

NOTETAKER CHECKLIST FORM

(Complete one for each talk.)

Name: Leanne Merrill Email/Phone: leanne m@uoregon.edu / 518 461 7614
Speaker's Name: Soren Galatius
Talk Title: Stable homology of moduli spaces of manifolds.
Date: 1, 31, 14 Time: 2:00 am / pm (circle one)

List 6-12 key words for the talk: Moduli spaces, scanning map, diffeomorphism group, configuration space, group completion, loop spaces.

Please summarize the lecture in 5 or fewer sentences: This talk introduced the idea of stable homology of groups and manifolds. It worked out some simple examples of scanning maps and gave a general definition. It then showed a typical proof that these maps induce isomorphism in a stable range in homology by introducing monoidal structures and group completion. Finally, it gave a higher-dimensional analog.

CHECK LIST

(This is NOT optional, we will not pay for incomplete forms)

- Introduce yourself to the speaker prior to the talk. Tell them that you will be the note taker, and that you will need to make copies of their notes and materials, if any.
- Obtain ALL presentation materials from speaker. This can be done before the talk is to begin or after the talk; please make arrangements with the speaker as to when you can do this. You may scan and send materials as a .pdf to yourself using the scanner on the 3rd floor.
 - **Computer Presentations:** Obtain a copy of their presentation
 - **Overhead:** Obtain a copy or use the originals and scan them
 - **Blackboard:** Take blackboard notes in black or blue **PEN**. We will **NOT** accept notes in pencil or in colored ink other than black or blue.
 - **Handouts:** Obtain copies of and scan all handouts
- For each talk, all materials must be saved in a single .pdf and named according to the naming convention on the "Materials Received" check list. To do this, compile all materials for a specific talk into one stack with this completed sheet on top and insert face up into the tray on the top of the scanner. Proceed to scan and email the file to yourself. Do this for the materials from each talk.
- When you have emailed all files to yourself, please save and re-name each file according to the naming convention listed below the talk title on the "Materials Received" check list.
(YYYY.MM.DD.TIME.SpeakerLastName)
- Email the re-named files to notes@msri.org with the workshop name and your name in the subject line.

Soren Galatius - Stable Homology of moduli spaces of manifolds

(i)
1/31/14

Moduli spaces: come in families indexed by \mathbb{N} .

$\mathcal{M}_n \quad n \in \mathbb{N}$:

- Ex:
- $B \Sigma_n$
 - $B \text{Braid}_n$
 - $B GL_n(\mathbb{Z})$
 - $B \text{Aut}(F_n)$
 - $B \text{Diff}(\Sigma_{n,1})$
 - ⋮
- ↙ a bit outside these methods.
- Exhibit homological stability in a certain range.

Stable Homology:

i) Often given by:

(iterated) loop spaces

ii) Often a map $\mathcal{M}_n \rightarrow \Omega(?)$ inducing an isomorphism in this stable range, called a "scanning" map.

Other results:

- $B Br_n \rightarrow \Omega^2 S^2$ Cohen, Segal.
- $B \Sigma_n \rightarrow \Omega^\infty S^0$ Barratt - Priddy - Quillen - Segal
- $B \text{Diff}(\Sigma_{g,1}) \rightarrow \Omega^\infty(??)$ Tillman ~ '95.

Madsen - Weiss; '02:

$B \text{Diff}(\Sigma_{g,1}) \rightarrow \Omega^\infty(\text{MTSO}(2))$

also, $\mathbb{C}P^\infty = \text{MTSO}(2)$ ~~is~~ Spectrum whose K^{th} space is $\frac{SO(n)}{SO(2) \times SO(n-2)} \wedge S^{n-2}$

②

A similar result: (G. - Randal-Williams):

$$BDiff(D^{2n} \# g(S^n \times S^n)) \rightarrow \Omega^\infty(BO(2n)[n+1, \infty))^{-\gamma}$$

for $n > 2$.

How are these maps defined?

Scanning map:

example: $BBr_n \longrightarrow \Omega^2 S^2$

\parallel

$$C_n(\mathbb{R}^2)$$

Configuration space. \nearrow

Let $A \subseteq \mathbb{R}^2$,
 $|A| = n$.

This is a point in $C_n(\mathbb{R}^2)$. Want α :

$$\alpha(A) \in \Omega^2 S^2.$$

How to define α ?

Take $p \in \mathbb{R}^2$. Consider $(A - p) \cap B(0, \epsilon) \subseteq B(0, \epsilon)$.

Cardinality 0 or 1.

$$\text{So, } = B(0, \epsilon) \cup \{\infty\}$$

(one pt compactif.)

so consider a map from

$$\left\{ \begin{array}{l} \text{one pt} \\ \text{compactif.} \\ \text{of } \mathbb{R}^2 \end{array} \right\} \longrightarrow \left\{ \begin{array}{l} \text{one pt} \\ \text{compactif.} \\ \text{of } B(0, \epsilon) \end{array} \right\}$$

which sends $\infty \mapsto \infty$, and define

$$\alpha(A) \in \Omega^2 S^2 \text{ via this map.}$$

Instead, could take: $\mathcal{Q} =$ all discrete subsets
 $Q \subseteq \mathbb{R}^2$.

topologize: Q' near Q if it's a small
 perturbation inside a large ball.

Then, up to homotopy, the map can be described:

$$C_n(\mathbb{R}^2) \longrightarrow \Omega^2 \mathcal{Q}$$

$$A \longmapsto \left(\begin{array}{ccc} p \in \mathbb{R}^2 & \longmapsto & A - p \\ \infty & \longmapsto & \infty \end{array} \right)$$

and $S^2 \xrightarrow{\cong} \mathcal{H}$ is a homotopy equivalence.

- The same idea works for Σ_n , replacing \mathbb{R}^2 by \mathbb{R}^∞
- with small modifications, works for diffeomorphism groups of manifolds.

On to higher dimensional manifolds:

Oriented Surfaces

Σ a closed, orientable surface.

orientation-preserving diffeos. \rightarrow

$$B\text{Diff}^+(\Sigma) := \frac{\text{Emb}(\Sigma, \mathbb{R}^\infty) \times \text{Or}(\Sigma)}{\text{Diff}(\Sigma)}.$$

Could also have written (for consistency)

$$C_\Sigma(\mathbb{R}^\infty) = \{ Q \subset \mathbb{R}^\infty \mid Q \cong \Sigma \}.$$

④

Approximated by $C_\Sigma(\mathbb{R}^n) = \frac{\text{Emb}(\Sigma, \mathbb{R}^n) \sim \text{Or}(\Sigma)}{\text{Diff}(\Sigma)}$

The scanning map is:

$$C_\Sigma(\mathbb{R}^n) \xrightarrow{\alpha} \Omega^n$$

$$\begin{matrix} \mathbb{Q} \\ \uparrow \\ \mathbb{R}^n \end{matrix} \longmapsto \left(\begin{array}{l} p \in \mathbb{R}^n \longmapsto \overbrace{(\mathbb{Q}-p) \cap B(0, \varepsilon)}^{\text{empty or an affine subspace}} \\ \infty \longmapsto \phi \end{array} \right)$$

Then:

$$\frac{SO(n)}{SO(2)} \times_{SO(n-2)} \mathbb{R}^{n-2} = \text{space of affine 2-dimensional oriented subspaces of } \mathbb{R}^n$$

and, one point compactified, it is:

$$\frac{SO(n)}{SO(2)^+} \wedge_{SO(n-2)} S^{n-2} = \text{space of affine 2-dimensional oriented subspaces of } \mathbb{R}^n \cup \{\infty\}.$$

$n \rightarrow \infty$:

$$B\text{Diff}(\Sigma_{g,1}) \rightarrow B\text{Diff}^+(\Sigma_g) \rightarrow \Omega^\infty \text{MTSO}(2).$$

The above is due to Madsen-Weiss.

F. Cantero: extended it for $5 \leq n < \infty$.

Wahl: unoriented surfaces.

Nariman: Diff^S as discrete group.

Galatius: $\text{Aut}(F_n)$.

How does one prove these maps are isomorphisms ^⑤
 in a certain range? Reformulate slightly:

For example,

$$BBr_n \longrightarrow \Omega_n^2 S^2 \text{ iso. in } H_* , * \leq \frac{n}{2}$$

$$\begin{array}{c} \updownarrow \\ \leftarrow H_*\text{-stable} \end{array}$$

often a better way to prove these statements.

where $Br_\infty = \text{colim} (Br_n \rightarrow Br_{n+1} \rightarrow \dots)$.

For example: $\hookrightarrow \text{hocolim}_{g \rightarrow \infty} B \text{Diff}(D^{2n} \# g(S^n \times S^n))$

$$\longrightarrow \Omega_0^\infty BO(2n)[n+1, \infty)^{-\delta}$$

~~isomorphism~~ iso. in H_* for all n .

Monoid structures:

eg: $M = \coprod_{n \geq 0} B Br_n$

have a monoid structure given by putting braids next to one another:

$$Br_n \times Br_m \longrightarrow Br_{n+m}$$

$$\left(\begin{array}{c} \diagdown \quad \diagup \\ \diagup \quad \diagdown \end{array} , \begin{array}{c} \diagdown \quad \diagup \\ \diagdown \quad \diagup \end{array} \right) \longmapsto \begin{array}{c} \diagdown \quad \diagup \\ \diagdown \quad \diagup \end{array}$$

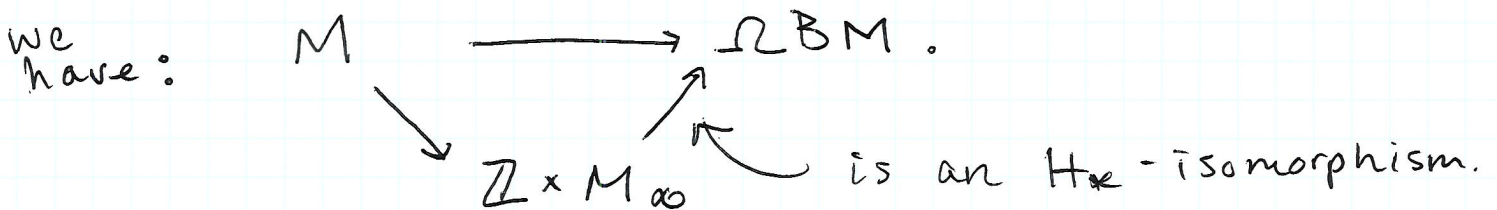
gives a strictly associative monoid structure $M \times M \rightarrow M$.
 can do similar things for $\coprod B \Sigma_n, \coprod B \text{Diff}(\Sigma_{g,n})$

"Group-Completion" Theorem: (Quillen, McDuff-Segal).

Let $M = \coprod_{n \geq 0} M_n$ be a topological monoid, $\pi_0 = \mathbb{N}_0$,

which is homotopy commutative.

Then if $M_\infty = \text{hocolim}(M_0 \xrightarrow{\cdot m} M_1 \xrightarrow{\cdot m} M_2 \rightarrow \dots)$



This implies:

$$\begin{array}{ccc}
 \mathbb{Z} \times BBr_\infty & \xrightarrow{H_*\text{-iso.}} & \Omega^2 S^2 \\
 \hat{=} & & \\
 B(\coprod BBr_n) & \xrightarrow{\simeq} & \Omega S^2
 \end{array}$$

These are general techniques that work in most of the previous examples.

How to prove the homotopy equivalence above?

Prove both sides $\simeq \left\{ A \in \mathcal{U} \mid A \in \mathbb{R} \times (-1, 1) \right\}$.

In general: (moduli spaces of higher dimensional manifolds)

- instead of a monoid, you have a category.
- often get "too big" moduli spaces
eg. non-connected 2-manifolds.
- Need to get ride of those.

Point: The right hand side is (a priori) easier to understand than the left hand side.

E.g. $H^*(B\text{Diff}(D^6 \# g S^3 \times S^3); \mathbb{Q})$
 independent of g for $* \leq \frac{g-3}{2}$.

Theorem:

$$\mathbb{Q}[\kappa_c \mid c \in B] \longrightarrow H^*(B\text{Diff}(D^6 \# g S^3 \times S^3); \mathbb{Q})$$

is an isomorphism for

$$* \leq \frac{g-3}{2}$$

This indexing set is:

$$c \in B = \left\{ p_i^i e^j p_2^k \mid \begin{matrix} i, j, k \geq 0 \\ |c| \geq 6 \end{matrix} \right\}$$

$$|\kappa_c| = |c| - 6$$

where p are Pontryagin classes

and e are Euler classes.

The kappa classes are:

$$W^6 \rightarrow E \rightarrow B$$

$c(T_x E) \in H^*(E)$

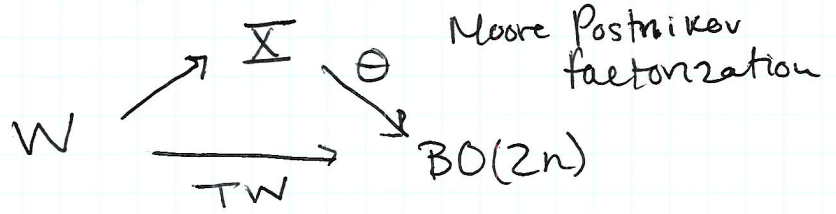
What if manifold is not parallelizable?

Can look at:

$$M^\theta \cong \text{Borel}(W^{2n} \# g S^n \times S^n) \rightarrow \Omega^\infty \Sigma^{-\theta}$$

where:

perform:
"space of θ -structures"
Dirf
construction.



What about manifolds with ~~exotic~~ exotic bdr?;

Doesn't matter; only depends on tangential ~~structure~~
 n -skeleton.