

The scaling limit of uniform random plane quadrangulations

Grégory Miermont

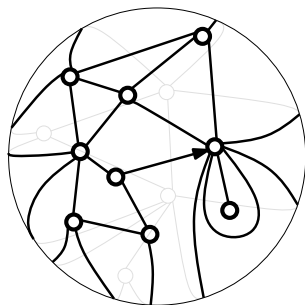
Université de Paris-Sud 11, Orsay

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MSRI, Berkeley
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Plane maps

Definition

A **plane map** is an embedding of a connected, finite (multi)graph into the 2-dimensional sphere, considered up to orientation-preserving homeomorphisms of the sphere.



$V(\mathbf{m})$ Vertices

$E(\mathbf{m})$ Edges

$F(\mathbf{m})$ Faces

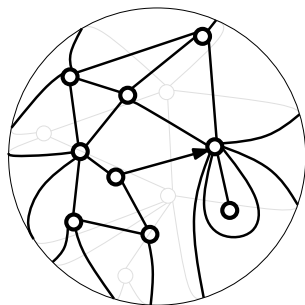
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A **rooted** map: one distinguished oriented edge.

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General motivation

Maps appear naturally in many contexts

- Graph theory (4-color theorem, ...)
- Counting problems
 - ▶ by direct resolution of the equation solved by generating functions, using the quadratic method [Tutte, Bender-Canfield, Bousquet-Mélou-Jehanne, Bousquet-Mélou-Bernardi]
 - ▶ by using matrix integrals [t'Hooft, Brézin-Parisi-Itzykson-Zuber, ...]
 - ▶ by algebraic methods: representation theory of the symmetric group, algebraic geometry [Goulden-Jackson,...]
 - ▶ by **bijjective methods** [Cori-Vauquelin, Schaeffer, Poulalhon, Bouttier-Di Francesco-Guitter, Bernardi, Chapuy, Fusy,...]
- Theoretical physics: random maps are natural models of random surfaces (discretization of 2D quantum gravity) [Polyakov, Kazakov, Kawai, Ambjørn & Watabiki, ...]
- Probability theory: finding scaling limits for discrete 'combinatorial' random structures (e.g. Donsker's theorem, continuum random trees, statistical physics in 2D and SLE)

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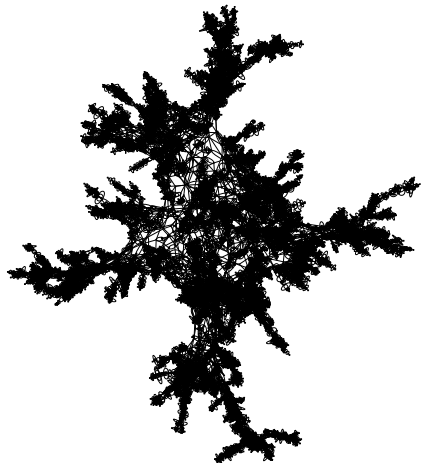
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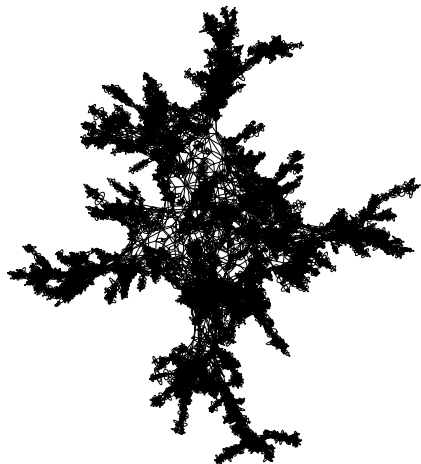
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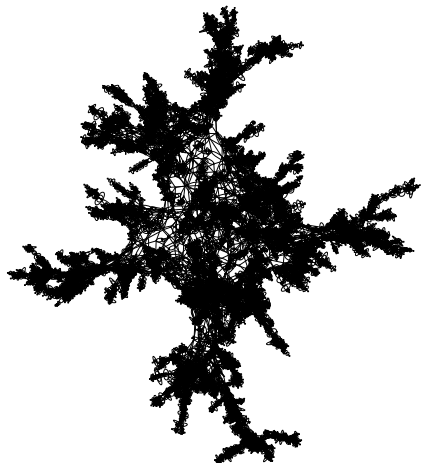
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Topologies on metric spaces

A natural framework for random metric spaces is to compare them using the **Gromov-Hausdorff distance**. If $(X, d), (X', d')$ are compact metric, let

$$d_{\text{GH}}(X, X') = \inf_{\phi, \phi'} \delta_H(\phi(X), \phi'(X')),$$

the infimum being taken over isometric embeddings of X, X' into a common metric space (Z, δ) and δ_H is the usual Hausdorff distance between compact subsets of Z .

Proposition

This endows the space \mathbb{M} of isometry classes of compact spaces with a complete, separable distance.

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Convergence to the Brownian map

Theorem (M. (2011))

There exists a random metric space (S, D^*) , called the **Brownian map**, such that the following convergence in distribution holds

$$(V(Q_n), (8n/9)^{-1/4} d_{Q_n}) \xrightarrow[n \rightarrow \infty]{(d)} (S, D^*)$$

as $n \rightarrow \infty$, for the Gromov-Hausdorff topology.

- This result has been proved independently by Le Gall (2011), via a different approach.
- Before this work, convergence was only known **up to extraction** of subsequences, but the uniqueness of the limiting law was open.
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Some of the previous results on random maps

- Chassaing-Schaeffer (2004) identify $n^{1/4}$ as the proper scaling and compute certain limiting functionals for random quadrangulations. Generalized by Marckert-M. (2007), M. (2008) to the larger class of Boltzmann random maps.
- Marckert-Mokkadem (2006) establish limit theorems (in a sense weaker than Gromov-Hausdorff), and introduce the Brownian map.
- Le Gall (2007) shows tightness for rescaled $2p$ -angulations in the Gromov-Hausdorff topology, and shows that the limiting topology is the same as that of the Brownian map. All subsequential limits have Hausdorff dimension 4, and so does the Brownian map.
- Le Gall-Paulin (2008), and later M. (2008) show that the limiting topology is that of the 2-sphere.
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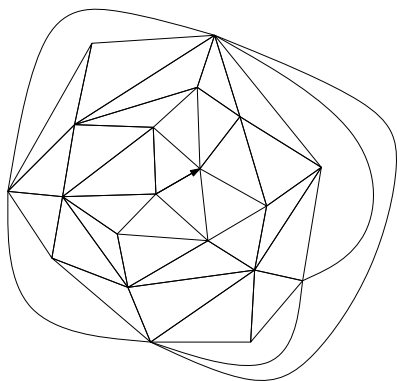
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Other topologies

- Similar results are known when the sphere is replaced by the **genus- g torus**, building on bijective results by Chapuy-Marcus-Schaeffer (2007), Chapuy (2009).
- Bettinelli (2010) shows that subsequential limits of genus- g random bipartite quadrangulations exist, have Hausdorff dimension 4, and have the same topology as the g -torus.
- Similar results are known for **plane quadrangulations with a boundary** (Bettinelli).

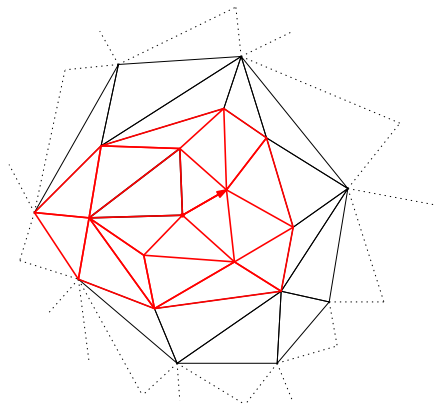
Local limits

- In another direction, Angel-Schramm (2002) and Angel (2002) consider **local limit** results for random triangulations. They construct the so-called **uniform infinite planar triangulation** (UIPT). See also Krikun (2003,2005).
- Followed by work of Chassaing-Durhuus (2006) Ménard (2008), that generalize the bijective approaches in this infinite context.



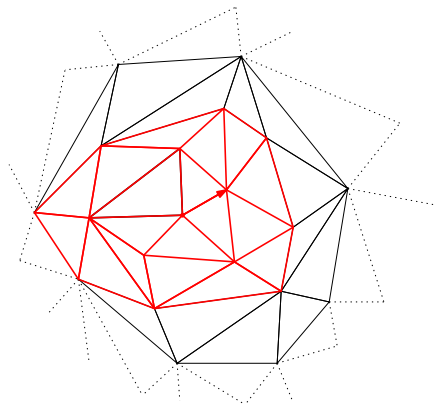
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Geometry at infinity of the UIPQ

Theorem (Curien-Ménard-M. (2012))

- *There exists a sequence of vertices p_1, p_2, \dots such that any infinite geodesic path goes through every but a finite number of the vertices $p_i, i \geq 1$.*
- *Moreover it holds that for every vertices $x, y, z \mapsto d_{\text{gr}}(x, z) - d_{\text{gr}}(y, z)$ takes the same value for every but a finite number of z 's.*

This says that the Uniform Infinite Planar **Quadrangulation** has an **essentially unique infinite geodesic path**, that leads to a single **point at infinity**.



Schaeffer's bijection: coding maps with trees

- Let \mathbf{T}_n be the set of rooted plane trees with n edges, pause
- \mathbb{T}_n be the set of labeled trees (\mathbf{t}, \mathbf{l}) where $\mathbf{l} : V(\mathbf{t}) \rightarrow \mathbb{Z}$ satisfies $\mathbf{l}(\text{root}) = 0$ and

$$|\mathbf{l}(u) - \mathbf{l}(v)| \leq 1, \quad u, v \text{ neighbors.}$$

Theorem

The construction to follow yields a bijection between $\mathbb{T}_n \times \{0, 1\}$ and \mathbb{Q}_n^ , the set of rooted, **pointed** plane quadrangulations with n faces.*

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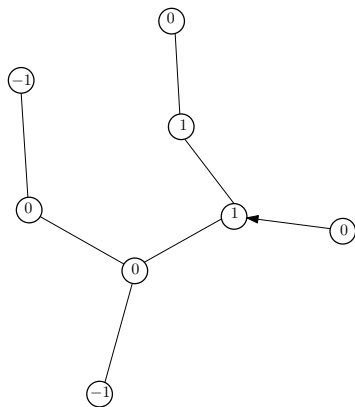
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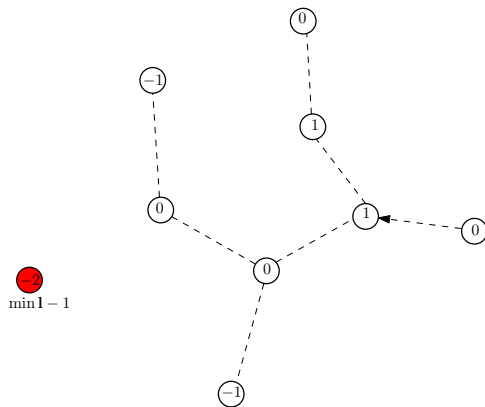
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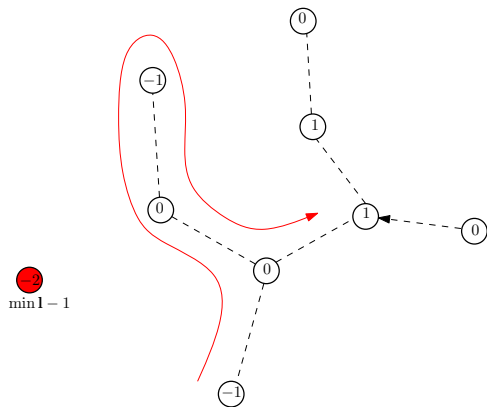
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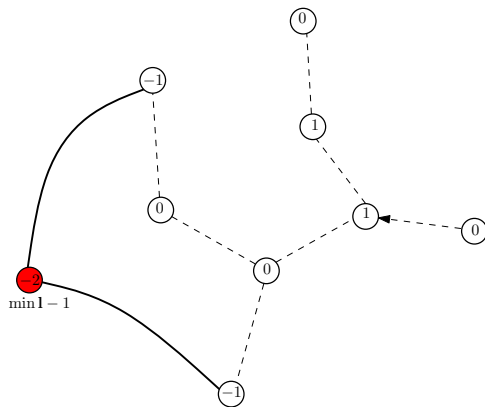
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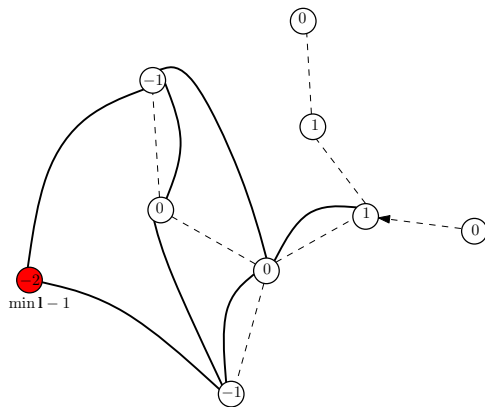
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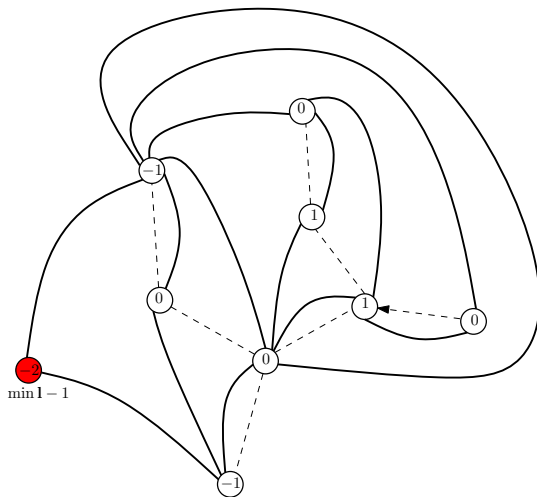
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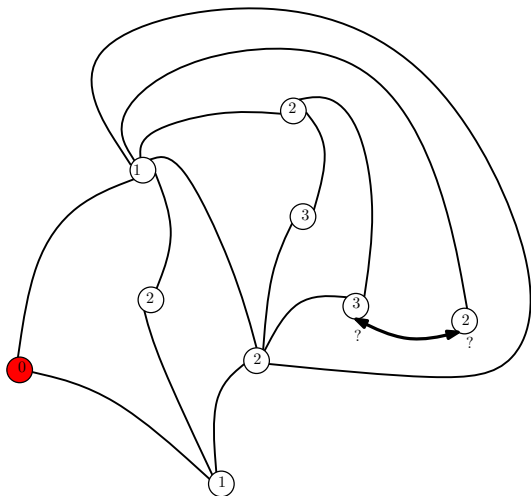
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Note that the labels are geodesic distances in the map. Key formula:

$$d_{\mathbf{q}}(v_*, v) = \mathbf{l}(v) - \inf \mathbf{l} + 1$$

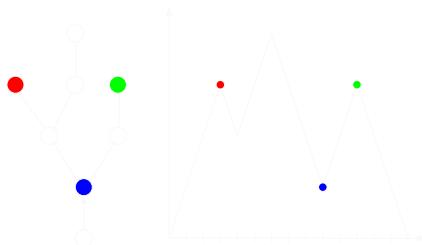
Scaling limits for plane trees: Aldous' CRT

- The **Brownian tree** arises as the scaling limit of many discrete random tree models, e.g. uniform random element T_n of \mathbf{T}_n :

$$(V(T_n), (2n)^{-1/2}d_{T_n}) \rightarrow \mathcal{T},$$

for the Gromov-Hausdorff distance.

- Note that a tree with n edges can be encoded by a walk (Harris encoding): let $u_i, 0 \leq i \leq 2n$ be the $i+1$ -th explored vertex in contour order (started at the root). Let C_i the height of u_i .



The Harris walk is a random walk conditioned to be non-negative and to be at 0 at time $2n$.

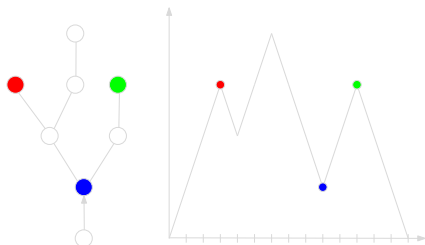
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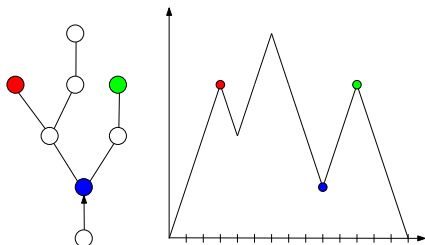
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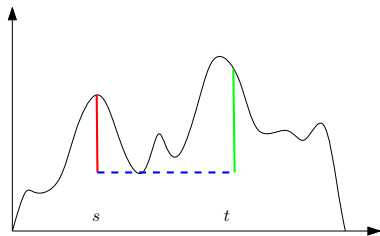
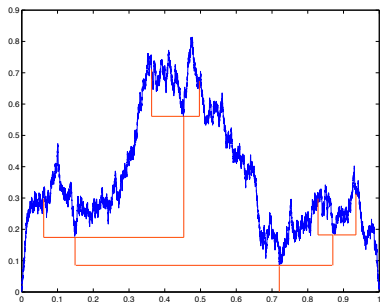
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The Brownian CRT

- Let T_n be uniform in \mathbf{T}_n , and C^n be its contour process. As $n \rightarrow \infty$, the process $((2n)^{-1/2} C^n_{[2nt]}, 0 \leq t \leq 1)$ converges in distribution to a **normalized Brownian excursion** $(e_t, 0 \leq t \leq 1)$.
- Define

$$d_e(s, t) = e_s + e_t - 2 \inf_{s \wedge t \leq u \leq s \vee t} e_u.$$

This is a pseudo-distance on $[0, 1]$. The continuum random tree is the quotient space $\mathcal{T}_e = [0, 1] / \sim_e$, where $s \sim t \iff d_e(s, t) = 0$. It defines an **\mathbb{R} -tree**.

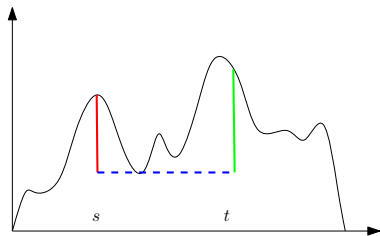
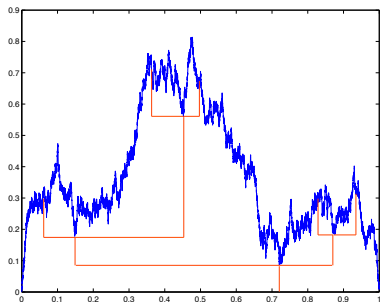


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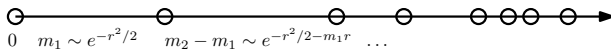
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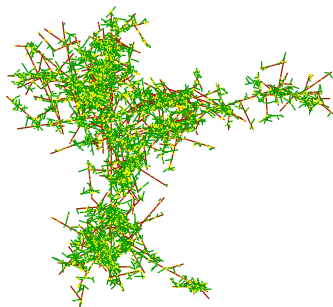
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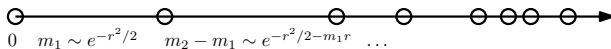
Stick-breaking construction



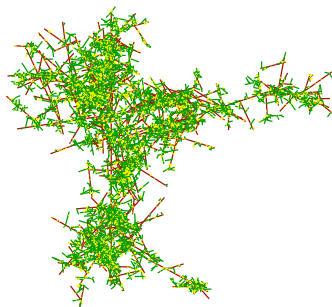
- Build \mathcal{T}_o as an \mathbb{R} -tree, by grafting segments drawn from a Poisson measure on \mathbb{R}_+ with intensity $t dt$ recursively at a uniform location in the tree constructed at each stage.
- Then let \mathcal{T} be (the isometry class of) the metric completion of \mathcal{T}_o . It holds that $\mathcal{T} =_d \mathcal{T}_e$.



Stick-breaking construction



- Build \mathcal{T}_\circ as an \mathbb{R} -tree, by grafting segments drawn from a Poisson measure on \mathbb{R}_+ with intensity $t dt$ recursively at a uniform location in the tree constructed at each stage.
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Brownian labels on the Brownian tree

- Once the tree is build, one can consider a **white noise** supported by the tree, or, equivalently, branching Brownian paths.
- Informally, we let Z be a centered Gaussian process run on \mathcal{T} , with covariance function

$$\text{Cov}(Z_a, Z_b) = d_{\mathcal{T}}(\text{root}, a \wedge b),$$

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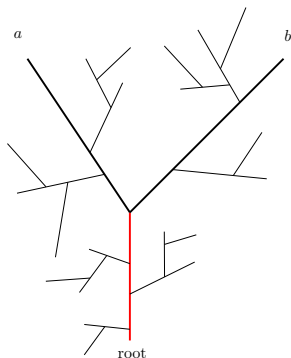
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Convergence of labeled trees

- Let (T^n, ℓ^n) be uniform in \mathbb{T}_n . Then

$$\left(\frac{1}{\sqrt{2n}} T_n, \left(\frac{9}{8n} \right)^{1/4} \ell_n \right) \xrightarrow[n \rightarrow \infty]{(d)} (\mathcal{T}_e, Z),$$

e.g. in the sense of convergence of contour encoding functions.

- We want to apply to (\mathcal{T}_e, Z) a similar construction as Schaeffer's bijection. Assume

$$(T_n = V(Q_n) \setminus \{v_*\}, (8n/9)^{-1/4} d_{Q_n}) \xrightarrow[n \rightarrow \infty]{(d)} (\mathcal{T}_e, D)$$

where D is some random (pseudo-)distance on \mathcal{T}_e (a true distance on $\mathcal{T}_e / \{D = 0\}$).

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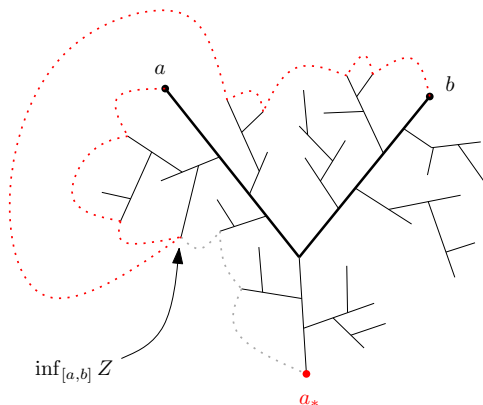
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The Brownian map

- Set

$$D^\circ(a, b) = Z_a + Z_b - 2 \max \left(\min_{[a,b]} Z, \min_{[b,a]} Z \right).$$

This will be an upper-bound for $D(a, b)$, and equal to $D(a, b)$ whenever $a = a_*$ or more generally if a_* , a, b are aligned.



- A straightforward analog of D° gives an upper-bound for the distance in the discrete setting, by concatenating pieces of geodesics from a, b to a_* .

The Brownian map

- The function D° is not a pseudo-distance, so we set

$$D^*(a, b) = \inf \left\{ \sum_{i=1}^{k-1} D^\circ(a_i, a_{i+1}) : a_1 = a, a_k = b \right\},$$

the **largest pseudo-distance** on \mathcal{T}_e that is less than D° .

- The space (S, D^*) where

$$S = \mathcal{T}_e / \{D^* = 0\}$$

is called the Brownian map.

- The method to prove that $(V(Q_n), (8n/9)^{-1/4} d_{Q_n})$ converges in distribution to (S, D^*) is to show that the subsequential limit (\mathcal{T}_e, D) satisfies $D = D^*$.
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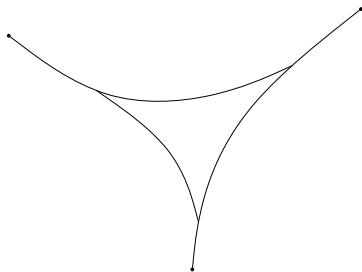
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Idea of proof: Shape of the typical geodesics

- The main idea for the proof is to describe precisely the geodesic γ between two “generic” points x_1, x_2 . More precisely, one must show that it is a patchwork of small segments of **geodesic paths headed toward a_*** (geodesics tend to **stick**).
- So we want to show that Γ , the set of points x on γ from which we can start a geodesic to a_* not meeting γ again, is a **small set**.



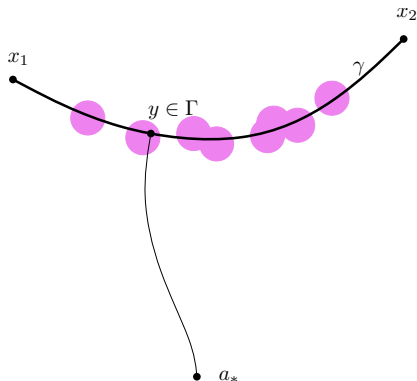
Proposition

There exists $\delta \in (0, 1)$ such that a.s. for every $\varepsilon > 0$, the set Γ can be covered with less than $\varepsilon^{-(1-\delta)}$ D -balls of radius ε . In particular $\dim_{\mathcal{H}}(\Gamma) < 1$.

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Idea of proof: almost equivalence between D and D^*

The previous proposition is enough, once complemented by the following lemma.

Lemma

For every $\alpha \in (0, 1)$, there exists a random $C \in (0, \infty)$ such that $D^(a, b) \leq CD(a, b)^\alpha$ for every $a, b \in \mathcal{T}_e$.*

- This lemma comes from precise **volume estimates** of balls for both metrics D and D^* (Le Gall 2010).
- Covering Γ with at most $\varepsilon^{-(1-\delta)}$ balls for D breaks γ into segments $[a_i, b_i]$, $1 \leq i \leq K$ say, each of which has $D^*(a_i, b_i) = D(a_i, b_i)$.
Then for $\alpha > 1 - \delta$,

$$\begin{aligned} D^*(x_1, x_2) &\leq \sum_{i=1}^K D^*(a_i, b_i) + \varepsilon^{-(1-\delta)} \sup_{D(a,b) \leq 2\varepsilon} D^*(a, b) \\ &\leq \sum_{i=1}^K D(a_i, b_i) + C(2\varepsilon)^{\alpha-1+\delta} \leq D(x_1, x_2) + o(1) \end{aligned}$$

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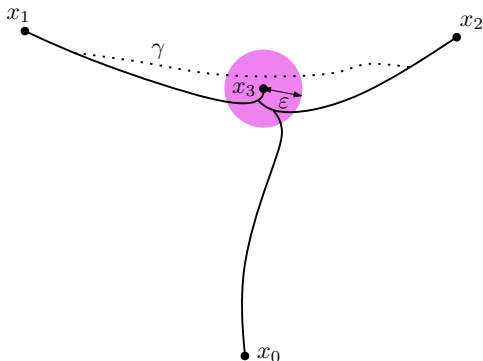
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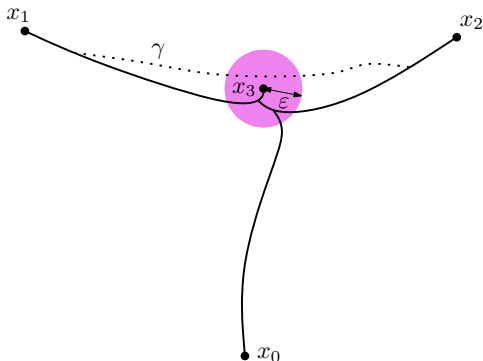


- A method to prove the main proposition is to approach points of Γ by points where geodesics perform a **quick separation**: Evaluate the probability that for 4 randomly chosen points x_0, x_1, x_2, x_3 ,
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The probability of the latter event is bounded above by $C\epsilon^{3+\chi}$ for some $\chi > 0$.

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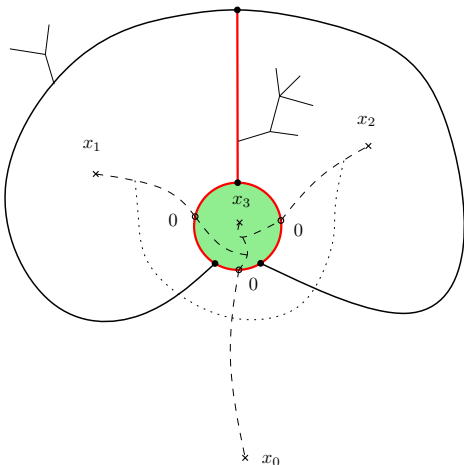


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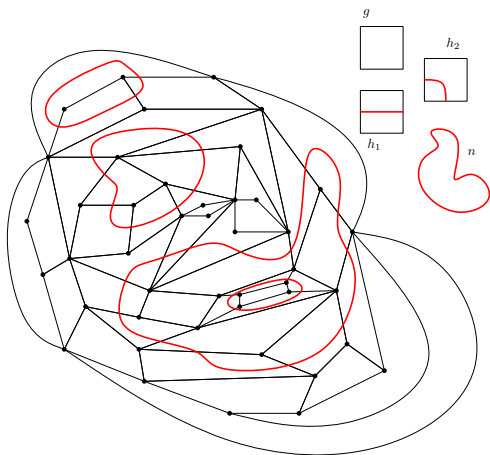
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Idea of proof: Evaluating quickly avoiding geodesic configurations



- We then use a bijection (M. 2009) generalizing Schaeffer's by adding sources at x_0, x_1, x_2, x_3 , measuring geodesic distances simultaneously from these points.
- Count labeled maps as in the picture: Labeled trees are branching out of a 3-regular graph with 4 faces.
- Red=non-negative labels. Green=labels are $\geq -2\varepsilon$ and $\ell(x_3) \leq -\varepsilon$. Dotted path is not a geodesic.

Loop models on random quadrangulations



weight $W_{g,h}^{(n)}(\mathbf{q}) = g^{12} h_1^{12} h_2^{16} n^4$

- Decorate a quadrangulation with “matter”: a configuration of **simple and mutually avoiding loops** on the dual graph (Borot, Bouttier, Guitter).

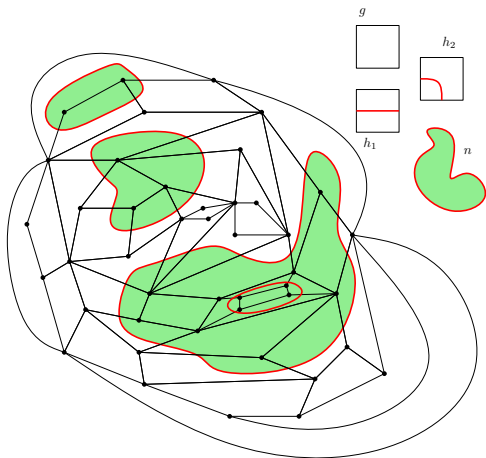
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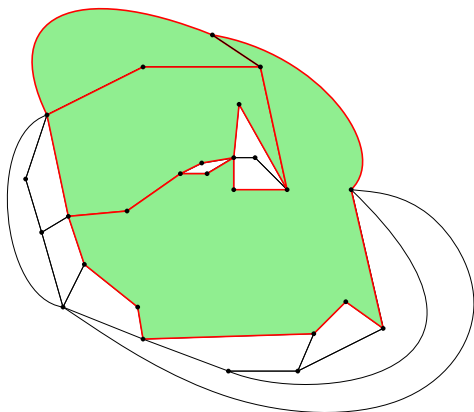
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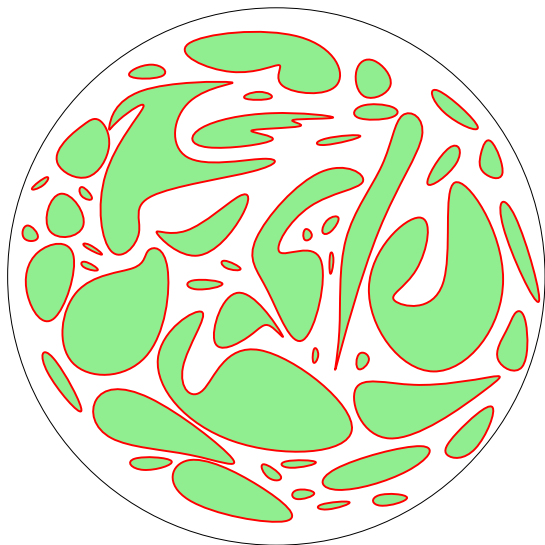
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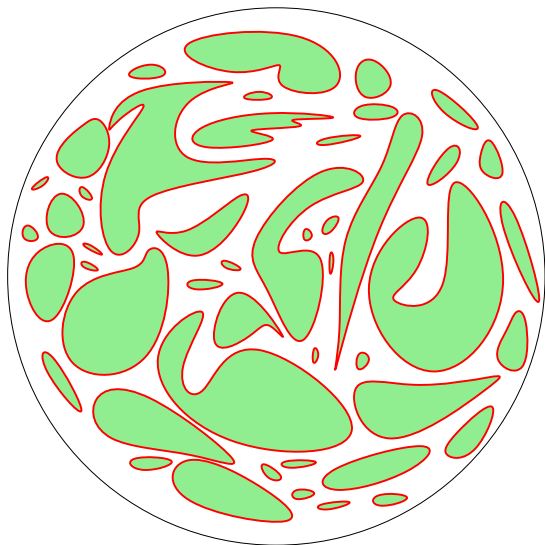
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Limits of maps with large faces: Stable maps



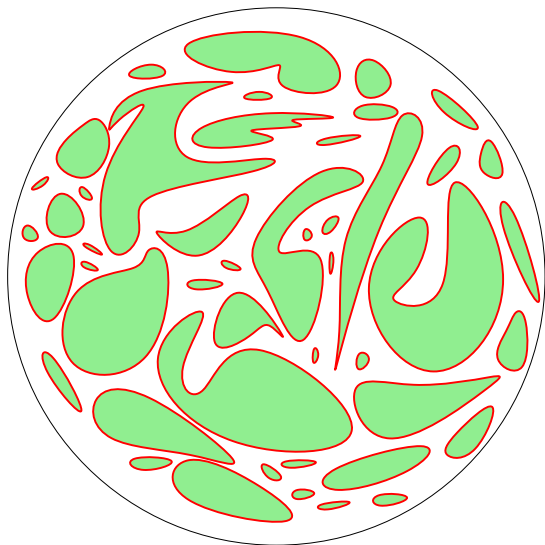
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