## RIGIDITY OF HIGHER RANK DIAGONALIZABLE ACTIONS

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#### 1. First examples

1.1.  $\mathbb{T} = \mathbb{R}/\mathbb{Z}$ . We can look at multiplication by  $p \in \mathbb{Z}$ ,  $p \times \sim \mathbb{T}$ . If  $p = 3$ , we get that the middle third Cantor set is a  $\times 3$  invariant set, modulo integers. Thus, there are many different types of orbits, closed invariant sets, and invariant measures.

1.2.  $\mathbb{T}^2$ . Consider the action  $A = \begin{pmatrix} 0 & 1 \\ 1 & 1 \end{pmatrix} : \mathbb{T}^2 \to \mathbb{T}^2$ . Adler-Weiss gave a complete description of this dynamical system. We have a covering of  $\mathbb{T}^2$  by a shift space in  $\{0,1\}^{\mathbb{Z}}$ . Again we get that there are many different types of orbits, closed invariant sets, and invariant measures

1.3.  $X_2 = SL(2,\mathbb{R})/SL(2,\mathbb{Z})$ . Where the action of  $SL(2,\mathbb{Z})$  is by Möbius transformations, that is  $\begin{pmatrix} a & b \\ c & d \end{pmatrix} z = \frac{az+b}{cz+d}.$ 



FIGURE 1. The space  $X_2$  with identifications

Consider the action of the geodesic flow *A* =  $\sqrt{e^2}$  $e^{-t}$ ◆ by left multiplication on  $X_2$ . There is a relation between the continued fraction expansion and the geodesic flow. Consider a geodesic with right endpoint  $\alpha \in \mathbb{R}$ , shifting the geodesic gets us another geodesic with right endpoint at  $\alpha - 1$ , eventually we will reach  $\{\alpha\}$ , the fractional part of  $\alpha$ , see Figure 2.

## 2. Higher rank

**Theorem 1** (Furstenberg, '67). *Consider the actions*  $2 \times, 3 \times \sim \mathbb{T}$ *, and*  $\alpha \in \mathbb{T}$ *. We have* 

$$
S = \overline{\{2^n 3^m \alpha\}} = \begin{cases} \text{finite} & \text{if } \alpha \in \mathbb{Q} \\ \mathbb{T} & \text{otherwise} \end{cases}
$$

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Figure 2. Relation between geodesic flow and continued fractions

**Theorem 2** (Berend). *Consider the actions*  $A, B: \mathbb{T}^k \to \mathbb{T}^k$ . *Assume these actions are totally irreducible, hyperbolic, and faithfully*  $\mathbb{Z}^2$ *. Take an A, B-invariant set S, then either*  $|S| < \infty$  *or*  $S = \mathbb{T}$ *.* 

# 3. HOMOGENEOUS SETTING

We would like to get a higher rank picture so that we have 2 multiplicatively independent actions. Our space is  $X_3 = SL(3, \mathbb{R})/SL(3, \mathbb{Z})$  where  $SL(3, \mathbb{Z}) = \{g\mathbb{Z}^3 \mid g \in SL(3, \mathbb{R})\}$  and we consider the action of

$$
A = \left\{ \begin{pmatrix} e^{t_1} & & \\ & e^{t_2} & \\ & & e^{t^3} \end{pmatrix} \mid t_1 + t_2 + t_3 = 0 \right\}
$$

**Conjecture 1** (Margulis). *If*  $Ax \subseteq X_3$  *is bounded for some*  $x \in X_3$ *, then*  $Ax$  *is periodic.* 

This is somehow the correct analog for the theorems of Furstenberg and Berend in this situation. It also gives the following:

Conjecture 2 (Littlewood's Conjecture).

$$
\liminf_{n\to\infty}n|||n\alpha_1|||\cdot||||n\alpha_2|||=0
$$

## 4. Measure Rigidity

**Theorem 3** (Rudolph '90). Suppose  $\mu$  is  $\times$ 2,  $\times$ 3-invariant and ergodic, and  $h_{\mu}(\times 2^m 3^n) > 0$  then  $\mu = m =$ *Lebesgue.*

Generalizations:

- Katok-Saptzier:  $\mathbb{T}^k$  and  $G/\Gamma$
- Kalinin-Katok:  $A, B: \mathbb{T}^3$ .

**Theorem 4** (Einsiedler-Lindenstrauss, '04). *Consider the actions of*  $A, B: \mathbb{T}^k \to \mathbb{T}^k$ , *totally irreducible, hyperbolic, and faithful. Then if*  $h_{\mu}(A^nB^m) > 0$  *and*  $\mu$  *invariant and ergodic, then*  $\mu = m_{\mathbb{T}^k}$ *.* 

**Theorem 5** (Lindenstrauss, '06). *Consider the space*  $X_{2,p} = SL(2,\mathbb{R} \times \mathbb{Q}_p)/SL(2,\mathbb{Z}[\frac{1}{p}])$  *and the action of* 

$$
A = \left\{ \begin{pmatrix} e^t & & \\ & e^{-t} \end{pmatrix}, \begin{pmatrix} p^n & & \\ & p^{-n} \end{pmatrix} \right\}
$$

*If*  $\mu$  *is an A-invariant and ergodic measure, with*  $h_{\mu}(a) > 0$  *then*  $\mu = m_{X_{2,p}}$ .

**Theorem 6** (EKL). *Consider the action of A on*  $X_3$  *and*  $\mu$  *A-invariant and ergodic with*  $h_{\mu}(a) > 0$ *, then*  $\mu = m_{X_3}$ . If we have A acting on  $X_n$ , then  $\mu_n$  is homogeneous and if n is prime,  $\mu = m_{X_n}$ .

Our lattice needs to be  $SL(3, \mathbb{Z})$  for the following reason:

**Theorem 7** (Ree's example). *There exists*  $\Gamma \subset SL(3,\mathbb{R})$ *, such that in*  $X = SL(3,\mathbb{R})/\Gamma$  *we have a centralizer direction that closes up.*

**Theorem 8** (EL). Let  $X = \mathbb{G}(\mathbb{R} \times \mathbb{Q}_p)/\mathbb{G}(\mathbb{Z}[\frac{1}{p}])$  and consider the action of A, the maximal  $\mathbb{R}/\mathbb{Q}_p$ -split *subgroup in some of the (almost) direct factors. Then there are 4 possible conclusions depending on your measure and lattice, either:*

- (I) *Invariance*
- (Z) *Zero entropy*
- (R) *Rank one*
- (T) *Periodic orbit*