

# Equivalent boundary conditions for Monge-Ampère solutions of the L2 Optimal Transportation problem

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<http://arxiv.org/pdf/1208.4870.pdf>

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A - Monge-Ampère solutions of the L2 Optimal Transportation problem

B - State Constraint reformulation

C - The viscosity solutions framework

D - Numerical Results

## $L^2$ Optimal Transportation

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- **Source/Target Data** :  $d\rho_X(x)(= \rho_X(x) dx)$ ,  $d\rho_Y(y)(= \rho_Y(y) dy)$   
s.t.  $X, Y \subset \mathbb{R}^2$ ,  $\rho_{X,Y} > 0$ ,  $\int_X \rho_X(x) dx = \int_Y \rho_Y(y) dy$ ,  
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- Boundary conditions are replaced by **state constraints** :

$$\nabla\psi(\bar{X}) \subset \bar{Y}.$$

This is called the "Second Boundary Value problem" (Classical solution studied in Delanoë, Urbas ..) .

## OUR GOAL :

Solve with a PDE discretization method

$$(MA) \quad \langle u \rangle + \det(D^2 u(x)) \rho_Y(\nabla u(x)) = \rho_X(x), \text{ on } X$$

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## WHAT DO WE NEED TO PURSUE THIS IDEA :

- (BV2) is non standard/non local  $\rightarrow$  We introduce a much simpler reformulation (HJ) in section B.
- Brenier/Aleksandrov solutions are too weak. Give a meaning to solutions of (MA-HJ) for which discretizations with "good" (convergence, fast solver) properties are available  $\rightarrow$  Viscosity solutions setting in section C.

## (BV2) numerical state of the art : specific geometries

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- The periodic setting : use the "displacement" change of variable  $u \rightarrow v = u - \frac{x^2}{2}$ .

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- "Face to Face" Neuman type BCs : ex. square to square :  
 $u_{x_1}(\pm 1, \cdot) = \pm 1, \quad u_{x_2}(\cdot, \pm 1) = \pm 1.$

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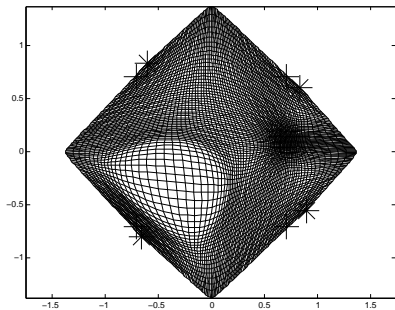
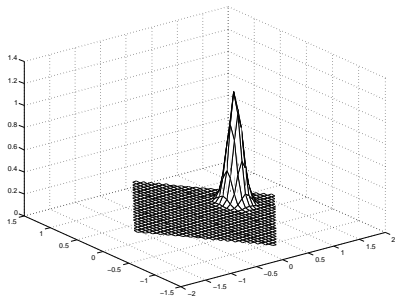
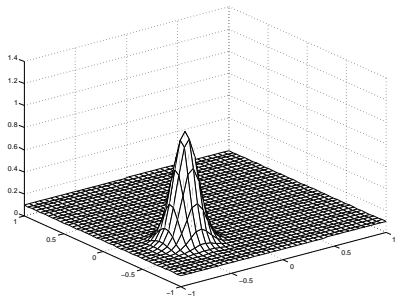
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- BUT it assumes a priori knowledge on the boundary to boundary map : illustration on a square to rhombus map.



## Equivalent Hamilton-Jacobi equation on the boundary

---

- Use the ("Y defining function" ... Delanoë, Urbas : Let  $H(y)$  convex such that :

$$\begin{cases} H(y) < 0, & y \in Y \\ H(y) = 0, & y \in \partial Y \\ H(y) > 0, & y \in Y^c \end{cases}$$

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- We use the signed Euclidean distance to  $\partial Y$  :

$$H(y) = \begin{cases} +\text{dist}(y, \partial Y), & y \in \bar{Y}, \\ -\text{dist}(y, \partial Y), & y \in Y^c. \end{cases}$$

## $H$ properties and usage

---

- **Obliqueness** : Let  $y = \nabla u(x)$ ,  $x, y \in \partial X, \partial Y$  and  $n_x, n_y$  then exterior normals at  $x, y$ . Using  $H(\nabla u) = 0$  on  $\partial X$  (by definition) and  $n_y = \nabla H(y)$  (by construction) we get

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- Dual formulation of  $H$  : using the supporting hyperplane theorem

$$\begin{cases} H(y) = \sup_{\|n\|=1} \{n \cdot y - H^*(n)\} \\ H^*(n) = \sup_{y_0 \in \partial Y} \{n \cdot y_0\} \end{cases}$$

- On the boundary the sup is attained for  $n_y$  the exterior normal to  $Y$  at  $y = \nabla u(x)$   
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$$\approx \sup_{\{\|n\|=1, n \cdot n_x > 0\}} \left\{ \frac{u(x) - u(x - nh)}{h} - H^*(n) \right\}.$$

Using the discontinuous viscosity solution framework  
(Lions, Perthame, Barles, Souganidis ...)

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**Theorem :** Assuming  $X, Y$  convex,  $\rho_{X,Y} > 0$  and  $\rho_Y$  Lipschitz then  $(MA - HJ)$  has a unique convex viscosity solution (using results of Barles, Perthame, Souganidis ...).



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- $(OBL)$  is an important ingredient to get uniqueness (Non-Linear Neuman BCs, Barles, 1993).

## Discretization and Solver

---

$$MA(u) = \begin{cases} \det(D^2u) - \frac{\rho_X}{\rho_Y(\nabla u)} - \langle u \rangle, & \text{sur } X \\ \sup_{\{\|n\|=1, n \cdot n_x > 0\}} \{\nabla u \cdot n - H^*(n)\}, & \text{sur } \partial X \end{cases}$$

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- : –) Can use Newton (convergent, fast) on the non-linear system :  $u^{k+1} = u^k - \alpha(\nabla MA[u^k])^{-1} MA[u^k]$ ,  $(\nabla MA[u^k]) > 0$ .

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- : –( Accuracy is limited by the stencil width which cannot be arbitrarily increased in practice. (Hybrid FD/Wide Stencil discretization partly fix this problem).

Reconstruction of geodesics  $x \mapsto (1 - \frac{t}{T})x + \frac{t}{T}\nabla u(x)$ ,  $t \in ]0, T[$

## Ellipse to Ellipse, constant density densité

---

$N_X$	Max. error					Iterations	Time (s)
	$N_Y$						
	32	64	128	256	512		
32	0.0691	0.0667	0.0662	0.0660	0.0660	4	0.2
64	0.0306	0.0284	0.0279	0.0277	0.0277	4	0.5
128	0.0203	0.0176	0.0169	0.0167	0.0167	4	1.7
256	0.0127	0.0096	0.0088	0.0086	0.0088	5	10.1
512	0.0086	0.0056	0.0047	0.0045	0.0047	5	52.2

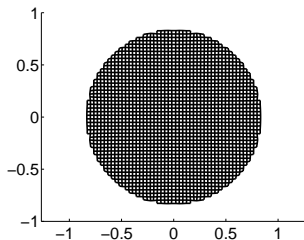
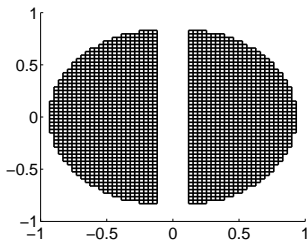
**Table:** Exact gradient error # Newton itération de Newton, timing for  $N_y = 512$ . Wide-Stencil : 9pts



Illustration 2D  $(x \mapsto (1 - \frac{t}{T})x + \frac{t}{T}\nabla\phi^*(x), t \in ]0, T[)$

Discussion on Caffarelli counter example :  
 Constant density - one non convex domain

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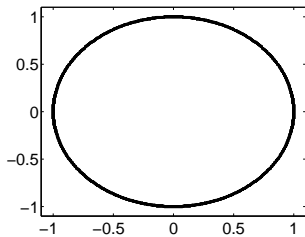
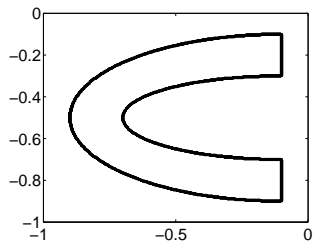
← : Brenier (not Aleksandrov) Solution.

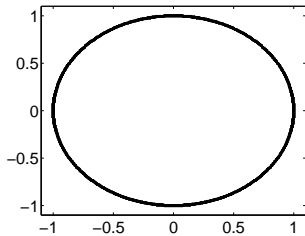
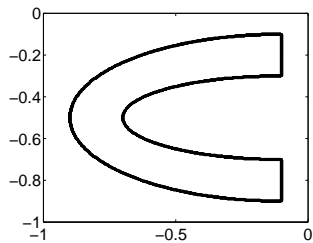
→ : Viscosity solution (non strictly convex) de viscosité. We can do it :-)

## Inverse Caffarelli example

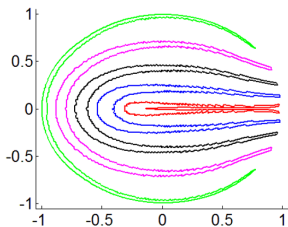
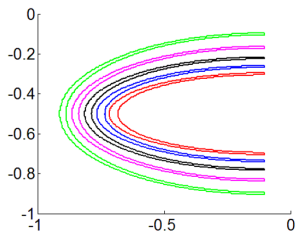
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128	0.0092	0.0093	0.0092	0.0092	0.0092	3	1.3
256	0.0047	0.0036	0.0036	0.0036	0.0036	4	8.3
512	0.0049	0.0040	0.0034	0.0033	0.0033	5	51.7

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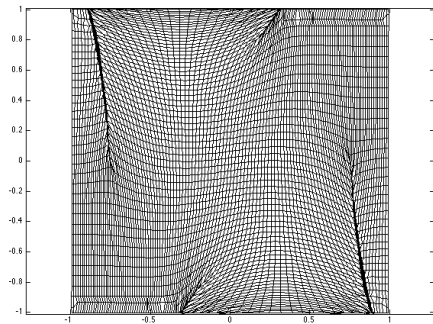
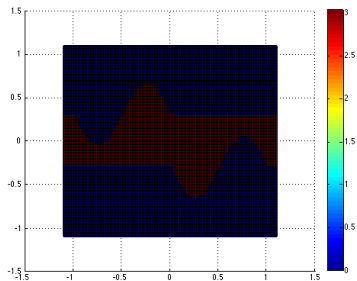
Non convex  $\rho_X > 0$  support

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## Markers displacements



## Toy S.-G. case



THANK YOU for your attention.

<https://team.inria.fr/mokaplan/>