#### **RIGIDITY OF HIGHER RANK DIAGONALIZABLE ACTIONS**

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### 1. FIRST EXAMPLES

1.1.  $\mathbb{T} = \mathbb{R}/\mathbb{Z}$ . We can look at multiplication by  $p \in \mathbb{Z}$ ,  $p \times \curvearrowright \mathbb{T}$ . If p = 3, we get that the middle third Cantor set is a  $\times 3$  invariant set, modulo integers. Thus, there are many different types of orbits, closed invariant sets, and invariant measures.

1.2.  $\mathbb{T}^2$ . Consider the action  $A = \begin{pmatrix} 0 & 1 \\ 1 & 1 \end{pmatrix} : \mathbb{T}^2 \to \mathbb{T}^2$ . Adler-Weiss gave a complete description of this dynamical system. We have a covering of  $\mathbb{T}^2$  by a shift space in  $\{0,1\}^{\mathbb{Z}}$ . Again we get that there are many different types of orbits, closed invariant sets, and invariant measures

1.3.  $X_2 = \mathbf{SL}(2, \mathbb{R})/\mathbf{SL}(2, \mathbb{Z})$ . Where the action of  $\mathbf{SL}(2, \mathbb{Z})$  is by Möbius transformations, that is  $\begin{pmatrix} a & b \\ c & d \end{pmatrix} z = \frac{az+b}{cz+d}$ .



FIGURE 1. The space  $X_2$  with identifications

Consider the action of the geodesic flow  $A = \begin{pmatrix} e^2 \\ e^{-t} \end{pmatrix}$  by left multiplication on  $X_2$ . There is a relation between the continued fraction expansion and the geodesic flow. Consider a geodesic with right endpoint  $\alpha \in \mathbb{R}$ , shifting the geodesic gets us another geodesic with right endpoint at  $\alpha - 1$ , eventually we will reach  $\{\alpha\}$ , the fractional part of  $\alpha$ , see Figure 2.

### 2. Higher rank

**Theorem 1** (Furstenberg, '67). Consider the actions  $2\times, 3\times \curvearrowright \mathbb{T}$ , and  $\alpha \in \mathbb{T}$ . We have

$$S = \overline{\{2^n 3^m \alpha\}} = \begin{cases} finite & if \ \alpha \in \mathbb{Q} \\ \mathbb{T} & otherwise \end{cases}$$

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FIGURE 2. Relation between geodesic flow and continued fractions

**Theorem 2** (Berend). Consider the actions  $A, B : \mathbb{T}^k \to \mathbb{T}^k$ . Assume these actions are totally irreducible, hyperbolic, and faithfully  $\mathbb{Z}^2$ . Take an A, B-invariant set S, then either  $|S| < \infty$  or  $S = \mathbb{T}$ .

# 3. Homogeneous Setting

We would like to get a higher rank picture so that we have 2 multiplicatively independent actions. Our space is  $X_3 = SL(3, \mathbb{R})/SL(3, \mathbb{Z})$  where  $SL(3, \mathbb{Z}) = \{g\mathbb{Z}^3 \mid g \in SL(3, \mathbb{R}) \text{ and we consider the action of } \}$ 

$$A = \left\{ \begin{pmatrix} e^{t_1} & & \\ & e^{t_2} & \\ & & e^{t^3} \end{pmatrix} \mid t_1 + t_2 + t_3 = 0 \right\}$$

**Conjecture 1** (Margulis). If  $Ax \subseteq X_3$  is bounded for some  $x \in X_3$ , then Ax is periodic.

This is somehow the correct analog for the theorems of Furstenberg and Berend in this situation. It also gives the following:

Conjecture 2 (Littlewood's Conjecture).

$$\liminf_{n \to \infty} n |||n\alpha_1||| \cdot ||||n\alpha_2||| = 0$$

## 4. Measure Rigidity

**Theorem 3** (Rudolph '90). Suppose  $\mu$  is  $\times 2, \times 3$ -invariant and ergodic, and  $h_{\mu}(\times 2^m 3^n) > 0$  then  $\mu = m =$  Lebesgue.

Generalizations:

- Katok-Saptzier:  $\mathbb{T}^k$  and  $G/\Gamma$
- Kalinin-Katok:  $A, B : \mathbb{T}^3$ .

**Theorem 4** (Einsiedler-Lindenstrauss, '04). Consider the actions of  $A, B : \mathbb{T}^k \to \mathbb{T}^k$ , totally irreducible, hyperbolic, and faithful. Then if  $h_{\mu}(A^n B^m) > 0$  and  $\mu$  invariant and ergodic, then  $\mu = m_{\mathbb{T}^k}$ .

**Theorem 5** (Lindenstrauss, '06). Consider the space  $X_{2,p} = SL(2, \mathbb{R} \times \mathbb{Q}_p)/SL(2, \mathbb{Z}[\frac{1}{p}])$  and the action of

$$A = \left\{ \begin{pmatrix} e^t \\ e^{-t} \end{pmatrix}, \begin{pmatrix} p^n \\ p^{-n} \end{pmatrix} \right\}$$

If  $\mu$  is an A-invariant and ergodic measure, with  $h_{\mu}(a) > 0$  then  $\mu = m_{X_{2,p}}$ .

**Theorem 6** (EKL). Consider the action of A on  $X_3$  and  $\mu$  A-invariant and ergodic with  $h_{\mu}(a) > 0$ , then  $\mu = m_{X_3}$ . If we have A acting on  $X_n$ , then  $\mu_n$  is homogeneous and if n is prime,  $\mu = m_{X_n}$ .

Our lattice needs to be  $SL(3,\mathbb{Z})$  for the following reason:

**Theorem 7** (Ree's example). There exists  $\Gamma \subset SL(3, \mathbb{R})$ , such that in  $X = SL(3, \mathbb{R})/\Gamma$  we have a centralizer direction that closes up.

**Theorem 8** (EL). Let  $X = \mathbb{G}(\mathbb{R} \times \mathbb{Q}_p)/\mathbb{G}(\mathbb{Z}[\frac{1}{p}])$  and consider the action of A, the maximal  $\mathbb{R}/\mathbb{Q}_p$ -split subgroup in some of the (almost) direct factors. Then there are 4 possible conclusions depending on your measure and lattice, either:

- (I) Invariance
- (Z) Zero entropy
- (R) Rank one
- (T) Periodic orbit