

Diffusive limits for stochastic kinetic equations

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MSRI, Berkeley

October 19th, 2015

Kinetic models

Many physical systems are described by a kinetic equation:

$$\partial_t f + a(v) \cdot \nabla_x f = Q(f),$$

- ▶ $v \in V$ represents the various degrees of freedom of a particle, $a(v)$ is its velocity (often $a(v) = v$).
- ▶ $f(x, v)$ is the distribution function of the particles with degrees of freedom v at position $x \in \mathbb{T}^N$ (in this talk).
- ▶ V is endowed with a probability measure μ and the averaged velocity is zero : $\bar{a} = \int_V a(v) d\mu = 0$.
- ▶ Q accounts for the interaction between particles or between a particle and the medium.
- ▶ In general, it has a family of equilibrium F such that:
 $Q(f) = 0$ iff $f = \bar{f} F = (\int_V f d\mu) F$ with $F > 0$, $\bar{F} = 1$.
- ▶ Often, a small parameter ε is present in the equation and, after rescaling, the following equation is obtained:

$$\partial_t f^\varepsilon + \frac{1}{\varepsilon} a(v) \cdot \nabla_x f^\varepsilon = \frac{1}{\varepsilon^2} Q(f^\varepsilon),$$

Radiative transfer and Rosseland approximation



$$\partial_t f^\varepsilon + \frac{1}{\varepsilon} a(v) \cdot \nabla_x f^\varepsilon = \frac{1}{\varepsilon^2} \sigma(\bar{f}) L f^\varepsilon,$$

with $L(f) = \bar{f}F - f$ describes the interaction between a surrounding continuous medium and a flux of photons radiating through it in the absence of hydrodynamical motion.

- ▶ The unknown $f^\varepsilon(t, x, v)$ then stands for a distribution function of photons having position x and velocity v at time t .
- ▶ The function σ is the opacity of the matter.

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- ▶ The unknown $f^\varepsilon(t, x, v)$ then stands for a distribution function of photons having position x and velocity v at time t .
- ▶ The function σ is the opacity of the matter.
- ▶ When the surrounding medium becomes very large compared to the mean free paths ε of photons, f^ε is known to behave like ρ the solution of the Rosseland equation

$$\partial_t \rho - \operatorname{div}_x (\sigma(\rho)^{-1} K \nabla_x \rho) = 0, \quad (t, x) \in [0, T] \times \mathbb{T}^N.$$

with $K := \int_V a(v) \otimes a(v) dv$. This is called the Rosseland approximation. (Bardos, Golse, Perthame, Sentis)

Deterministic equation, diffusive limit, $F = 1$

$$\partial_t f^\varepsilon + \frac{1}{\varepsilon} a(v) \cdot \nabla_x f^\varepsilon = \frac{1}{\varepsilon^2} \sigma(\bar{f}) L(f^\varepsilon), \quad L(f) = \bar{f} - f.$$

Hilbert expansion (formal): $f^\varepsilon = f_0 + \varepsilon f_1 + \varepsilon^2 f_2 + \dots$

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\rightsquigarrow order -2 : $Lf_0 = \bar{f}_0 - f_0 = 0$ and $f_0 = \bar{f}_0 = \rho$.

(We assume $0 < \sigma_* \leq \sigma(\rho) \leq \sigma^*$, $\rho \in \mathbb{R}$).

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The equation

$$L(g) = \bar{g} - g = \int_V g d\mu - g = h$$

can be solved iff $\int_V h d\mu = 0$ and in this case, we can take
 $g = -h$.

Recall that $\int_V a(v) d\mu = 0 \rightarrow f_1 = -\sigma(\rho)^{-1} a(v) \cdot \nabla_x \rho$

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$$\longrightarrow \partial_t \rho - \int_V a(v) \cdot \nabla_x (\sigma(\rho)^{-1} a(v) \cdot \nabla_x \rho) d\mu = 0$$

$$\longrightarrow \partial_t \rho - \operatorname{div} (\sigma(\rho)^{-1} K \nabla_x \rho) = 0,$$

with

$$K := \int_V a(v) \otimes a(v) d\mu(v).$$

Deterministic equation, diffusive limit

$$\partial_t f^\varepsilon + \frac{1}{\varepsilon} a(v) \cdot \nabla_x f^\varepsilon = \frac{1}{\varepsilon^2} \sigma(\bar{f}^\varepsilon) L f^\varepsilon, \quad L(f) = \bar{f} F - f.$$

When $\varepsilon \rightarrow 0$, the density $\rho^\varepsilon := \int_V f^\varepsilon d\mu$ converges to the solution ρ of the diffusion equation

$$\partial_t \rho - \operatorname{div}(\sigma(\rho)^{-1} K \nabla \rho) = 0$$

with initial data $\rho_0 = \int_V f_0 d\mu$. We assume $\int_V a(v) F(v) d\mu(v) = 0$ and:

$$\forall \varepsilon > 0, \forall (\xi, \alpha) \in S^{N-1} \times \mathbb{R}, \quad \mu(\{v \in V, |a(v) \cdot \xi + \alpha| < \varepsilon\}) \leq \varepsilon^\theta,$$

for some $\theta > 0$.

The stochastic case

We first consider a similar model with time white noise:

$$df^\varepsilon + \frac{1}{\varepsilon} a(v) \cdot \nabla_x f^\varepsilon dt = \frac{1}{\varepsilon^2} \sigma(\bar{f}^\varepsilon) Lf^\varepsilon dt + f^\varepsilon \circ QdW_t,$$

$$x \in \mathbb{T}^N, v \in V, Lf = \bar{f}F - f.$$

- ▶ The noise represents random creations/absorptions of photons.
- ▶ We expect to obtain a stochastic quasilinear parabolic equation at the limit.
- ▶ We adapt the Hilbert expansion method.
- ▶ We first have to prove existence of f^ε , we need non degeneracy of a :

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Hilbert expansion, stochastic case

$$\partial_t f^\varepsilon + \frac{1}{\varepsilon} a(v) \cdot \nabla_x f^\varepsilon = \frac{1}{\varepsilon^2} \sigma(\bar{f}^\varepsilon) L f^\varepsilon + f^\varepsilon \circ Q dW_t, \quad L(f) = \bar{f} - f.$$

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$\longrightarrow \partial_t \rho - \operatorname{div} \left(\sigma(\rho)^{-1} \left(\int_V a(v) \otimes a(v) d\mu \right) \nabla_x \rho \right) = \rho \circ Q dW_t$.

and

$$\operatorname{div} \left(\sigma(\rho)^{-1} \left(a(v) \otimes a(v) - \int_V a(v) \otimes a(v) d\mu \right) \nabla_x \rho \right) = \sigma(\rho) L f_2.$$

Hilbert expansion, rigorous proof

- ▶ We take the solution of the SPDE:

$$\partial_t \rho - \operatorname{div} \left(\sigma(\rho)^{-1} \left(\int_V a(v) \otimes a(v) d\mu \right) \nabla_x \rho \right) = \rho \circ Q dW_t.$$

It is smooth in space provided the noise and initial data are also smooth. (D., De Moor, Hofmanova).

- ▶ Define: $f_1 = -\sigma(\rho)^{-1} a(v) \cdot \nabla_x \rho$ and

$$f_2 = -\operatorname{div} \left(\sigma(\rho)^{-1} \left(a(v) \otimes a(v) - \int_V a(v) \otimes a(v) d\mu \right) \nabla_x \rho \right).$$

- ▶ Set

$$r^\varepsilon = f^\varepsilon - \rho - \varepsilon f_1 - \varepsilon^2 f_2$$

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then, with $df_1 = f_{1,d} dt + \Psi_1^b dW$,

$$\begin{aligned} dr^\varepsilon + \frac{1}{\varepsilon} a(v) \cdot \nabla_x r^\varepsilon dt &= \frac{1}{\varepsilon^2} [\sigma(\bar{f}^\varepsilon) L(f^\varepsilon) - \sigma(\rho) L(f^\varepsilon - r^\varepsilon)] dt \\ &\quad - \varepsilon a(v) \cdot \nabla_x f_2 dt + (f^\varepsilon - \rho - \varepsilon f_1) QdW_t \\ &\quad + G(f^\varepsilon - \rho) dt - \varepsilon f_{1,d} dt - \varepsilon \Psi_1^b dW_t - \varepsilon^2 df_2. \end{aligned}$$

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The terms: $\frac{1}{\varepsilon} a(v) \cdot \nabla_x r^\varepsilon$ and $\frac{1}{\varepsilon^2} [\sigma(\bar{f}^\varepsilon)L(f^\varepsilon) - \sigma(\rho)L(f^\varepsilon - r^\varepsilon)]$ behave well in L^1 :

$$\frac{1}{\varepsilon} \int_{\mathbb{T}^N \times V} (a(v) \cdot \nabla_x r^\varepsilon) \operatorname{sign}(r^\varepsilon) d\mu dx = 0,$$

$$\frac{1}{\varepsilon^2} \int_{\mathbb{T}^N \times V} [\sigma(\bar{f}^\varepsilon)L(f^\varepsilon) - \sigma(\rho)L(f^\varepsilon - r^\varepsilon)] \operatorname{sign}(r^\varepsilon) d\mu dx \leq 0.$$

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Problem: we cannot use Itô formula for $\|r^\varepsilon\|_{L^1}$.

Hilbert expansion, rigorous proof

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- ▶ We use Itô formula for a δ smoothed version of the L^1 norm.
- ▶ This introduces singular terms in the Itô correction: the second derivative of this smoothed L^1 norm is of order $\frac{1}{\delta}$ multiplied by ε^2 .
- ▶ The use of a modified L^1 norm introduces a term of order $\frac{\delta}{\varepsilon^2}$.

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 - ▶ The use of a modified L^1 norm introduces a term of order $\frac{\delta}{\varepsilon^2}$.
- We need to kill the noise term of order ε .
- We need a third corrector f_3 such that

$$\varepsilon^2 df_3 - \sigma(\rho)L(f_3)dt = \Psi_1^b dW_t$$

The convergence result

Theorem Let f^ε denote the solution of the kinetic problem

$$df^\varepsilon + \frac{1}{\varepsilon} a(v) \cdot \nabla_x f^\varepsilon dt = \frac{1}{\varepsilon^2} \sigma(\bar{f}^\varepsilon) (\bar{f}^\varepsilon F - f^\varepsilon) dt + f^\varepsilon \circ QdW_t, \\ x \in \mathbb{T}^N, v \in V.$$

and ρ the solution of the non-linear stochastic partial differential equation

$$\partial_t \rho - \operatorname{div} (\sigma(\rho)^{-1} K \nabla_x \rho) = \rho \circ QdW_t,$$

where K denotes the matrix $(\int_V a(v) \otimes a(v) d\mu)$. Then, the solution f^ε converges as ε tends to 0 to the fluid limit ρ and we have the estimate:

$$\sup_{t \in [0, T]} \mathbb{E} \|f_t^\varepsilon - \rho_t\|_{L^1_{x,v}} \leq C\varepsilon.$$

Another model with "real noise"

We now start with a noise with non vanishing correlation length:

$$\partial_t f^\varepsilon + \frac{1}{\varepsilon} a(v) \cdot \nabla_x f^\varepsilon = \frac{1}{\varepsilon^2} \sigma(\bar{f}^\varepsilon) L f^\varepsilon + \frac{1}{\varepsilon} f^\varepsilon m\left(\frac{t}{\varepsilon^2}\right),$$

where $m(t)$ is an ergodic centered markov process with values in a space of functions of x .

- ▶ We assume (V, μ) is a measured space, μ is a probability measure, $a \in L^\infty(V; \mathbb{R}^N)$, $N \geq 1$ and $x \in \mathbb{T}^N$.
- ▶ The equation is set in $\mathbb{R}_t^+ \times \mathbb{T}_x^N \times V_v$, with initial data $f^\varepsilon(0) = f_0$.
- ▶ As before, $L = \bar{f}F - f$ and the velocities are centered:
 $\int_V a(v) d\mu(v) = \int_V a(v) F(v) d\mu(v) = 0$ and non degenerate:

$$\forall \varepsilon > 0, \forall (\xi, \alpha) \in \mathcal{S}^{N-1} \times \mathbb{R}, \mu(\{v \in V, |a(v) \cdot \xi + \alpha| < \varepsilon\}) \leq \varepsilon^\theta.$$

- ▶ Existence and uniqueness of f^ε is classical under these assumptions.

Diffusion approximation :

We consider a differential equation in \mathbb{R}^d with random coefficients:

$$\frac{dx_t^\varepsilon}{dt} = F(x_t^\varepsilon, m_t^\varepsilon) + \frac{1}{\varepsilon} G(x_t^\varepsilon, m_t^\varepsilon).$$

The driving process m_t^ε scales like $m_t^\varepsilon = m(\varepsilon^{-2}t)$ where m_t is a \mathbb{R}^d valued homogeneous stationary and mixing Markov process. If $G \equiv 0$, then $x_t^\varepsilon \rightarrow \bar{x}_t$ where

$$\frac{d\bar{x}}{dt} = \bar{F}(\bar{x}_t), \quad \bar{F}(x) := \int_{\mathbb{R}} F(x, n) d\nu(n),$$

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and ν is the invariant measure of m_t . We are interested in the case:

$$G \not\equiv 0, \quad \int_{\mathbb{R}} G(\cdot, n) d\nu(n) \equiv 0 ?$$

We concentrate on the case: $G(x, m) = G(x)m$.

Donsker Theorem

Let (ξ_i) be i.i.d centered random variables, with variance $\sigma^2 < +\infty$. Let

$$X_n(t) = \frac{1}{\sigma\sqrt{n}} (\xi_1 + \cdots + \xi_{nt}), \quad t \in [0, 1],$$

the random variable on $C = C([0, 1]; \mathbb{R})$ defined by linear interpolation between the points $t = i/n$. Then

$$X_n \rightarrow \beta$$

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$$M_t^\varepsilon = \frac{1}{\varepsilon} \int_0^t m\left(\frac{s}{\varepsilon^2}\right) ds \sim \varepsilon \sum_0^{\lfloor \frac{t}{\varepsilon^2} \rfloor} \int_k^{k+1} m(s) ds \rightarrow W_t,$$

where $W = (\beta_1, \dots, \beta_d)$ is d dimensional brownian motion.

The perturbed test function method.

Problem : We assume that the driving process m_t^ε scales like $m_t^\varepsilon = m(\varepsilon^{-2}t)$ where m_t is homogeneous and stationary Markov process. We assume that it is mixing with invariant measure ν . Let

$$\frac{d}{dt}x_t^\varepsilon = F(x_t^\varepsilon) + \frac{1}{\varepsilon}G(x_t^\varepsilon)m_t^\varepsilon, .$$

We expect that at the limit $\varepsilon \rightarrow 0$, x_t^ε converges in law to the solution of:

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To prove this we use the generator of $(x^\varepsilon, m^\varepsilon)$. We denote by M the generator of m , then $(x_t^\varepsilon, m_t^\varepsilon)$ has the following generator:

$$\mathcal{L}^\varepsilon \Phi(x, n) = \left(F(x) + \frac{1}{\varepsilon}G(x)n, D_x \Phi(x, n) \right) + \frac{1}{\varepsilon^2}M\Phi(x, n),$$
$$\Phi \in C_b^2(\mathbb{R}^{2d}).$$

Let $v^\varepsilon(t, x, n) = \mathbb{E}(\varphi(x_t^\varepsilon(x), m_t^\varepsilon(n)))$, then $\frac{d}{dt}v^\varepsilon = \mathcal{L}^\varepsilon v^\varepsilon$

The perturbed test function method.

Evolution of $\mathbb{E}(\varphi(x_t^\varepsilon))$:

$$\mathcal{L}^\varepsilon \varphi(x^\varepsilon) = \left(F(x^\varepsilon) + \frac{1}{\varepsilon} G(x^\varepsilon, n), D_x \varphi(x) \right)$$

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\rightsquigarrow We try to find correctors $\varphi_1, \varphi_2 \in C_b^2(\mathbb{R}^d \times \mathbb{R}^d)$ such that the perturbed test function

$$\varphi^\varepsilon := \varphi + \varepsilon \varphi_1 + \varepsilon^2 \varphi_2,$$

satisfies

$$\mathcal{L}^\varepsilon \varphi^\varepsilon(x, n) = \mathcal{L} \varphi(x) + \mathcal{O}(\varepsilon)$$

(Papanicolaou, Stroock, Varadhan 77. See the recent book by Fouque, Garnier, Papanicolaou and Solna)

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$$\mathcal{L}^\varepsilon \varphi^\varepsilon(x, n) = \mathcal{L}\varphi(x) + \mathcal{O}(\varepsilon), \quad \varphi^\varepsilon := \varphi + \varepsilon\varphi_1 + \varepsilon^2\varphi_2.$$

Write:

$$\begin{aligned} & \mathbb{E}(\varphi^\varepsilon(x_t^\varepsilon, m_t^\varepsilon)) \\ &= \mathbb{E}(\varphi^\varepsilon(x_s^\varepsilon, m_s^\varepsilon)) + \mathbb{E}\left(\int_s^t \mathcal{L}^\varepsilon \varphi^\varepsilon(x_\sigma^\varepsilon, m_\sigma^\varepsilon) d\sigma\right) \end{aligned}$$

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$$\varepsilon \rightarrow 0 \quad \rightsquigarrow \quad \mathbb{E}(\varphi(x_t)) = \mathbb{E}(\varphi(x_s)) + \mathbb{E}\left(\int_s^t \mathcal{L}\varphi(x_\sigma) d\sigma\right)$$

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$\rightsquigarrow \mathcal{L}$ is the generator of the limit process.

Equations for the correctors

$$\begin{aligned}\mathcal{L}^\varepsilon \varphi(x, n) &= (F(x) + \frac{1}{\varepsilon} G(x, n), D_x \varphi(x, n)) + \frac{1}{\varepsilon^2} M \varphi(x, n) \\ &= \mathcal{L} \varphi(x) + \mathcal{O}(\varepsilon), \quad \varphi \in C_b^2(\mathbb{R}^2),\end{aligned}$$

$$\varphi^\varepsilon := \varphi + \varepsilon \varphi_1 + \varepsilon^2 \varphi_2.$$

We derive

$$M \varphi(x) = 0, \quad (1)$$

$$(G(x)n, D_x \varphi(x)) + M \varphi_1(x, n) = 0, \quad (2)$$

$$(F(x), D_x \varphi) + (G(x)n, D_x \varphi_1(x)) + M \varphi_2(x, n) = \mathcal{L} \varphi(x). \quad (3)$$

The first equation is satisfied since φ does not depend on n .

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The first equation is satisfied since φ does not depend on n . To solve the second equation, we need to solve the Poisson equation associated to M .

The Poisson equation

We assume that for a large class of functions ψ such that $\int \psi(n) d\nu(n) = 0$ (ν is the invariant law of m_t), the equation

$$M\theta = \psi, \quad \psi \in C_b(\mathbb{R})$$

has a solution in $\theta \in C_b(E)$, unique under the condition $\int \theta(n) d\nu(n) = 0$.

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has a solution in $\theta \in C_b(E)$, unique under the condition $\int \theta(n) d\nu(n) = 0$. It is given by:

$$\theta(n) = M^{-1}\psi(n) := - \int_0^\infty e^{Mt}\psi(n) dt = \int_0^\infty \mathbb{E}\psi(m_t | m(0) = n) dt.$$

e^{Mt} is the transition semi-group associated to m_t .

Equations for the correctors

$$(G(x)n, D_x\varphi(x)) + M\varphi_1(x, n) = 0, \quad (4)$$

$$(F(x), D_x\varphi) + (G(x)n, D_x\varphi_1(x)) + M\varphi_2(x, n) = \mathcal{L}\varphi(x). \quad (5)$$

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$$\varphi_1 = -M^{-1}(G(x)n, D_x\varphi)$$

$$\rightsquigarrow \mathcal{L}\varphi(x) = (F(x), D_x\varphi) - \int_E (G(x)n, D_x(M^{-1}G(x)n, D_x\varphi(x))) d\nu(n).$$

This is the generator associated to the SDE:

$$dx = f(X)dt + G(X) \circ C^{1/2} d\beta$$

where β is a d dimensional brownian motion and C is computed from $\int_E n \otimes M^{-1}n d\nu(n)$.

If all coefficients are bounded.
We obtain bounds of the form:

$$\mathbb{E} \left(\sup_{t \in [0, T]} |x^\varepsilon(t)|^2 \right) \leq c$$

independent on ε and:

$$\mathbb{E} (|x^\varepsilon(t) - x^\varepsilon(s)|^4) \leq |t - s|^2 + \varepsilon.$$

We write:

$$\begin{aligned} & \mathbb{E}(\varphi^\varepsilon(x^\varepsilon(t), m^\varepsilon(t))) \\ &= \mathbb{E}(\varphi^\varepsilon(x^\varepsilon(t_0), m^\varepsilon(t_0))) + \int_{t_0}^t \mathcal{L}^\varepsilon \varphi^\varepsilon(x^\varepsilon(s), m^\varepsilon(s)) ds \end{aligned}$$

$$\rightsquigarrow \mathbb{E}(\varphi(x^\varepsilon(t))) = \mathbb{E}(\varphi(x^\varepsilon(t_0))) + \mathbb{E} \int_{t_0}^t \mathcal{L} \varphi(x^\varepsilon(s)) ds + O(\varepsilon),$$

Back to the stochastic kinetic equation

$$\partial_t f^\varepsilon + \frac{1}{\varepsilon} a(v) \cdot \nabla_x f^\varepsilon = \frac{1}{\varepsilon^2} \sigma(\bar{f}^\varepsilon) L f^\varepsilon + \frac{1}{\varepsilon} f^\varepsilon m^\varepsilon(t),$$

- $m^\varepsilon(t)$ is a centered, mixing markov process with values in a space E of functions of x .
- (V, μ) is a measured space and μ is a probability measure.
- $a \in L^\infty(V; \mathbb{R}^d)$
- $d \geq 1$ and $x \in \mathbb{T}^d$ the d dimensional torus.
- L is a dissipative operator.
- We assume $\int_V a(v) d\mu(v) = 0$ and

$$\forall \varepsilon > 0, \forall (\xi, \alpha) \in \mathcal{S}^{N-1} \times \mathbb{R}, \mu(\{v \in V, |a(v) \cdot \xi + \alpha| < \varepsilon\}) \leq \varepsilon^\theta,$$

for some $\theta > 0$.

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We denote by M the generator of m , then the generator of $(f^\varepsilon, m^\varepsilon)$ is:

$$\mathcal{L}^\varepsilon \varphi^\varepsilon(f, n) = -\frac{1}{\varepsilon} (Af, D\varphi) + \frac{1}{\varepsilon^2} (\sigma(\bar{f})Lf, D\varphi) + \frac{1}{\varepsilon} (nf, D\varphi) + \frac{1}{\varepsilon^2} M\varphi$$

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where $Af = a(v) \cdot \nabla_x f$, D is the gradient with respect to f and

$$\mathcal{L}_1 \varphi = -(Af, D\varphi) + (nf, D\varphi)$$

and

$$\mathcal{L}_2 \varphi = (\sigma(\bar{f})Lf, D\varphi) + M\varphi.$$

Perturbed test function method:

$$\begin{aligned}\mathcal{L}^\varepsilon \varphi^\varepsilon(f, n) &= -\frac{1}{\varepsilon}(Af, D\varphi) + \frac{1}{\varepsilon^2}(\sigma(\bar{f})Lf, D\varphi) + \frac{1}{\varepsilon}(nf, D\varphi) + \frac{1}{\varepsilon^2}M\varphi \\ &= \frac{1}{\varepsilon}\mathcal{L}_1\varphi + \frac{1}{\varepsilon^2}\mathcal{L}_2\varphi\end{aligned}$$

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We expect a limit model which is a SPDE with unknown

$$\rho = \int_V f d\mu(v)$$

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$$\mathcal{L}_2\psi = (\sigma(\bar{f})Lf, D\psi) + M\psi = \Phi$$

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$$\frac{d}{dt}g = \sigma(\bar{g})Lg = \sigma(\bar{g}) \left(\int_V g d\mu(v) - g \right) = \sigma(\bar{g})(\rho - g), \quad g(0) = f,$$

where m is the driving process starting from n at $t = 0$.

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where m is the driving process starting from n at $t = 0$.

- ▶ Explicit solution : $\rho = \int_V g(t) d\mu(v) = \int_V f d\mu(v)$

$$\rightsquigarrow g(t) = e^{-\sigma(\bar{g})t}f + (1 - e^{-\sigma(\bar{g})t})\rho.$$

\rightsquigarrow

$$\psi(f, n) = \mathcal{L}_2^{-1}\Phi(f, n) = - \int_0^\infty \mathbb{E}(\Phi(g(t; f, n); m(t; f, n))) dt$$

$$\text{if } \int_E \Phi(\rho, n) d\nu(n) = 0.$$

Perturbed test function method:

$$\begin{aligned}\mathcal{L}^\varepsilon \varphi^\varepsilon(f, n) &= -\frac{1}{\varepsilon}(Af, D\varphi) + \frac{1}{\varepsilon^2}(\sigma(\bar{f})Lf, D\varphi) + \frac{1}{\varepsilon}(nf, D\varphi) + \frac{1}{\varepsilon^2}M\varphi \\ &= \frac{1}{\varepsilon}\mathcal{L}_1\varphi + \frac{1}{\varepsilon^2}\mathcal{L}_2\varphi\end{aligned}$$

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$$\int_E \mathcal{L}_1\varphi(\rho, n) d\nu(n) = \int_E -(A\rho, D\varphi) + (n\rho, D\varphi) d\nu(n) = 0$$

Perturbed test function method:

$$\begin{aligned}\mathcal{L}^\varepsilon \varphi^\varepsilon(f, n) &= -\frac{1}{\varepsilon}(Af, D\varphi) + \frac{1}{\varepsilon^2}(\sigma(\bar{f})Lf, D\varphi) + \frac{1}{\varepsilon}(nf, D\varphi) + \frac{1}{\varepsilon^2}M\varphi \\ &= \frac{1}{\varepsilon}\mathcal{L}_1\varphi + \frac{1}{\varepsilon^2}\mathcal{L}_2\varphi\end{aligned}$$

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$$\begin{aligned}\rightarrow \varphi_1 &= -\mathcal{L}_2^{-1}\mathcal{L}_1\varphi = \\ &\int_0^\infty -(Ag(t; f, n), D\varphi) + (m(t; f, n)g(t, f, n), D\varphi) dt\end{aligned}$$

Perturbed test function method:

$$\begin{aligned}\mathcal{L}^\varepsilon \varphi^\varepsilon(f, n) &= -\frac{1}{\varepsilon}(Af, D\varphi) + \frac{1}{\varepsilon^2}(Lf, D\varphi) + \frac{1}{\varepsilon}(m, D\varphi) + \frac{1}{\varepsilon^2}M\varphi \\ &= \frac{1}{\varepsilon}\mathcal{L}_1\varphi + \frac{1}{\varepsilon^2}\mathcal{L}_2\varphi\end{aligned}$$

$$\mathcal{L}_1\varphi = -(Af, D\varphi) + (m, D\varphi), \quad \mathcal{L}_2\varphi = (Lf, D\varphi) + M\varphi$$

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\rightsquigarrow Order -1 : $\mathcal{L}_1\varphi + \mathcal{L}_2\varphi_1 = 0$

$$\int_E \mathcal{L}_1\varphi(\rho, n) d\nu(n) = \int_E -(A\rho, D\varphi) + (n\rho, D\varphi) d\nu(n) = 0$$

$$\rightarrow \varphi_1 = -\mathcal{L}_2^{-1}\mathcal{L}_1\varphi = -(A(\sigma(\rho)^{-1}f), D\varphi) - (fM^{-1}n, D\varphi).$$

Perturbed test function method:

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\rightsquigarrow Order -1 :

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\rightsquigarrow Order 0 : $\mathcal{L}_1\varphi_1 + \mathcal{L}_2\varphi_2 = \mathcal{L}\varphi \rightarrow \mathcal{L}\varphi(\rho) = \int_E \mathcal{L}_1\varphi_1(\rho, n) d\nu(n).$

Limit generator:

$$\begin{aligned}\mathcal{L}\varphi &= \int_E \mathcal{L}_1\varphi_1 d\nu(n) \\ &= (\mathcal{A}\rho, D\varphi) - \int_E \left((\rho n M^{-1} n, D\varphi(\rho)) + D^2\varphi(\rho) \cdot (\rho M^{-1} n, \rho n) \right) d\nu(n).\end{aligned}$$

where

$$\mathcal{A}\rho = \operatorname{div}((\sigma(\rho))^{-1}) K \nabla \rho$$

This is the generator of

$$\begin{aligned}d\rho &= \operatorname{div}(K \nabla \rho) dt + \rho \circ Q^{1/2} dW(t) \\ &= \operatorname{div}(K \nabla \rho) dt + \frac{1}{2} F \rho + \rho Q^{1/2} dW(t).\end{aligned}$$

Limit $\varepsilon \rightarrow 0$

- ▶ To complete the proof, we need to prove tightness of the laws of $\rho^\varepsilon = \bar{f}^\varepsilon$.
- ▶ Bound in $L^2(\mathbb{T}^N)$: Take $\varphi(f) = \|f\|_{L^2}^2$
(weighed norm: $\|f\|_{L^2}^2 = \int_{\mathbb{T}^N \times V} f^2(x, v) F^{-1}(v) dx dv$.)
- ▶ It is not a function of $\rho = \bar{f}$ but it is possible to compute correctors and obtain a bound on $\|f^\varepsilon\|_{L^2(\mathbb{T}^N)}$ in $L^\infty(0, T)$.
- ▶ This implies tightness in $C([0, T]; H^{-\eta}(\mathbb{T}^N))$, $\eta > 0$.
- ▶ This is not sufficient to deal with the nonlinear term.

Limit $\varepsilon \rightarrow 0$

- ▶ We also have a bound $\frac{1}{\varepsilon} \|Lf^\varepsilon\|_{L^2}$ in $L^2(0, T)$.
- ▶ $\varepsilon \partial_t f^\varepsilon + a(v) \cdot \nabla_x f^\varepsilon = \frac{1}{\varepsilon} \sigma(\bar{f}^\varepsilon) Lf^\varepsilon + m^\varepsilon f^\varepsilon$ is bounded in $L^2(0, T; L^2(\mathbb{T}^N))$.
- ▶ **Averaging Lemma:** Assume

$$\forall \varepsilon > 0, \forall (\xi, \alpha) \in S^{N-1} \times \mathbb{R}, \mu(\{v \in V, |a(v) \cdot \xi + \alpha| < \varepsilon\}) \leq \varepsilon^\theta,$$

for some $\theta > 0$.

If f^ε and $\varepsilon \partial_t f^\varepsilon + a(v) \cdot \nabla_x f^\varepsilon$ are bounded in $L^2(0, T; L^2(\mathbb{T}^N))$ then $\rho^\varepsilon = \bar{f}^\varepsilon$ is bounded in $L^2(0, T; H^s)$, for $s < \theta/2$.

- ▶ We get tightness in $L^2(0, T; L^2(\mathbb{T}^N))$

Limit $\varepsilon \rightarrow 0$

Theorem Let $f_0^\varepsilon \in L^2_{x,v}$ and

$$\rho_0 := \int_V f_0 d\mu.$$

Under the above assumptions on the velocities a and on the driving process m^ε , we have: for all $\eta > 0$, the density $\rho^\varepsilon := \int_V f^\varepsilon d\mu$ converge in law in $C([0, T]; H^{-\eta})$ and in $L^2(0, T; H^s)$ to the solution ρ of the equation

$$\begin{aligned} d\rho &= \operatorname{div}(\sigma(\rho)^{-1} K \nabla \rho) dt + \rho \circ Q^{1/2} dW(t), \text{ in } \mathbb{R}_t^+ \times \mathbb{T}^d, \\ &= \operatorname{div}(\sigma(\rho)^{-1} K \nabla \rho) dt + \frac{1}{2} F \rho + \rho Q^{1/2} dW(t), \text{ in } \mathbb{R}_t^+ \times \mathbb{T}^d, \end{aligned}$$

with initial data ρ_0 , where W is a cylindrical Wiener process on $L^2(\mathbb{T}^d)$, Q is a nuclear operator on $L^2(\mathbb{T}^d)$ determined by the correlation of m .

Coefficient Q in the limit model

It is associated to a kernel k :

$$Qf(x) = \int_{\mathbb{T}^d} k(x, y)f(y)dy, \quad f \in L^2(\mathbb{T}^d),$$

where

$$k(x, y) := \mathbb{E} \int_{\mathbb{R}} m(0)(y)m(t)(x)dt, \quad x, y \in \mathbb{T}^d.$$

The Itô correction :

$$F(x) = k(x, x).$$

The noise as a force (linear case):

$$\partial_t f^\varepsilon + \frac{1}{\varepsilon} a(v) \cdot \nabla_x f^\varepsilon + \frac{1}{\varepsilon^2} m^\varepsilon \cdot \nabla_v f = \frac{1}{\varepsilon^2} Lf^\varepsilon.$$

- $m^\varepsilon(t)$ is a centered mixing markov process with values in a space of functions E .
- $v \in V = \mathbb{T}^d$.
- $a(v) = v$.
- $Lf = \rho F - f$ where F is an equilibrium function satisfying:

$$\int_V v F(v) d\mu(v) = 0.$$

The noise as a force (linear case):

$$\partial_t f^\varepsilon + \frac{1}{\varepsilon} v \cdot \nabla_x f^\varepsilon + \frac{1}{\varepsilon^2} m^\varepsilon \cdot \nabla_v f = \frac{1}{\varepsilon^2} Lf^\varepsilon.$$

We denote by M the generator of m , then the generator of f^ε , m^ε is given by:

$$\begin{aligned} \mathcal{L}^\varepsilon \varphi^\varepsilon(f, n) &= -\frac{1}{\varepsilon} (Af, D\varphi) + \frac{1}{\varepsilon^2} (Lf, D\varphi) - \frac{1}{\varepsilon^2} (mBf, D\varphi) + \frac{1}{\varepsilon^2} M\varphi \\ &= \frac{1}{\varepsilon} \mathcal{L}_1 \varphi + \frac{1}{\varepsilon^2} \mathcal{L}_2 \varphi \end{aligned}$$

where $Af = v \cdot \nabla_x f$, $Bf = \nabla_v f$, D is the gradient with respect to f and now

$$\mathcal{L}_1 \varphi = -(Af, D\varphi)$$

and

$$\mathcal{L}_2 \varphi = (Lf, D\varphi) - (mBf, D\varphi) + M\varphi$$

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$$\rightsquigarrow \mathcal{L}_2^{-1}\psi(f, n) = - \int_0^\infty \mathbb{E}(\psi(g(t; f, n); m(t; f, n))) dt \text{ if}$$

$$\int_E \psi \left(\int_{-\infty}^0 e^s \rho F(v - \int_s^0 m(\sigma, n) d\sigma) ds, n \right) d\nu(n) = 0.$$

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$$\rightarrow \mathcal{L}\varphi = - \int_E \mathcal{L}_1\varphi_1 \left(\int_{-\infty}^0 e^{s\rho} F(v - \int_s^0 m(\sigma, n) d\sigma) ds \right) d\nu(n)$$

Limit generator:

Very long computations ...

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We obtain the limit SPDE:

$$d\rho = \operatorname{div}((K+H)\nabla\rho)dt + \operatorname{div}(\rho G) + \operatorname{div}(\rho \circ Q^{1/2}dW(t)), \text{ in } \mathbb{R}_t^+ \times \mathbb{T}^d$$

The operator Q :

$$Qf(x) = \int_{\mathbb{T}^d} k(x,y)f(y)dy, \quad f \in L^2(\mathbb{T}^d),$$

where

$$k(x,y) := \mathbb{E} \int_{\mathbb{R}} m(0)(y) \otimes m(t)(x)dt, \quad x,y \in \mathbb{T}^d.$$

The extra (deterministic) diffusion:

$$H(x) := \mathbb{E} \int_0^\infty e^{-s} m(0)(x) \otimes m(t)(x)dt, \quad x \in \mathbb{T}^d.$$