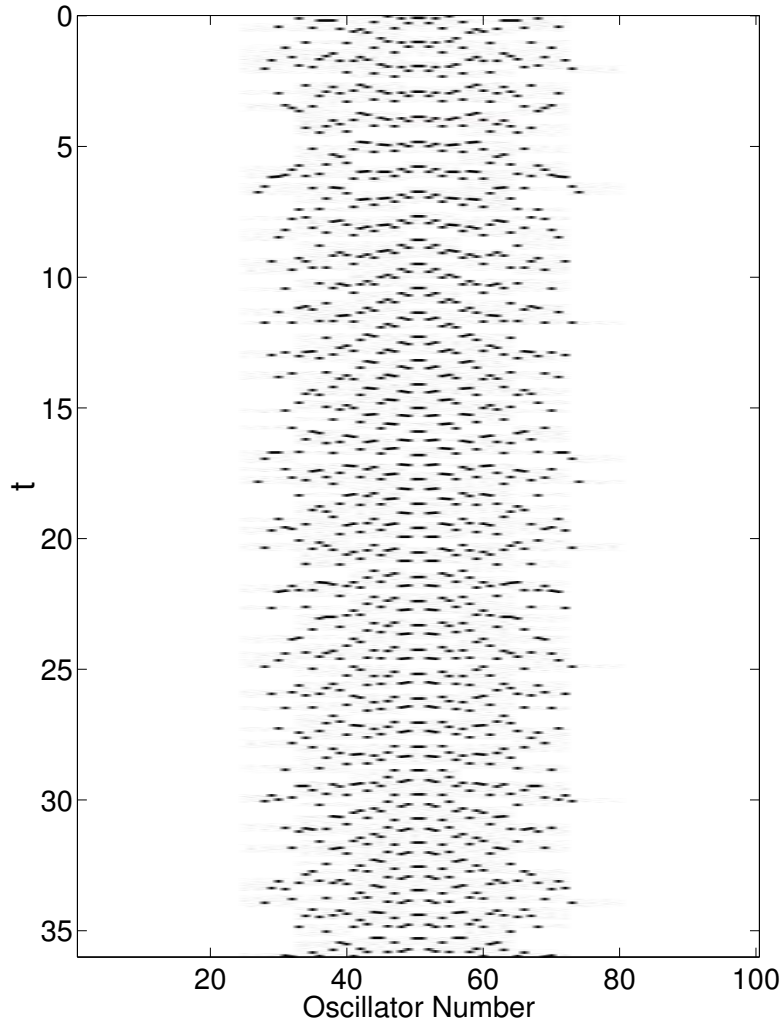
Simulation



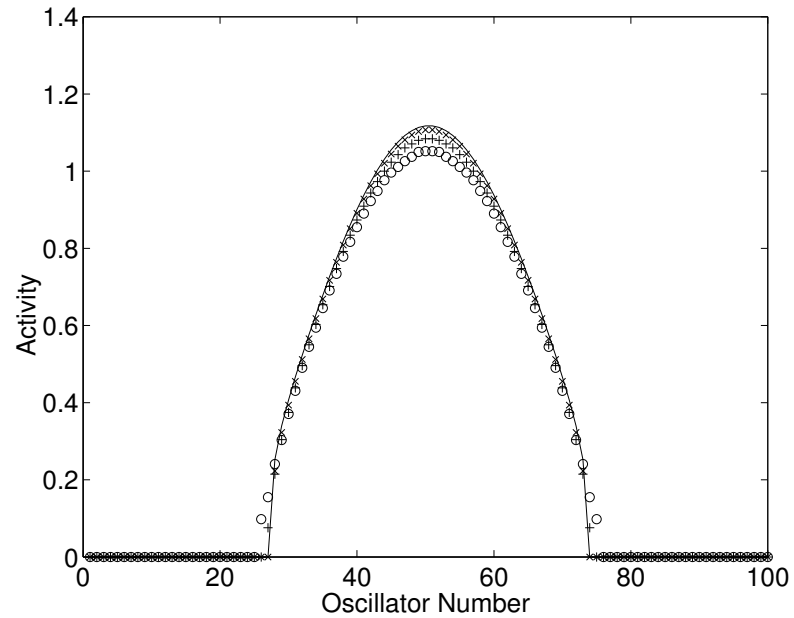
Laing and Chow, 2001

# Localized persistent state (pulse)

Simulation



Average firing rate



Laing and Chow, 2001

# Mean field approach

- Neuronal dynamics if neuron last fired at  $t = s$

$$v_i(t) = I(1 - e^{-(t-s)}) + u_i(t) - u(s)e^{-(t-s)}$$

with neuronal input

$$u_i(t) = \sum_{l \in \text{spikes}} \sum_{j \in \text{neurons}} w_{ij} \epsilon(t - t_j^l)$$

where

$$\epsilon(t) = \beta \frac{e^{-\beta t} - e^{-t}}{\beta - 1}$$



- Can rewrite as

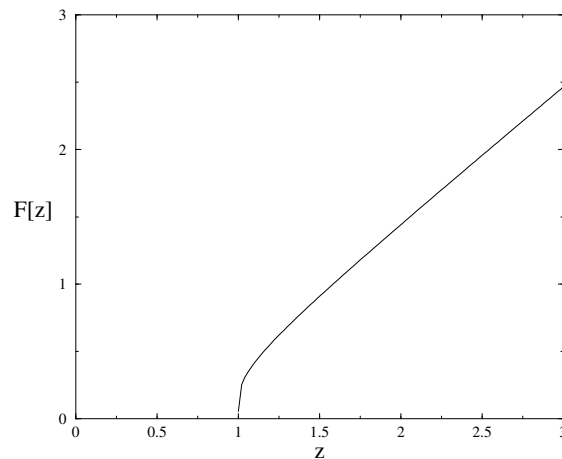
$$u_i(t) = \sum_j w_{ij} \int_0^\infty \epsilon(s) A_j(t-s) ds$$

where  $A_j(t) = \sum_l \delta(t - t_j^l)$  is the “activity” of neuron  $j$

- $u_i$  is almost constant if input is uncorrelated (or if synapses are slow)
- Average of  $A_i$  is the firing rate of neuron  $i$  given  $u_i$ , i.e.  
 $A_i = f[u_i]$

- For integrate-and-fire neuron:

$$f[u] = 1/\ln \left[ \frac{I + u}{I + u - 1} \right]$$

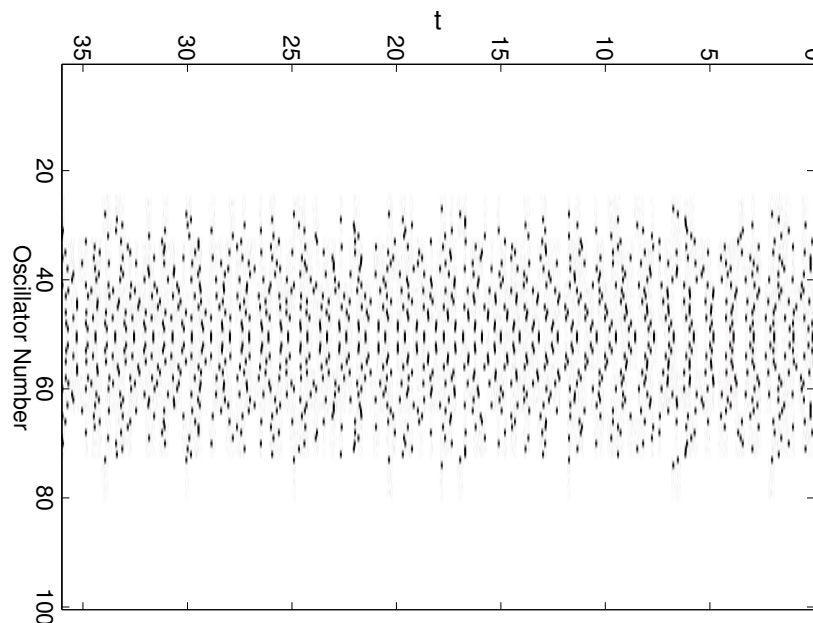
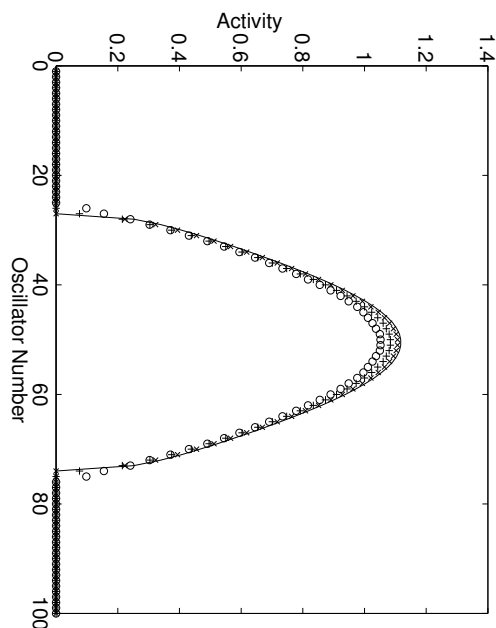


- $f[u]$  is the 'gain function'

- This gives the mean field equations

$$u_i = \sum w_{ij} f[u_j], \quad A_i = f[u_i]$$

- Matched simulations of integrate-and-fire network (with Carlo Laing)



# Dynamics

- Suppose inputs are slowly varying:  $A_i(t) \simeq f[u_i(t)]$ ,

$$u_i(t) = \sum_j w_{ij} \int_{-\infty}^t \epsilon(t-s) f[u_j(s)] ds$$

- If  $\epsilon(t) \sim \exp(-t/\tau)/\tau$  then

$$\tau \frac{du_i(t)}{dt} = -u_i + \sum_j w_{ij} f[u_j]$$

(..., Wilson-Cowan, Cohen-Grossberg, Amari, Ermentrout,...)

- Breaks down if not slowly varying (Gerstner, van Hemmen)  
–Spike response formalism

- Coarse-grain in space

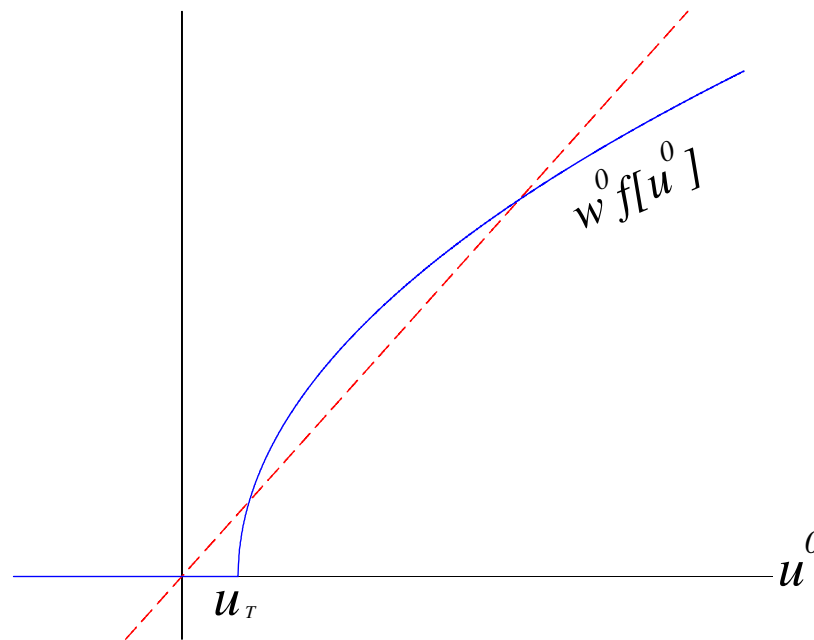
$$\tau \frac{\partial u(x, t)}{\partial t} = -u(x, t) + \int_{\Omega} w(x - y) f[u(y, t)] dy$$

- Stationary solutions obey

$$u(x) = \int_{\Omega} w(x - y) f[u(y)] dy$$

# Constant stationary solutions

- Suppose  $\int_{\Omega} w(x - y) dy = w^0$ , constant solutions  $u_i = u^0$  satisfy  $u^0 = w^0 f[u^0]$



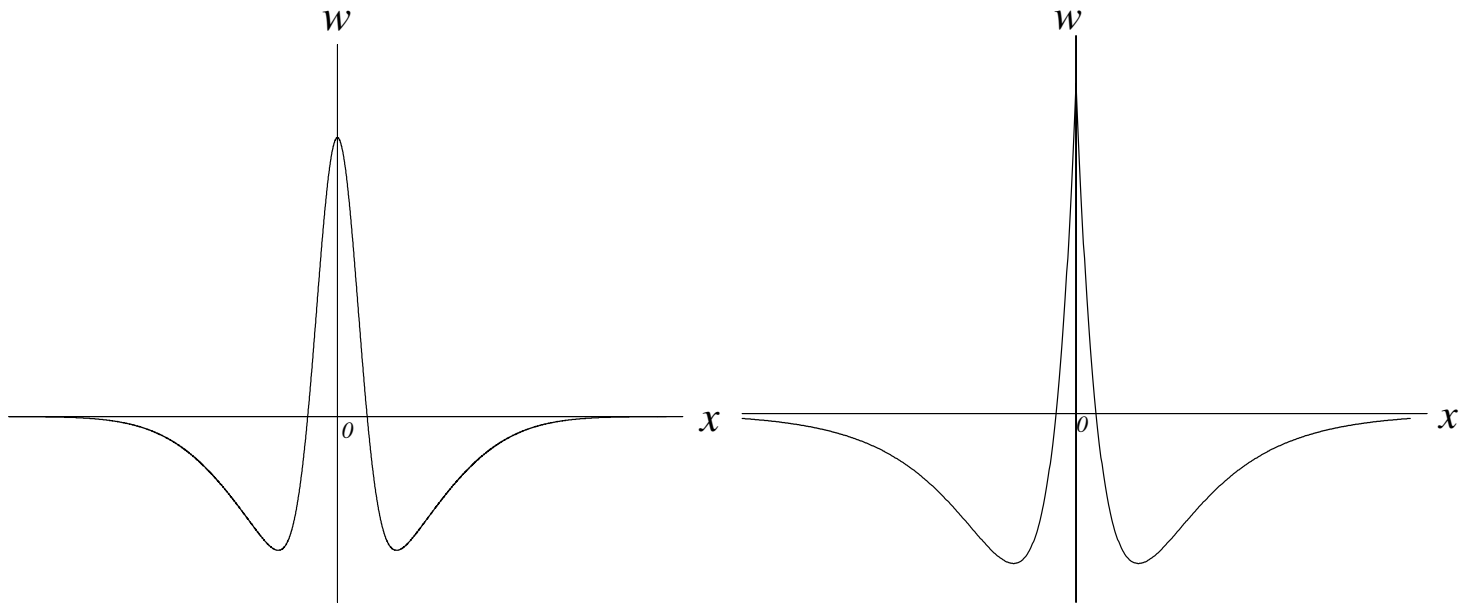
- Multiple stationary solutions possible (analogue of memory)

# Localized pulse solutions

$$u(x) = \int_{\Omega} w(x - y) f[u(y)] dy$$

- Spatially dependent weights  
e.g. 'Mexican Hat'

'Wizard Hat'

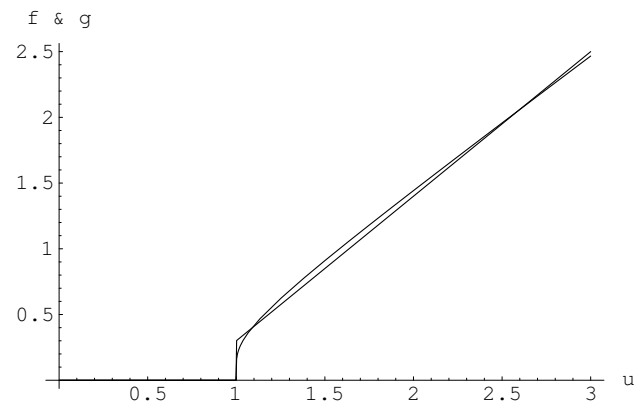
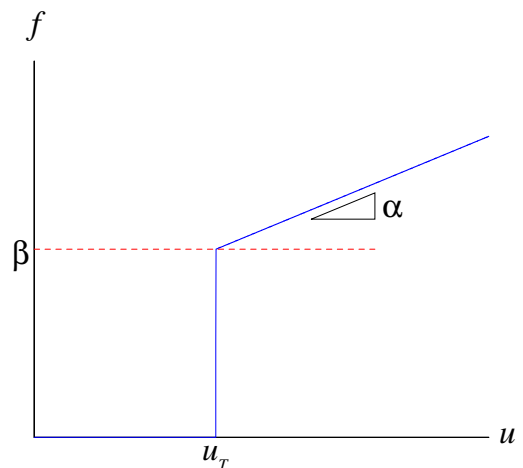


$$w(x) = Ae^{-ax^2} - Be^{-bx^2}$$

$$w(x) = Ae^{-a|x|} - Be^{-b|x|}$$

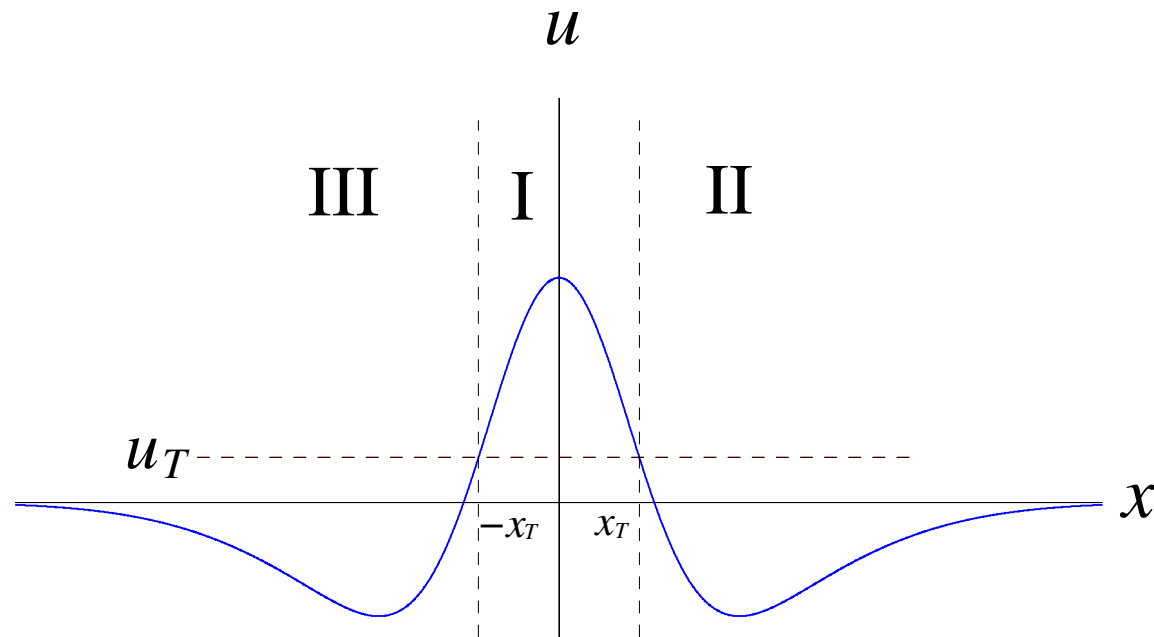
- Consider ‘jump linear’ gain function to represent integrate-and-fire gain

$$f[u] = [\alpha(u - u_T) + \beta] H(u - u_T)$$





- Find pulse solutions of the form



- $u(x_T) = u_T$

# Project to Low Dimension

- Strategy is to transform to ODE and solve
- Fourier transform deconvolves integral operator

$$u(x) = \int_{-\infty}^{\infty} w(x - y) f[u(y)] dy$$

to

$$F[u] = F[w]F[f[u]]$$

with

$$F[\cdot] = \int e^{isx} \cdot dx, \quad F^{-1}[\cdot] = \frac{1}{2\pi} \int e^{-isx} \cdot dx$$

- For  $w(z) = Ae^{-a|z|} - Be^{-b|z|}$

$$F[w] = \frac{2aA(s^2 + b^2) - 2bB(s^2 + a^2)}{(s^2 + a^2)(s^2 + b^2)}$$

- Rearrange to obtain

$$(s^2 + a^2)(s^2 + b^2)F[u] = 2ab(Ab - Ba)F[f] + 2(aA - bB)s^2F[f]$$

- Inverse transform

$$\begin{aligned} u'''' - (a^2 + b^2)u'' + a^2b^2u &= 2ab(bA - aB)f[u] \\ &+ 2(aA - bB) \left\{ f[u(x_T)] [\delta'(x - x_T) + \delta'(x + x_T)] \right. \\ &\quad + f'[u(x_T)]u'(x_T) [\delta(x - x_T) + \delta(x + x_T)] \\ &\quad \left. + [f''[u(x)](u')^2 + f'[u(x)]u'']_{u \geq u_T} \right\} \end{aligned}$$

- Piecewise linear 4th order ODE

- Choice of coupling allows for projection to low dimension

Pulse solution must satisfy:

## 1. Boundary conditions

$$u(x) > u_T, \quad -x_T < x < x_T$$

$$u'(0) = u'''(0) = 0$$

$$u(\pm\infty) = 0 \text{ and derivatives}$$

## 2. Matching conditions at $x = x_T$

$$u(x_T^+) = u(x_T^-) = u_T$$

$$u'(x_T^+) = u'(x_T^-)$$

$$u''(x_T^+) = u''(x_T^-) + 2(aA - bB)f[u(x_T^-)]$$

$$u'''(x_T^+) = u'''(x_T^-) + 2(aA - bB)f'[u(x_T^-)]u'(x_T^-)$$

- Solutions have the form

$$I : u(x) = C(e^{\omega+x} + e^{-\omega+x}) + D(e^{\omega-x} + e^{-\omega-x}) + U_0$$

$$II : u(x) = Ee^{-ax} + Fe^{-bx}$$

$$III : u(x) = Ee^{ax} + Fe^{bx}$$

where

$$U_0 = \frac{2(\beta - \alpha u_T)(bA - aB)}{ab - \alpha(bA - aB)}, \quad \omega_{\pm} = \left[ \frac{R \pm \sqrt{\Delta}}{2} \right]^{1/2}$$

$$R = a^2 + b^2 + 2\alpha(aA - bB), \quad \Delta = [R^2 - 4a^2b^2 + 8\alpha ab(bA - aB)]$$

- Solution structure changes as  $\omega_{\pm}$  changes

# Matching Conditions

$$Ee^{-ax_T} + Fe^{-bx_T} = u_T$$

$$C(e^{\omega+x_T} + e^{-\omega+x_T}) + D(e^{\omega-x_T} + e^{-\omega-x_T}) + U_0 = Ee^{-ax_T} + Fe^{-bx_T}$$

$$\omega_+ C(e^{\omega+x_T} - e^{-\omega+x_T}) + \omega_- D(e^{\omega-x_T} - e^{-\omega-x_T}) = -aEe^{-ax_T} - bFe^{-bx_T}$$

$$\omega_+^2 C(e^{\omega+x_T} + e^{-\omega+x_T}) + \omega_-^2 D(e^{\omega-x_T} + e^{-\omega-x_T}) = a^2 Ee^{-ax_T} + b^2 Fe^{-bx_T} \\ - 2\beta(aA - bB)$$

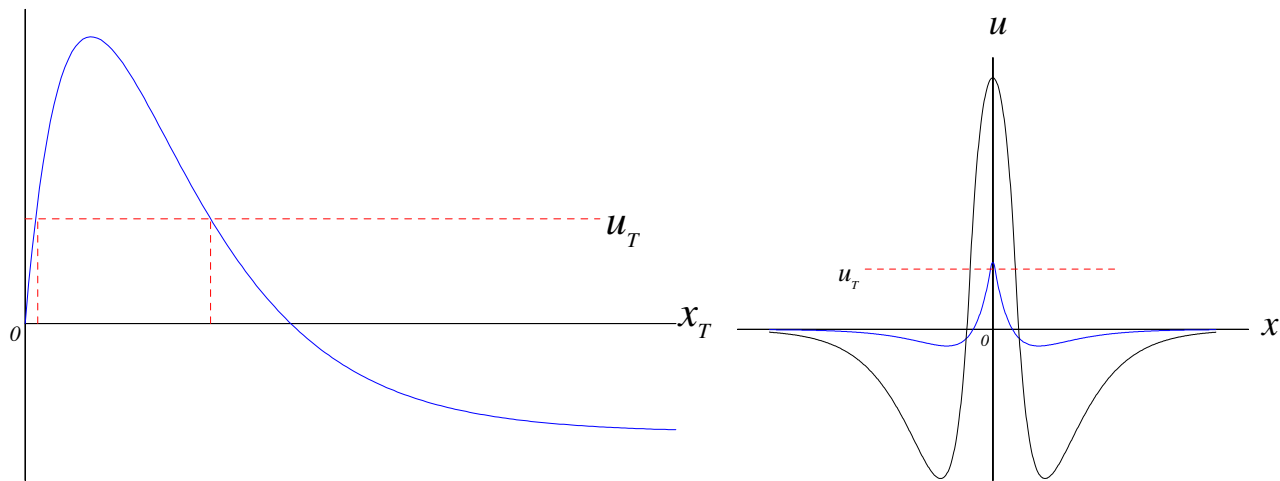
$$\omega_+^3 C(e^{\omega+x_T} - e^{-\omega+x_T}) + \omega_-^3 D(e^{\omega-x_T} - e^{-\omega-x_T}) = \\ - a^3 Ee^{-ax_T} - b^3 Fe^{-bx_T} + 2\alpha(aA - bB)[aEe^{-ax_T} + bFe^{-bx_T}]$$

- Pulse exists if solution can be found (5 eq'ns, 5 unknowns)
- Solve 'linear system' for coefficients  $C, D, E, F$  and obtain existence condition  $\Phi(x_T) = u_T$
- Simple for  $\alpha = 0$ , unwieldy otherwise

# Amari's Solution: $\alpha = 0$

- $f[u] = H[u - u_T]$  with  $w(z) = Ae^{-a|z|} - Be^{-b|z|}$
- Existence Condition ( $u_T = \int_{-x_T}^{x_T} w(x - y)dy$ )

$$\Phi(u_T) \equiv \frac{A}{a}(1 - e^{-2ax_T}) - \frac{B}{b}(1 - e^{-2bx_T}) = u_T$$

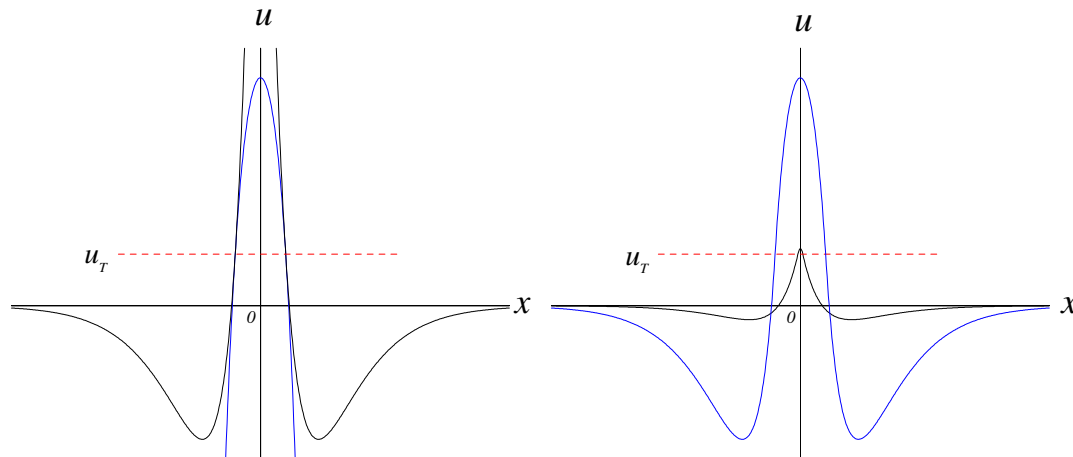
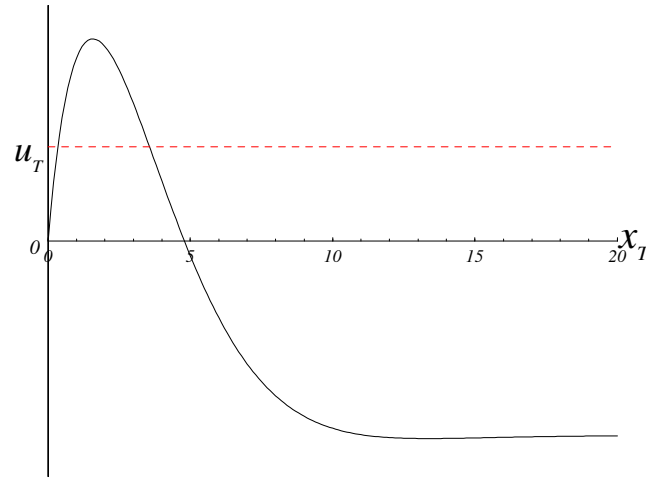


- Two pulse solutions (small and large)
- Only large one is linearly stable

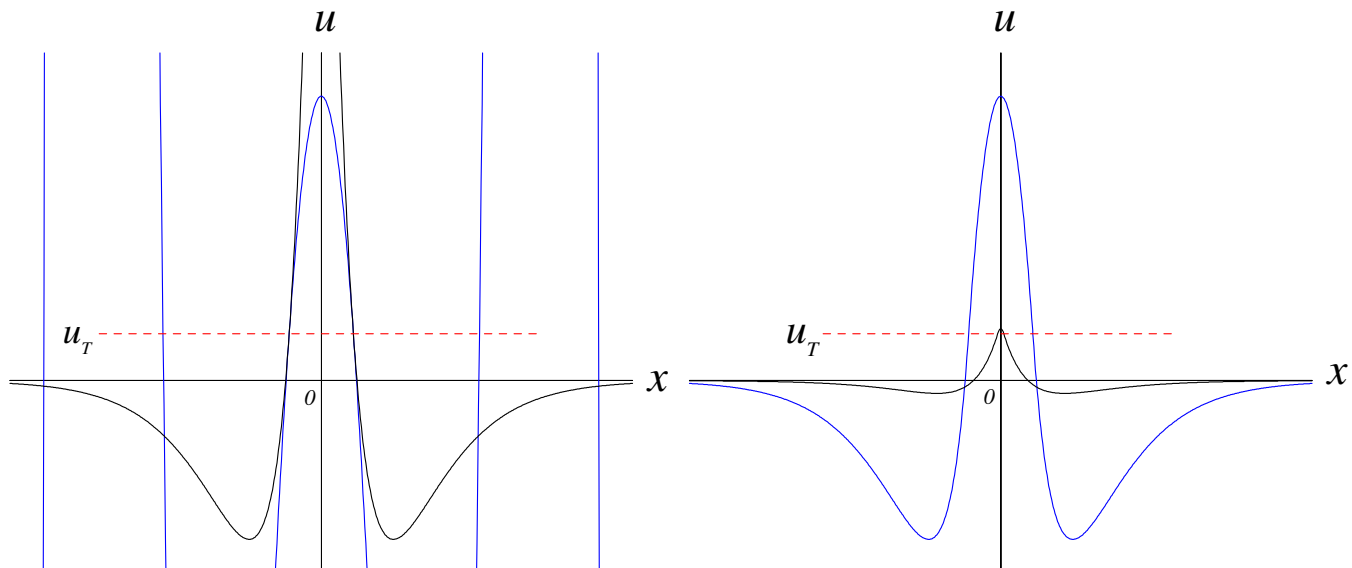
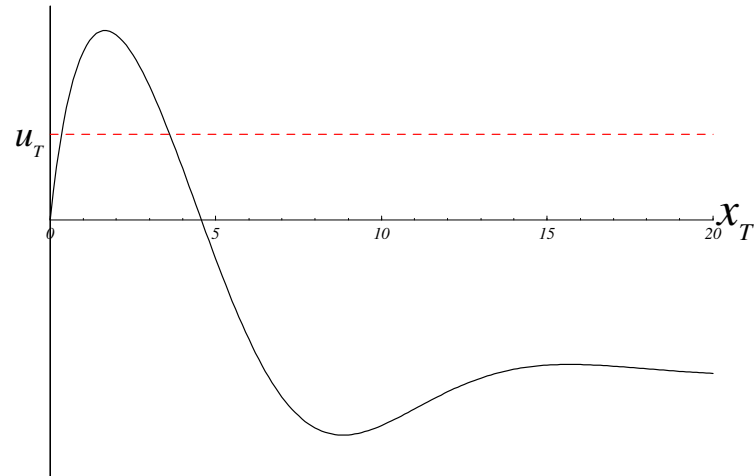


# Nonzero $\alpha$

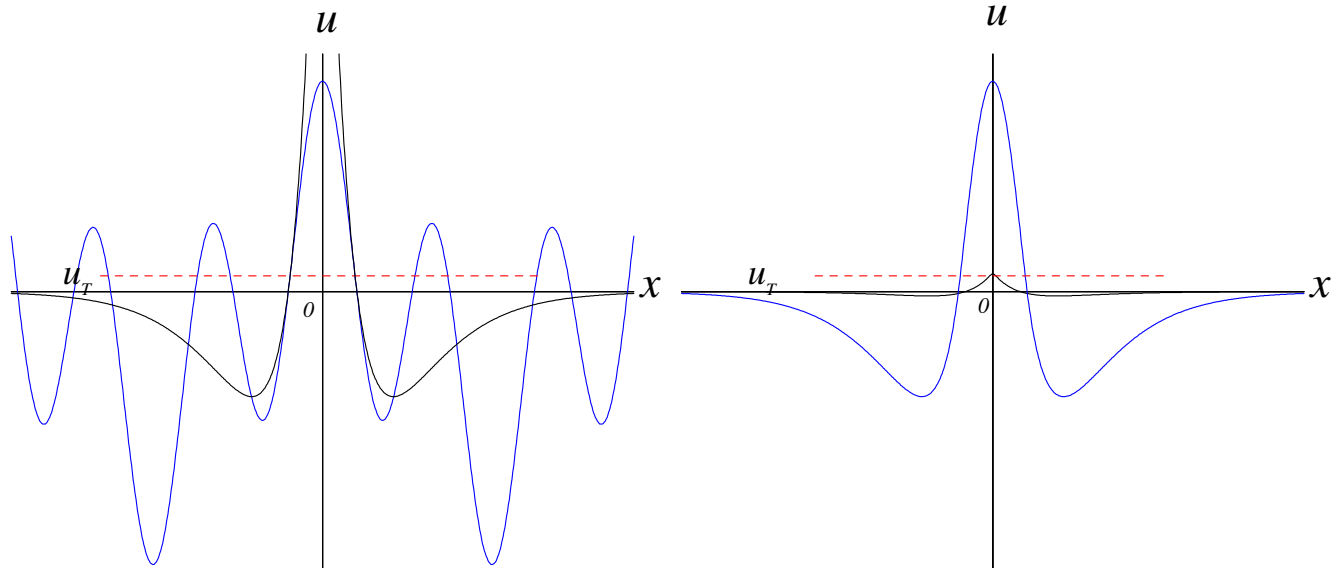
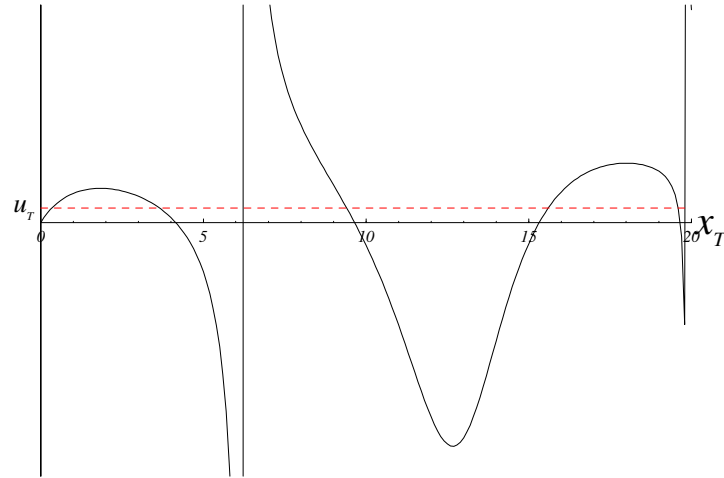
- Examples with  $A = 1, B = 0.65, a = 0.32, b = 0.18, \beta = 1$   
 $\alpha = 0.1$



$$\alpha = 0.5$$



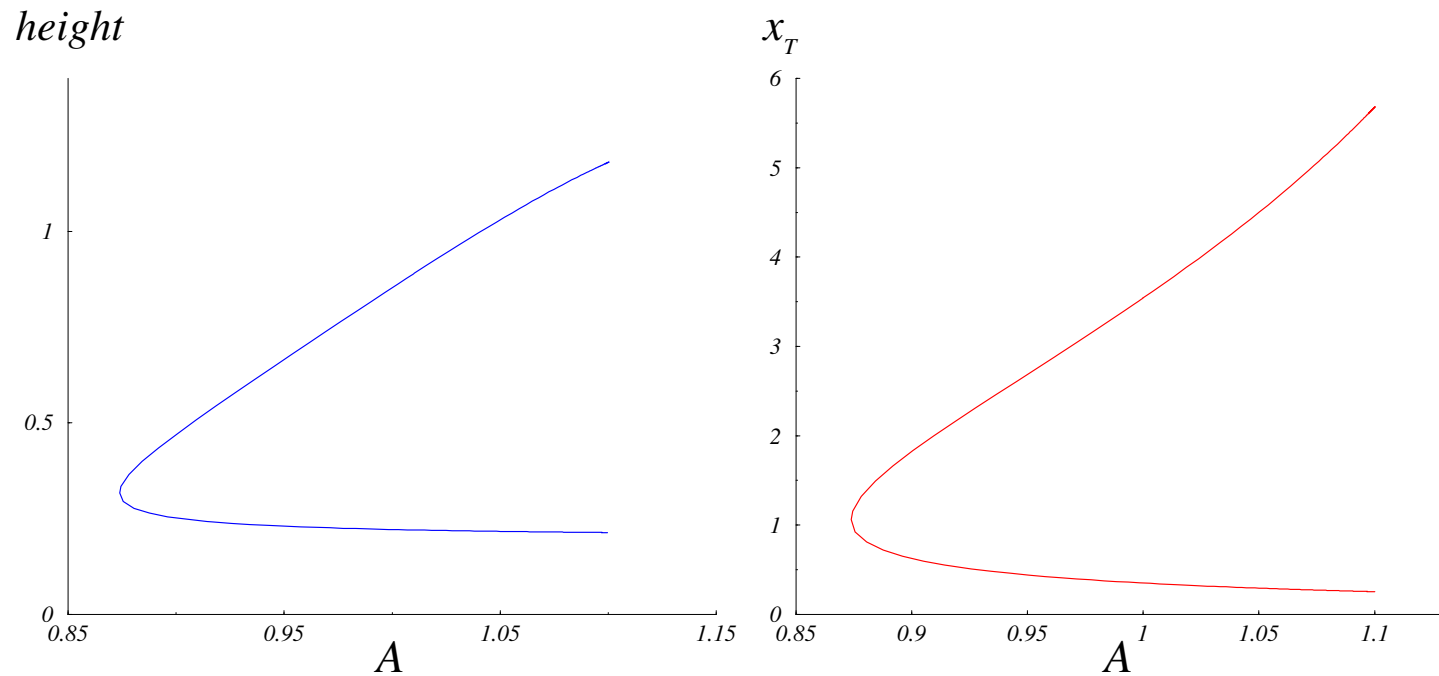
$$\alpha = 1.0$$



# Continuation

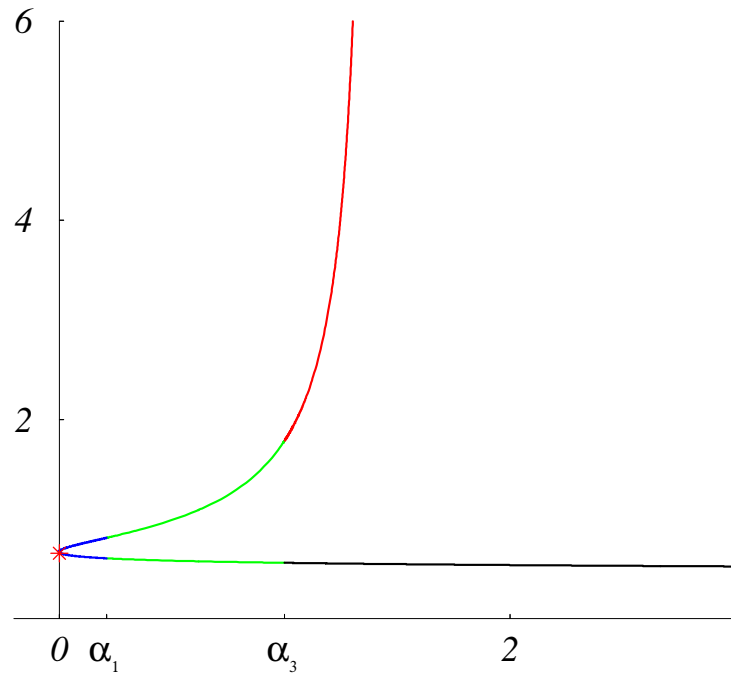
- Small bump and large bump annihilate in saddle node

$$\alpha = 0.04$$

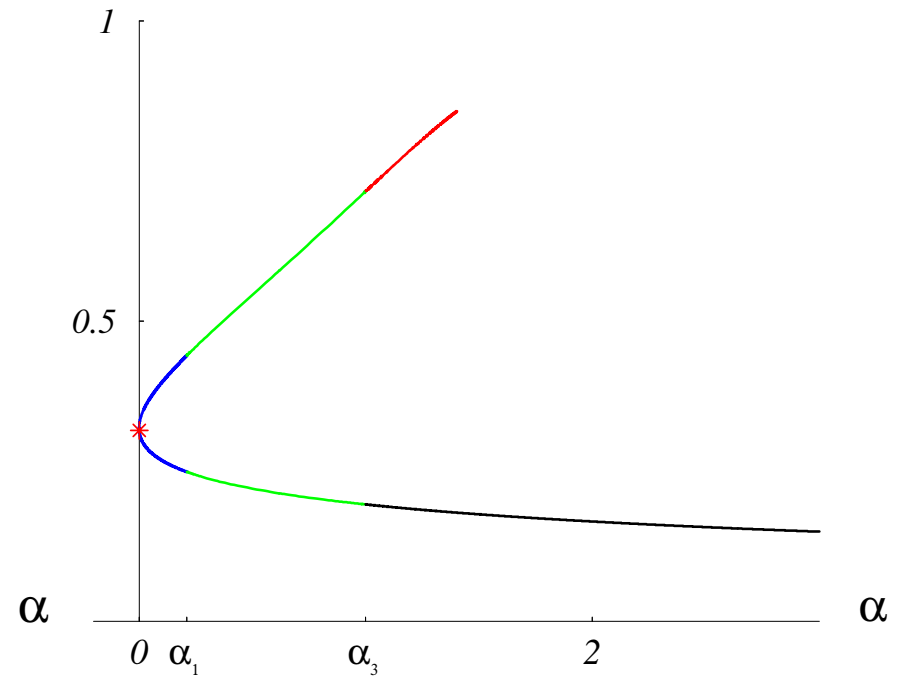


# Height goes to infinity at critical $\alpha$

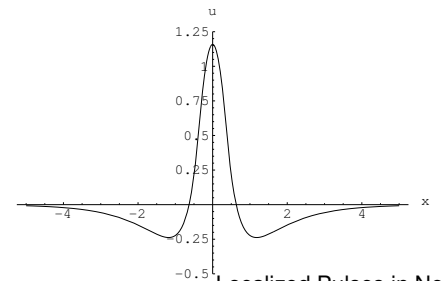
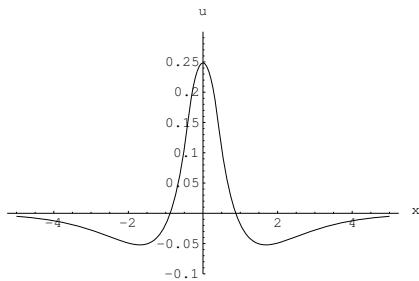
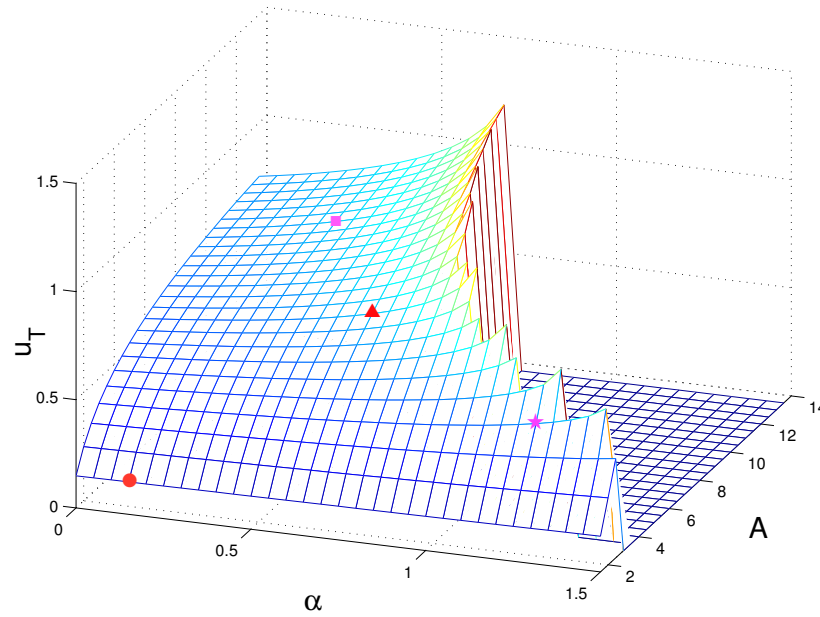
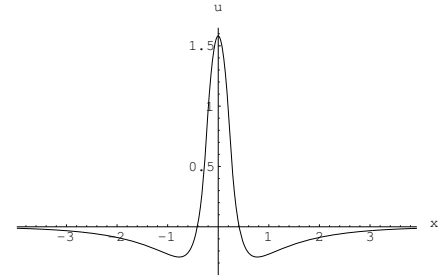
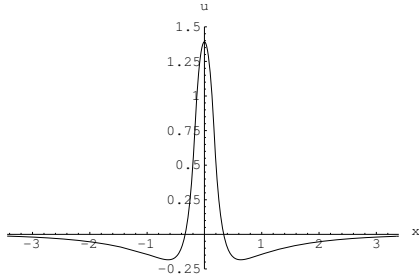
*Height*



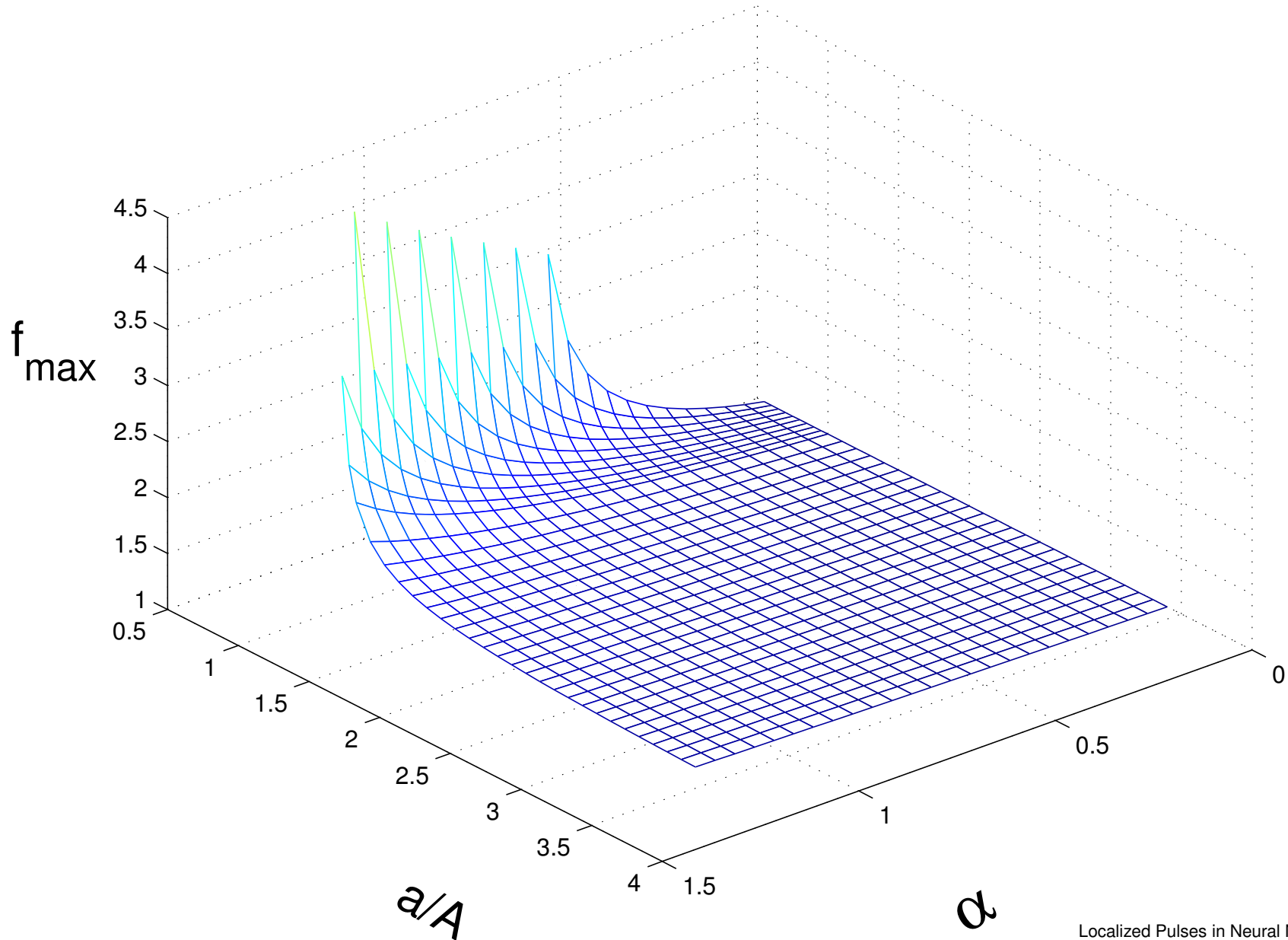
*Width*



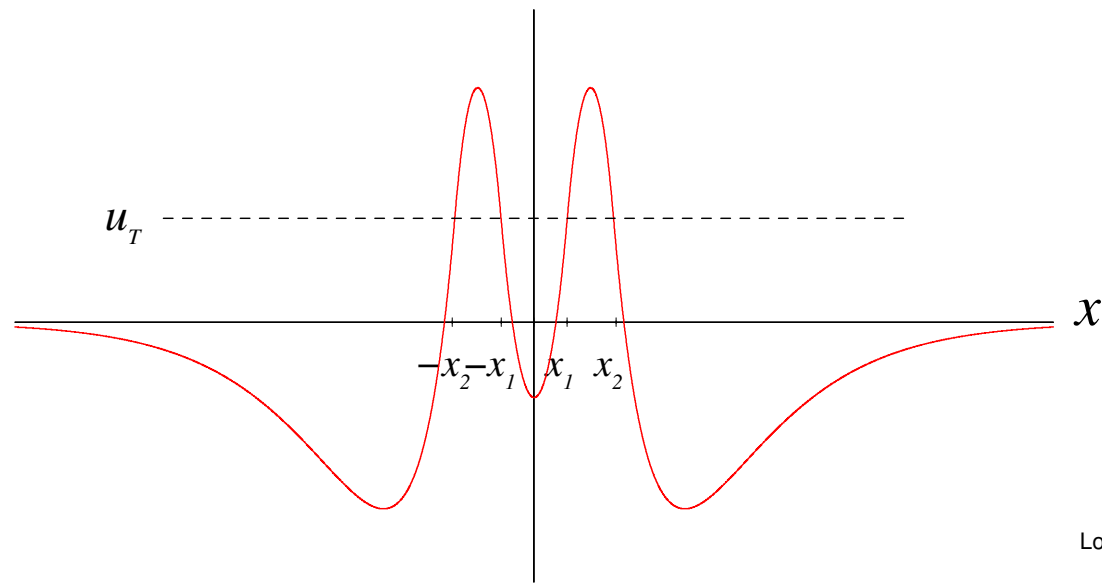
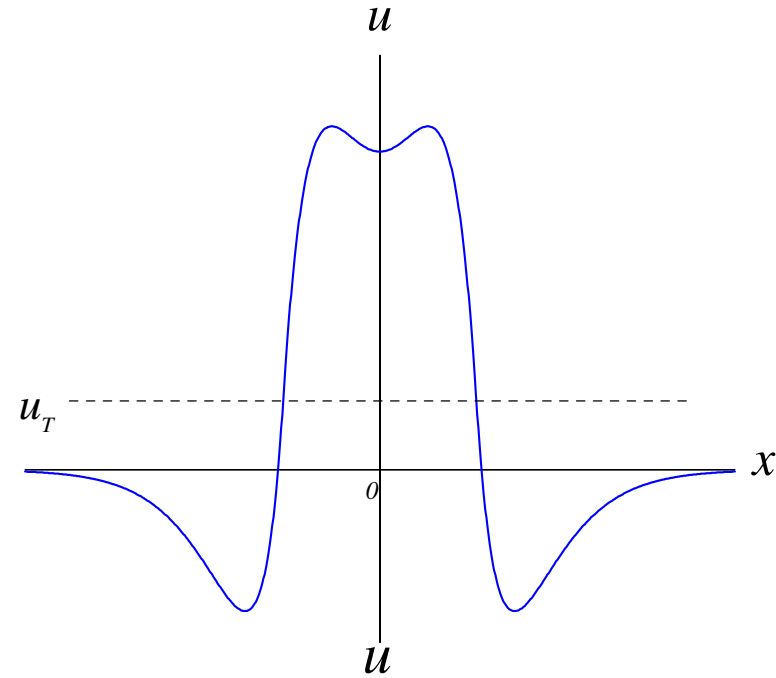
# Critical $u_T$ ( $A = a$ )



# Maximum firing rate

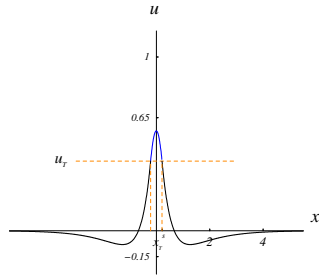


# Dimple and Double Pulses

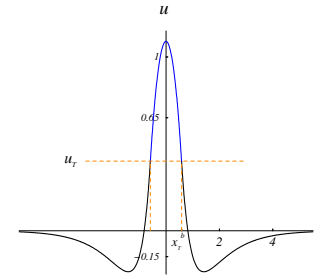




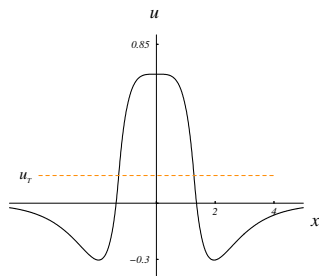
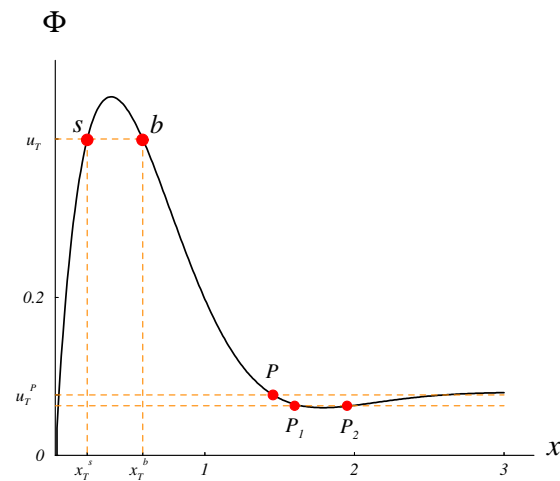
# Transitions in $u_T$ ( $\alpha = 0.6187$ , $A = 2.8$ , $a = 2.6$ , $B = b = \beta = 1$ )



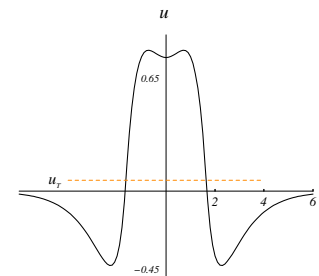
Single-pulse **s**



Single-pulse **b**

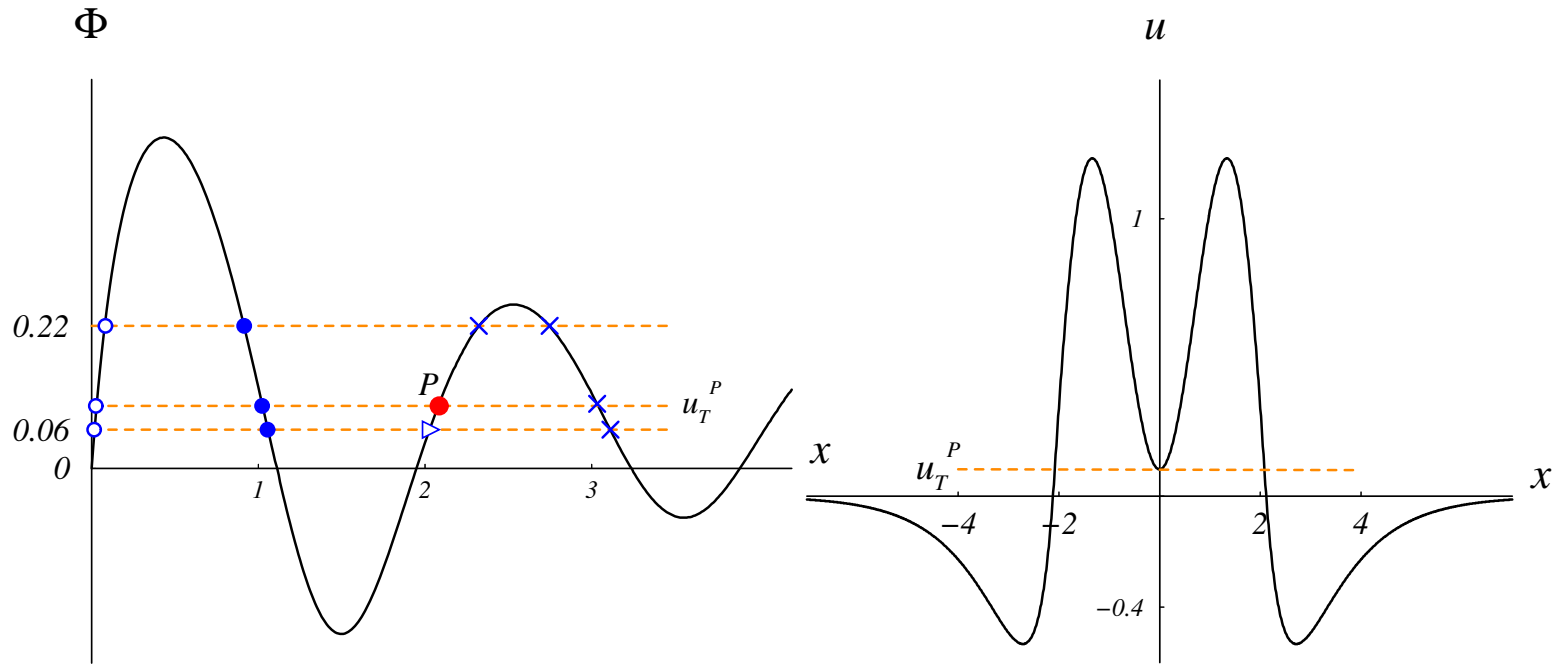


Pulse at transition **P**



Pulse at **P<sub>1</sub>**

$$A = 2.8, a = 2.6, \alpha = 0.9987, \beta = 1$$



- small single pulse
- big single pulse
- ▷ dimple pulse
- × not a valid solution

At  $P$ , dimple pulse splits into a double pulse.

# Linear Stability

$$u_t = -u + \int_{-\infty}^{\infty} w(x-y)f[u(y,t)]dy$$

- Let  $u(x,t) = u_0(x) + v(x)e^{\lambda t}$  and linearize

$$(1+\lambda)v(x) = w(x-x_T)\frac{v(x_T)}{c} + w(x+x_T)\frac{v(-x_T)}{c} + \alpha \int_{-x_T}^{x_T} w(x-y)v(y)dy$$

where  $c > 0$  is the slope of  $u_0(x)$  at  $-x_T$

- $\text{Re}\lambda > 0$  indicates instability
- Consider wizard hat coupling and solve eigenvalue problem

# Properties of Eigenvalue Problem

$$(1 + \lambda) = L(v)$$

- $\lambda$  is real
- $\lambda = 0$  is an eigenvalue (translational invariance)
- $\lambda$  is bounded above by  $\lambda_b$

$$\lambda \leq 2w_0\left(\frac{1}{c} + \alpha x_T\right) - 1 \equiv \lambda_b$$

where  $w_0$  is the maximum of  $|w(x)|$  on  $[-x_T, x_T]$

- Eigenfunction  $v(x)$  is either even or odd.
- $L(v)$  is a compact operator
- Essential spectrum is in the left half plane

# Eigenvalues

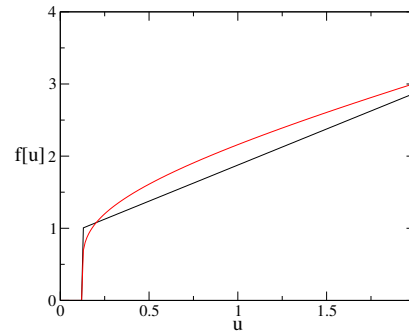
- To evaluate  $\lambda$  explicitly, transform to ODE and solve
- Matching conditions across  $\pm x_T$  form linear system of coefficients  $M(\lambda) = 0$
- Eigenvalues must satisfy  $\text{Det}M(\lambda) = 0$
- If there exists  $0 < \lambda < \lambda_b$  then the standing pulse is unstable
- Otherwise pulse is stable

# Stability Results

- Small pulse is unstable, large pulse is stable
- Can have coexisting stable pulses
- Dimple pulses can be stable and coexist with large pulses
- No stable double pulses for Amari case were found

# Compare to spiking models

- Search parameter space using jump-linear gain rate model matched to integrate-and-fire gain rate model



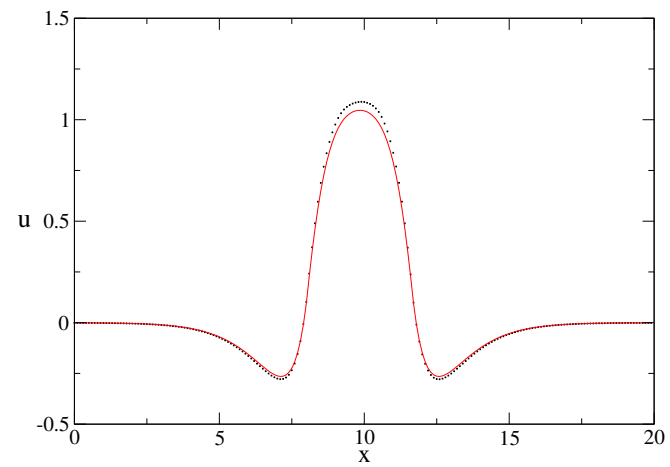
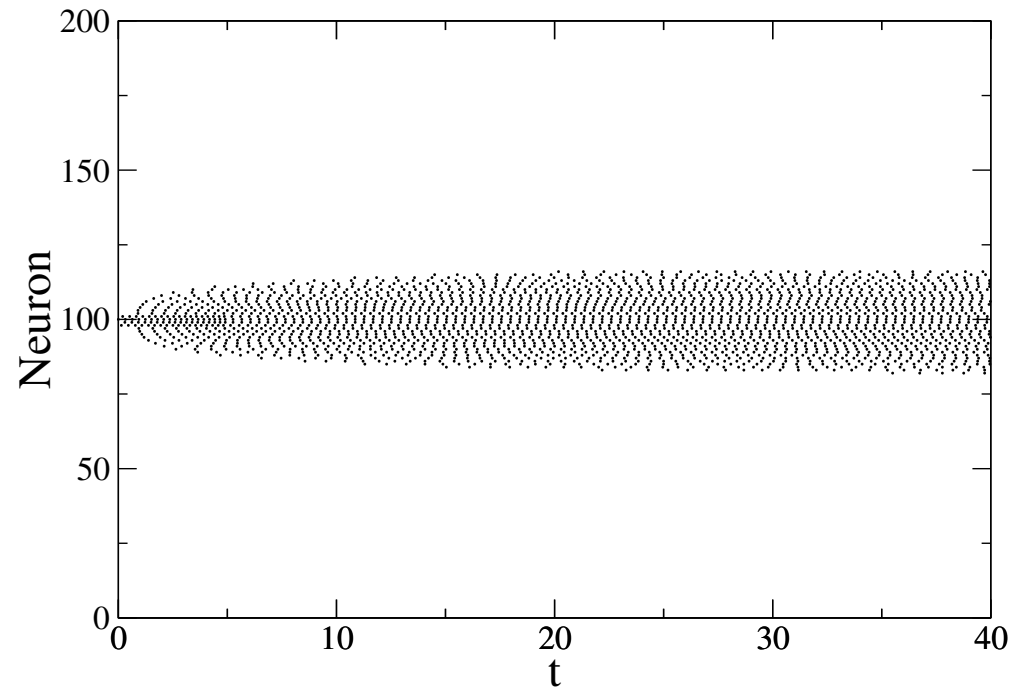
- Simulate in integrate-and-fire spiking model

$$\tau \frac{dv}{dt} = I - v + \sum_j w_{ij} s_j, \quad \frac{ds_j}{dt} = -\beta s_j$$

at  $v_j = \delta$ ,  $v_j \rightarrow 0$ ,  $s_j \rightarrow s_j + \beta$ ,  $\tau = .2$ ,

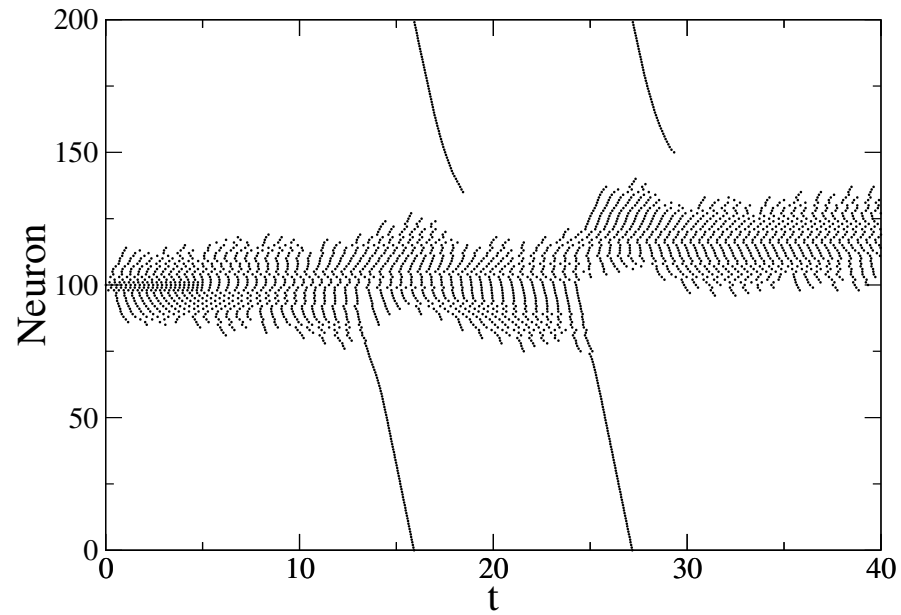
$$w_{ij} = (Ae^{-a|i-j|dx} - e^{-|i-j|dx})dx$$

$$I = 0.786 \quad A = 1.8 \quad a = 1.6 \quad \beta = .5$$

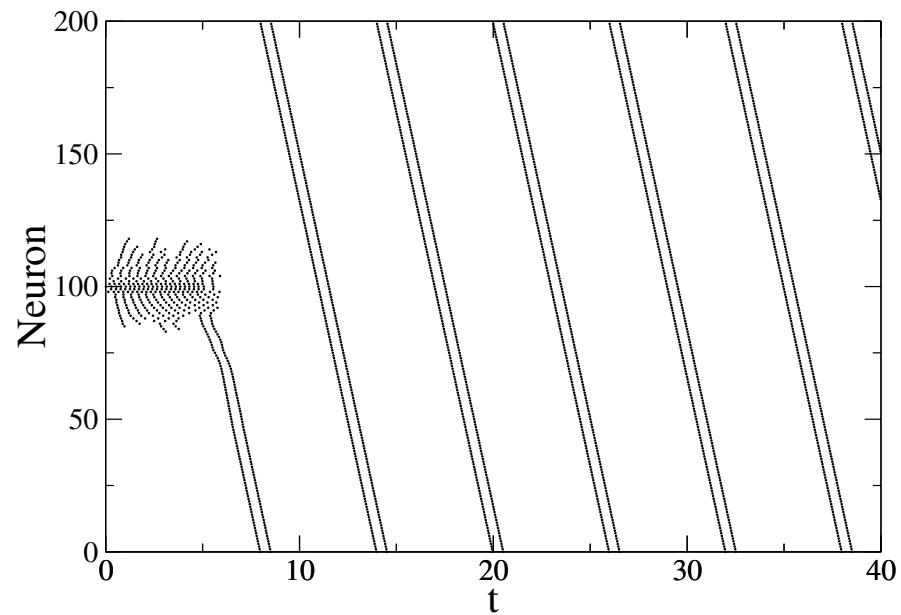




# Increase $\beta$

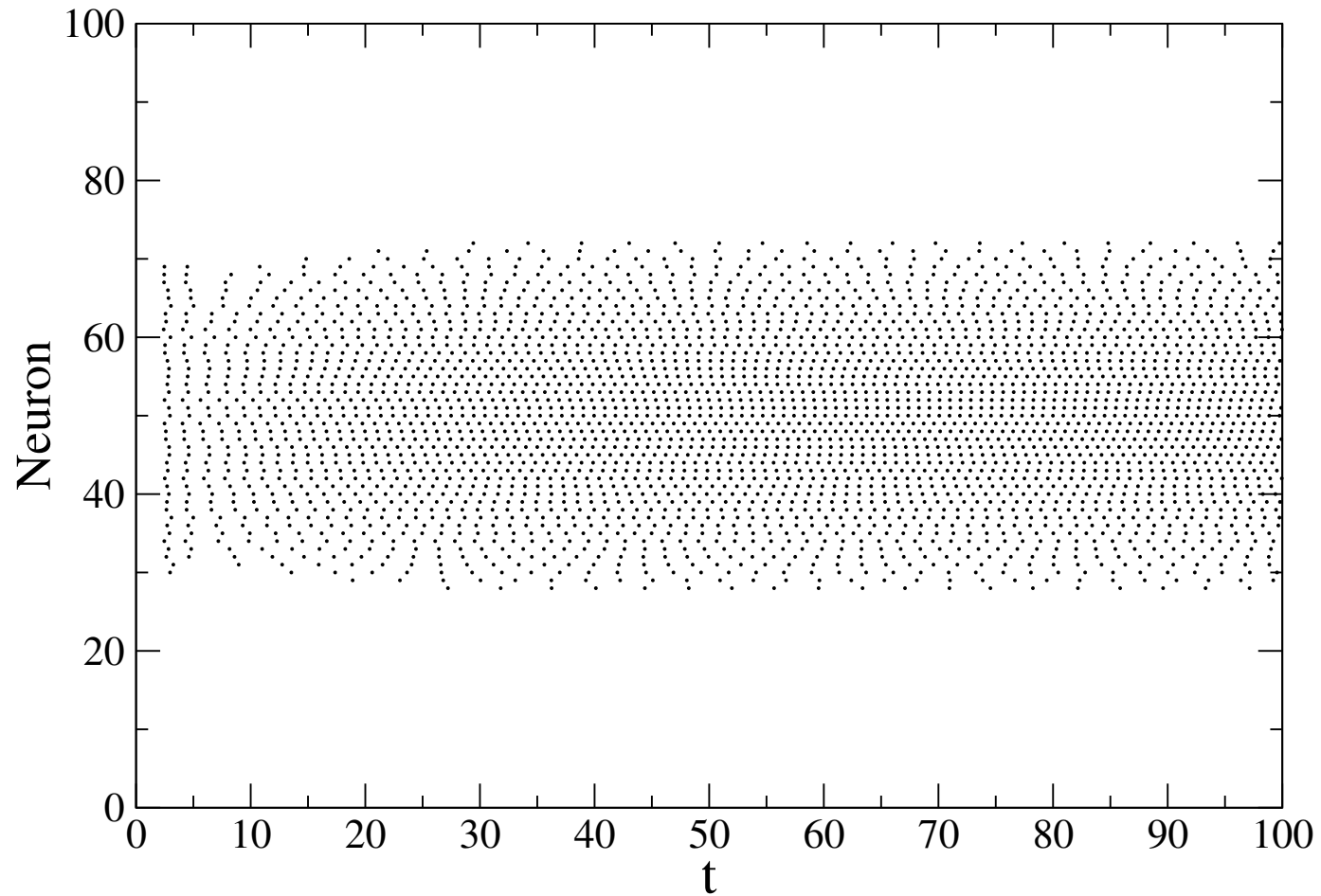


$$\beta = 4$$

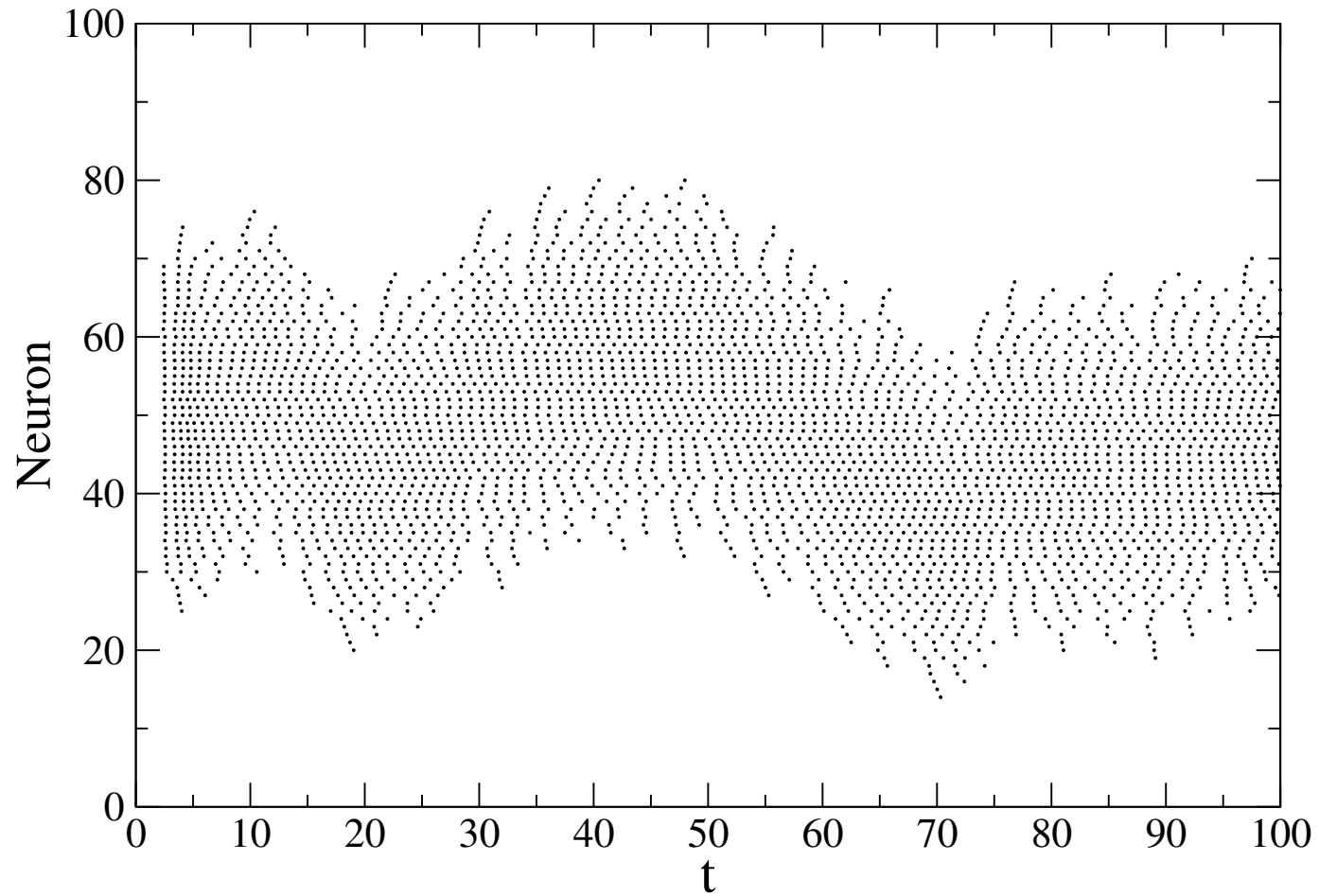


$$\beta = 6$$

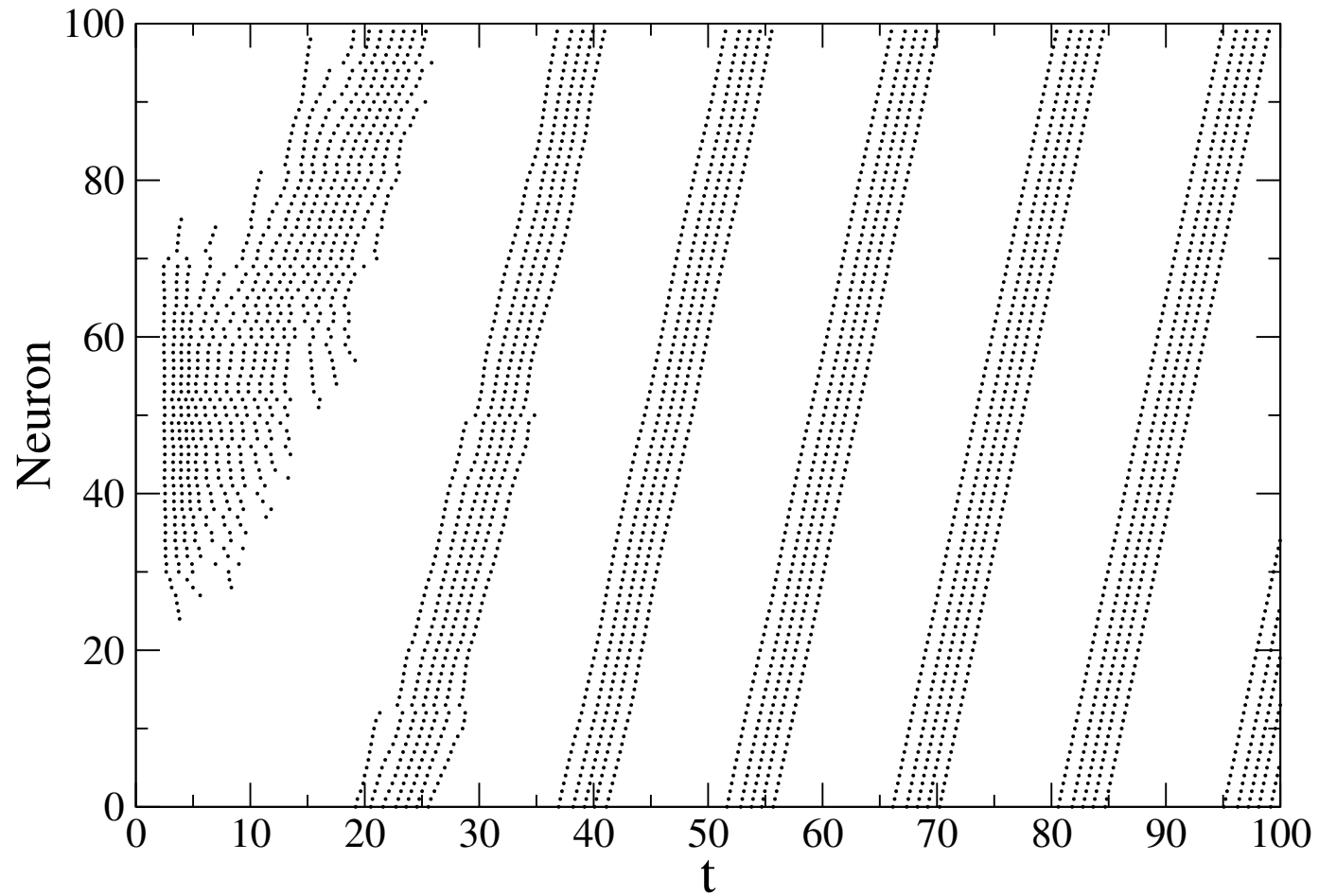
# Gaussian weight function: $\beta = 0.3$



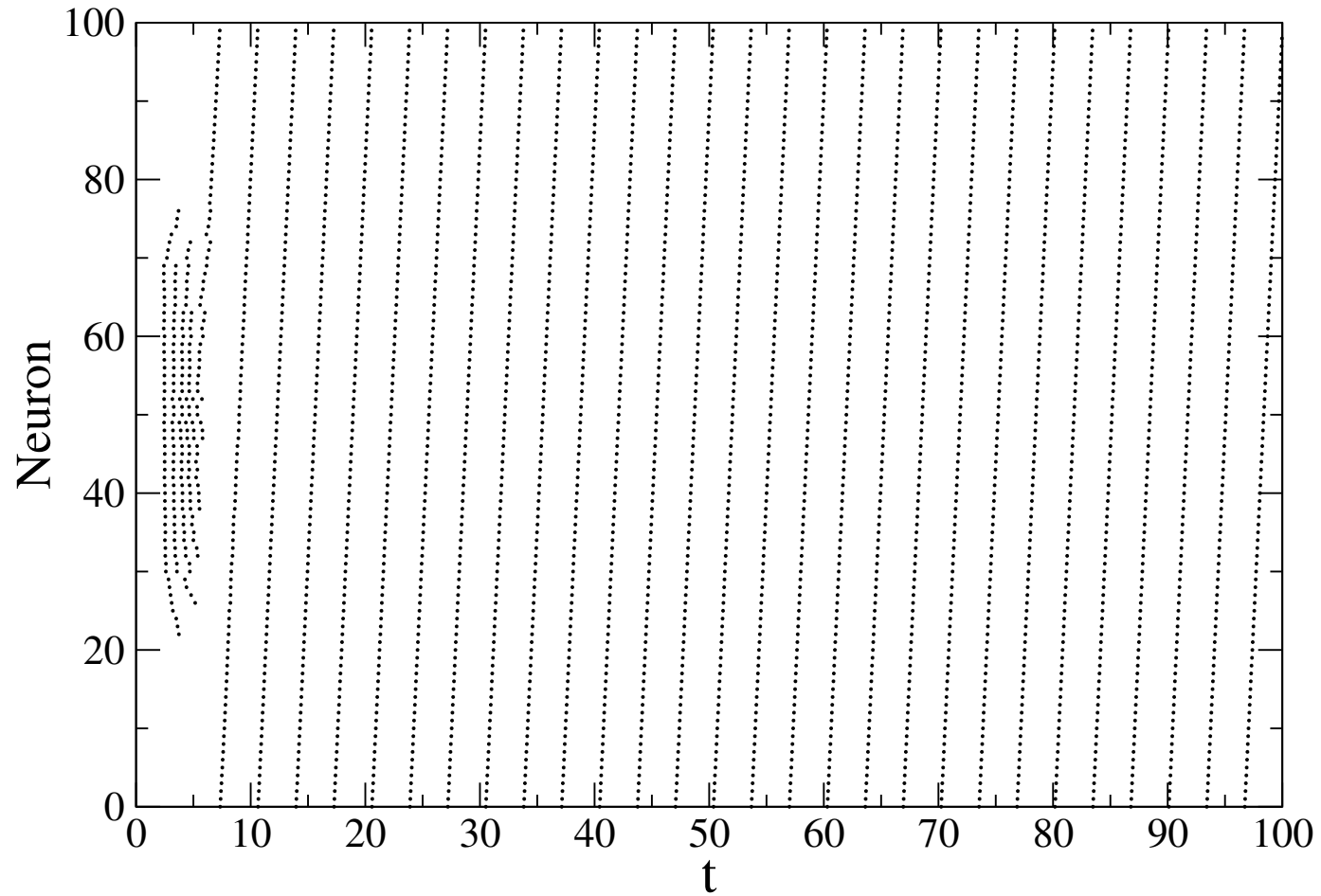
$$\beta = 2.5$$



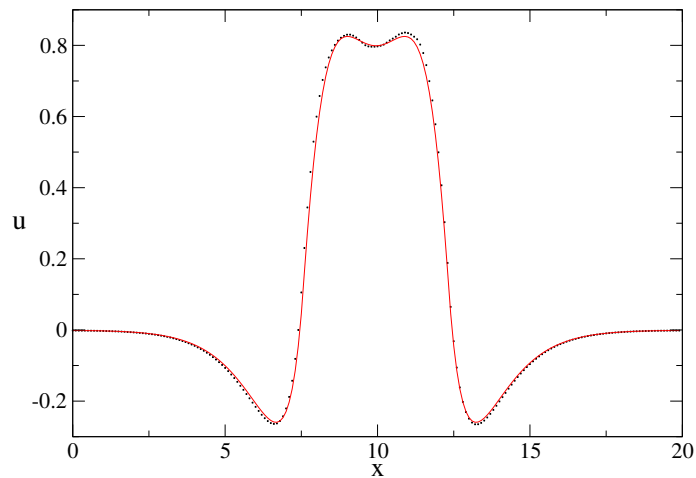
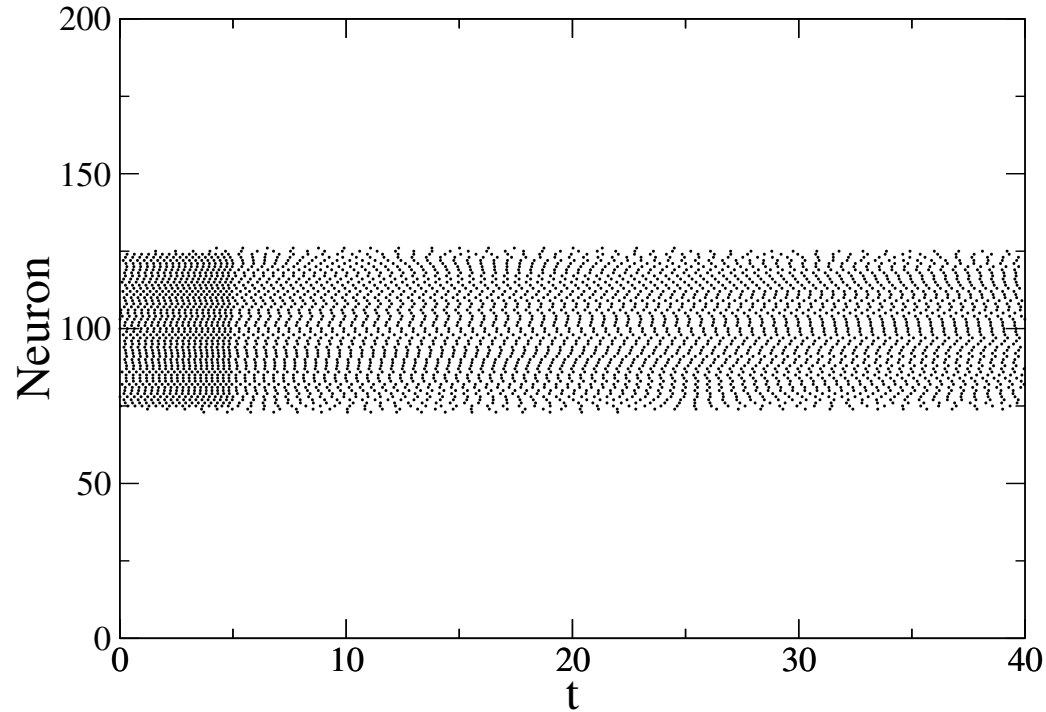
$$\beta = 3.5$$



$$\beta = 5$$

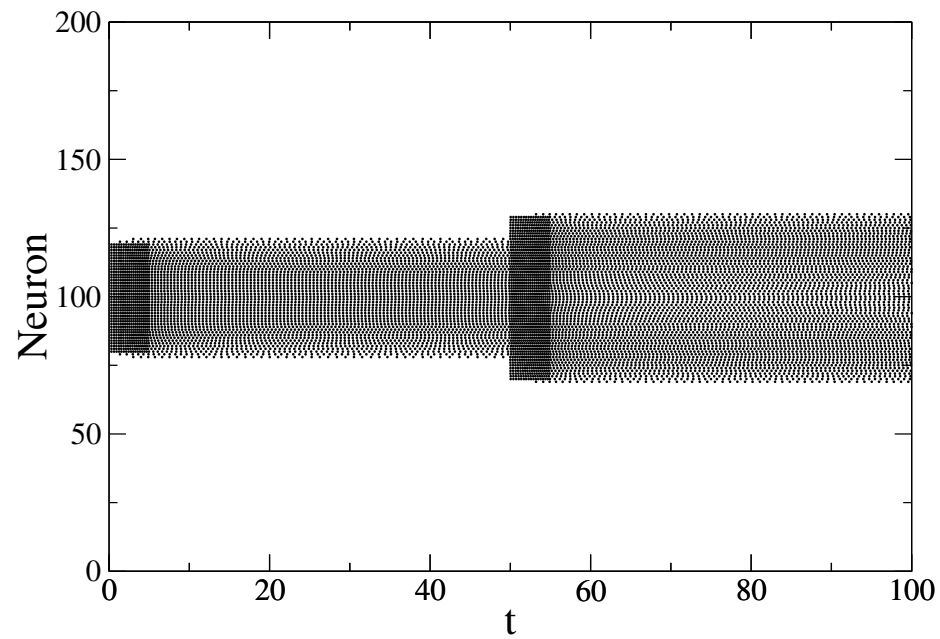
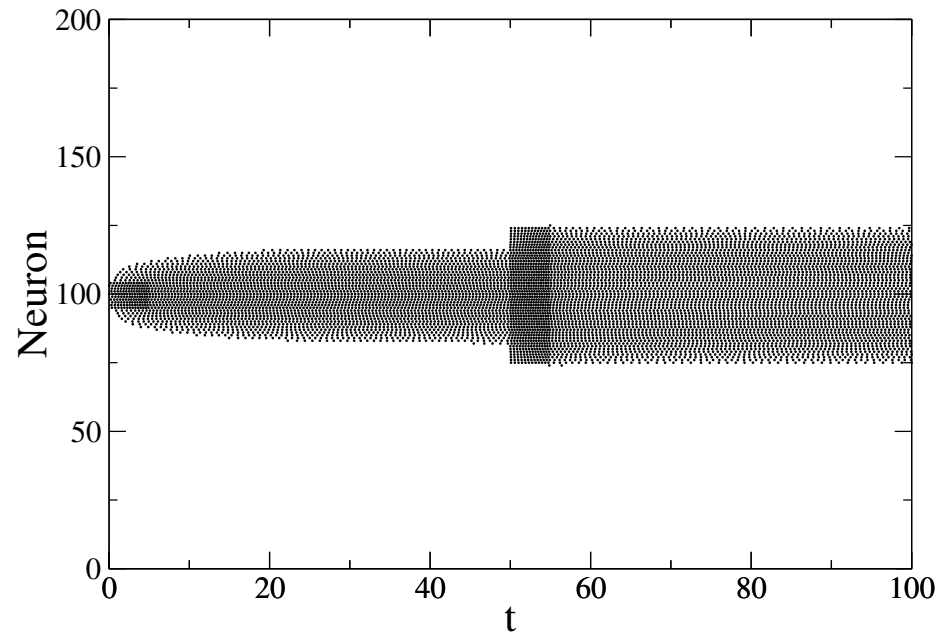


# Dimple Bumps (but not really)

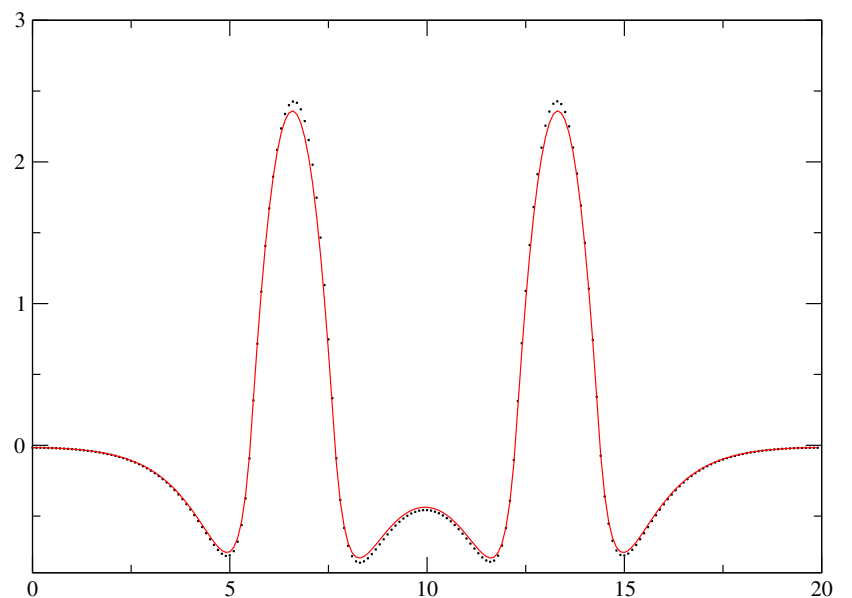
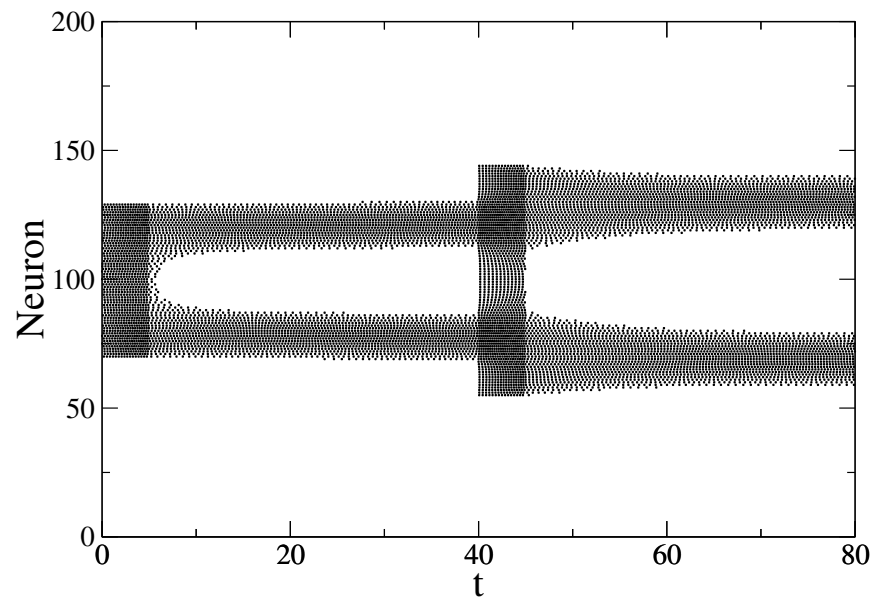
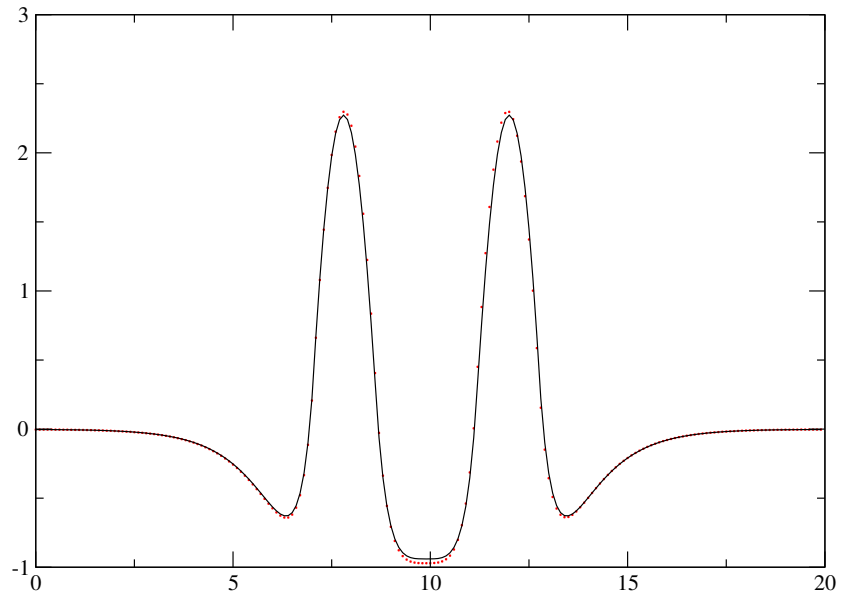
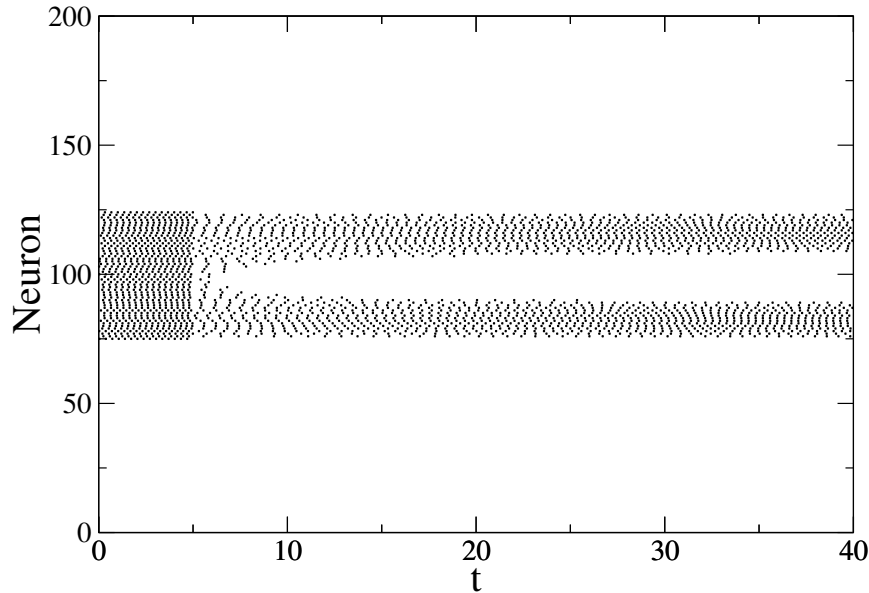


$$I = 0.786 \quad A = 1.8 \quad a = 1.6$$

# Multistability



# Double Bumps $I = 7.74$ $A = 2.8$ $a = 2.65$



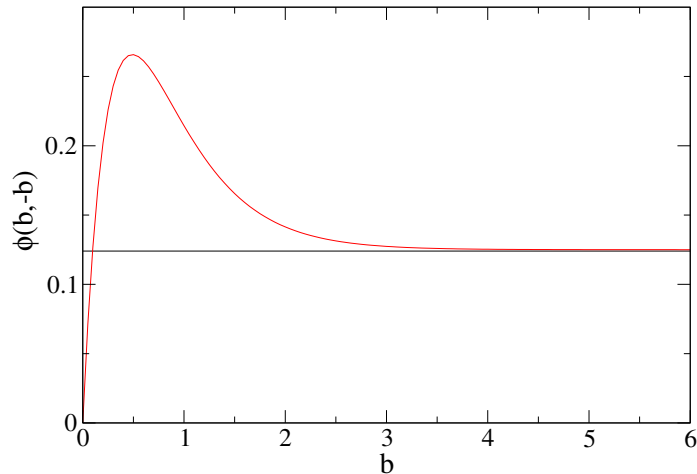


# Discreteness and Marginal Stability

- Discreteness can stabilize marginal modes
- Consider pulse of width  $b$  in Amari equation

$$u(x) = \phi(x, b), \quad u_T = \phi(b, b)$$

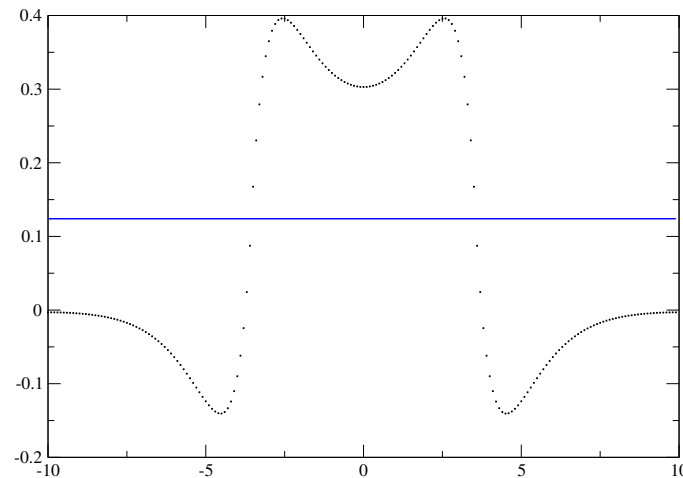
$$\phi(x, b) = \int_{-b}^b A e^{-a|x-y|} - e^{-|x-y|} dy$$



**Dimple case**

$$A = 1.8 \quad a = 1.6 \quad u_T = 0.124$$

- Discretization gives stability to marginal modes since neurons adjacent to edge are below threshold by  $\partial_x \phi(x = b, b) dx \sim (A - 1) dx$



- Since  $\phi(b, -b) - u_T \sim 0.001$ , to eliminate discreteness effect need adjacent neuron to be above threshold. i.e.  $(A - 1) dx < 0.001$
- Thus  $dx < 0.00125$  or need  $> 16,000$  neurons in simulation