Knots and surfaces in 3-dimensional space

Jennifer Schultens

March 13, 2012

Jennifer Schultens Knots and surfaces in 3-dimensional space

Definition

A *knot* is a smooth embedding of the circle into 3-dimensional space.

э



Figure: A knot

æ

∃ >

< E

• Fact I: The mathematical study of knots includes several different branches, each with a very different "flavour": algebraic, geometric, ...

< ∃ >

- Fact I: The mathematical study of knots includes several different branches, each with a very different "flavour": algebraic, geometric, ...
- Fact II: Knots relate to nature, for instance via the tangles in long strands of DNA.

Definition

Given a knot K in 3-dimensional space, an orientable (2-sided) surface S that has boundary K is called a *spanning surface*.



Figure: A Seifert surface



(Seifert) Every knot admits a spanning surface.

Jennifer Schultens Knots and surfaces in 3-dimensional space

æ

-

(Seifert) Every knot admits a spanning surface.

- ∢ ≣ ▶

(Seifert) Every knot admits a spanning surface.

Seifert's algorithm

- Step 1: Consider a projection of the knot and give it an orientation.
- Step 2: Resolve each crossing to obtain Seifert circles.

(Seifert) Every knot admits a spanning surface.

Seifert's algorithm

- Step 1: Consider a projection of the knot and give it an orientation.
- Step 2: Resolve each crossing to obtain Seifert circles.
- Step 3: The Seifert circles bound disks with a natural orientation.

(Seifert) Every knot admits a spanning surface.

Seifert's algorithm

- Step 1: Consider a projection of the knot and give it an orientation.
- Step 2: Resolve each crossing to obtain Seifert circles.
- Step 3: The Seifert circles bound disks with a natural orientation.
- Step 4: Connect disks via bands to obtain a spanning surface.

For a surface S constructed via Seifert's algorithm, the Euler characteristic of S, denoted by $\chi(S)$, can be computed as

$$\chi(S) = \# disks - \# bands$$

Definition

A *Seifert surface* for a knot K is a spanning surface of maximal Euler characteristic.

Seifert Surfaces (Results of Julian Eisner)

 Fact I: Many knots K in S³ admit non-isotopic Seifert surfaces. (Eisner 1977)

- Fact I: Many knots K in S³ admit non-isotopic Seifert surfaces. (Eisner 1977)
- Fact II: Many knots K in S³ admit disjoint non-isotopic Seifert surfaces. (Eisner 1977)



Figure: Connect sum of knots

Seifert Surfaces



Figure: Connect sum of knots

Seifert Surfaces



Figure: Schematic

Jennifer Schultens Knots and surfaces in 3-dimensional space

э

Definition

The vertices of the Kakimizu complex Kak(K) of a knot K in \mathbb{S}^3 are given by the isotopy classes of minimal genus Seifert surfaces for K.

Definition

The vertices of the Kakimizu complex Kak(K) of a knot K in \mathbb{S}^3 are given by the isotopy classes of minimal genus Seifert surfaces for K.

The *n*-simplices of the Kakimizu complex of K, for n > 1, are given by *n*-tuples of vertices that admit representatives that are pairwise disjoint.

• Example I: Fibered knots have trivial Kakimizu complexes.

- Example I: Fibered knots have trivial Kakimizu complexes.
- Example II: Hyperbolic knots have finite Kakimizu complexes.

(Scharlemann-Thompson) The Kakimizu complex of a knot is connected.

Not stated in these terms.

30.00

(Kakimizu) Suppose that K_1, K_2 are knots with unique minimal genus Seifert surfaces (up to isotopy). Then the Kakimizu complex of $K = K_1 \# K_2$ is a bi-infinite ray.

More recently, Kakimizu computed the Kakimizu complexes for all prime knots with up to 10 crossings.

(Banks) Suppose that K_1, K_2 are knots, then the Kakimizu complex of $K_1 \# K_2$ is the product of three complexes: The Kakimizu complex of K_1 , the Kakimizu complex of K_2 and the complex that has underlying space **R** and vertices at the integers.

(Banks) There exist knots with locally infinite Kakimizu complex.

Theorem

(Banks) A knot has locally infinite Kakimizu complex only if it is a satellite of either a torus knot, a cable knot or a connected sum, with winding number 0.

Jessica Banks' results



Figure: An essential torus in a knot complement

(S 2007) The Kakimizu complex of a knot K is a flag complex.

3 N

(S 2007) The Kakimizu complex of a knot K is a flag complex.

Theorem

(Kapovich 2009) Let M be a Riemannian 3-manifold with smooth strictly convex boundary, together with a compact family \mathcal{J} of smooth curves on ∂M . Let $f_i : (S_i, \partial S_i) \to (M, \mathcal{J}), i = 1, ..., n$ be incompressible surfaces which are pairwise non-isotopic and pairwise disjoint. Let $g_i : (S_i, \partial S_i) \to (M, \mathcal{J}), i = 1, ..., n$ be relative area minimizers in the proper isotopy classes of f_i , i = 1, ..., n. Then $g_1(S_1), ..., g_n(S_n)$ are also pairwise disjoint.

Contractibility of the Kakimizu complex

Theorem

(Przytycki-S 2010) The Kakimizu complex of a knot is contractible.

< ∃ >

Implicit in Kakimizu's work is a projection map (coming from considerations involving covering spaces and Kakimizu's formulation of the distance on the Kakimizu complex) that, given two vertices v, w, produces a vertex $\pi_v(w)$ that is one step closer to v than w.

$$d(v,\pi_v(w))=d(v,w)-1$$

(Przytycki-S 2010) The Kakimizu complex of a knot is contractible.

Idea of proof: Choose a vertex v in Kak(K) and prove that the projection map onto v is a contraction of Kak(K).

Challenge: Make sure that the projection map behaves well on links of vertices.

(Scharlemann-Thompson) The Kakimizu complex of a knot is connected.

Idea of new proof: Given any two vertices v, w, we construct a path