# Observability and control of water-waves

#### Thomas Alazard

CNRS & École normale supérieure

<span id="page-0-0"></span>MSRI October 2015



Water waves are, in general, generated by the motion of a solid component of the boundary or by impulsive pressures (blowing) applied on the free surface.

Question: generation and absorption of water waves

Question: which 2d or 3d water waves can be generated in a tank?



Figure: 3d and 2d waves in a rectangular tank

#### Main results

With Baldi and Han-Kwan: controllability of 2d gravity-capillary waves. Observability of 3d gravity water waves.

There are many results for equations describing water waves :

• Benjamin-Ono, KdV, Saint-Venant;

see works by Cerpa, Crépeau, Coron, Dubois, Glass, Guerrero, Laurent, Linares, Ortega, Petit, Rosier, Rouchon, Russell, Zhang....

Here we consider the dynamics of an incompressible, irrotational liquid flow

- moving under the force of gravitation and/or surface tension,
- in a time-dependent domain  $\Omega$  with a free boundary.

Problem determined by two unknowns :

- the free surface elevation  $\eta$ ,
- the fluid velocity  $v$ .

The fluid domain  $\Omega$  has a free surface. At time  $t \geq 0$ ,

 $\Omega(t) = \{ (x, y) \in Q \times \mathbb{R} : -h < y < \eta(t, x) \},\$ 

where  $\eta$  is an unknown,  $Q = [0, L_1] \times [0, L_2]$  or  $Q = [0, L_1]$ .



 $\Omega(t) = \{ (x, y) \in Q \times \mathbb{R} : -h < y < \eta(t, x) \}$  $\eta$  is an unknown,  $Q = [0, L_1] \times [0, L_2]$  or  $Q = [0, L_1]$ .

$$
\partial_t v + v \cdot \nabla v + \nabla (P + gy) = 0 \qquad \text{in } \Omega
$$
  
div  $v = 0$   
 $v \cdot n = 0$   
 $\partial_t \eta = \sqrt{1 + |\nabla \eta|^2} v \cdot n$   
on the force  
 $P - P_{ext} = \kappa \operatorname{div} \left( \frac{\nabla \eta}{\sqrt{1 + |\nabla \eta|^2}} \right)$  on the free surface

g gravity, P pressure,  $P_{ext}$  external pressure,  $\kappa$  surface tension. Moreover curl  $v = 0$  so that  $v = \nabla \phi$ .









$$
\Omega(t) = \{ (x, y) \in \mathbb{R} \times \mathbb{R} : -h < y < \eta(t, x) \}.
$$

## Periodization



Justification by ABZ / Thibault de Poyferré.

T. Alazard (ENS) [Control water-waves](#page-0-0) MSRI 8/23

$$
\Omega(t) = \{ (x, y) \in \mathbb{R} \times \mathbb{R} : -h < y < \eta(t, x) \}.
$$

## Periodization



Justification by ABZ / Thibault de Poyferré.

T. Alazard (ENS) [Control water-waves](#page-0-0) MSRI 8/23

$$
\Omega(t) = \{ (x, y) \in \mathbb{R} \times \mathbb{R} : -h < y < \eta(t, x) \}.
$$

## **Periodization**



Justification by ABZ / Thibault de Poyferré.

T. Alazard (ENS) [Control water-waves](#page-0-0) MSRI 8 / 23

$$
\Omega(t) = \{ (x, y) \in \mathbb{R} \times \mathbb{R} : -h < y < \eta(t, x) \}.
$$

### **Periodization**



Justification by ABZ / Thibault de Poyferré.

T. Alazard (ENS) [Control water-waves](#page-0-0) MSRI 8/23

### With surface tension

## Local controllability of 2D gravity-capillary water waves

Notations:  $d = 1$ ,  $\psi(t, x) = \phi(t, x, \eta(t, x))$ 

## Theorem (T.A., Baldi, Han-Kwan)

Let  $T > 0$  and consider  $\omega \subset \mathbb{T}$ . There exist  $s > 0$  (large) and  $M_0 > 0$ (small) s.t. for any  $(\eta_{in},\psi_{in})$  ,  $(\eta_{final},\psi_{final})$  in  $H_0^{s+\frac{1}{2}}(\mathbb{T})\times H^s(\mathbb{T})$ 

 $\|\eta_{in}\|_{H^{s+\frac{1}{2}}} + \|\psi_{in}\|_{H^{s}} < M_0, \quad \|\eta_{final}\|_{H^{s+\frac{1}{2}}} + \|\psi_{final}\|_{H^{s}} < M_0,$ 

there exists  $P_{ext}$  in  $C^0([0,T];H^s(\mathbb{T}))$  supported in  $[0,T]\times\omega$  , such that the Cauchy problem with data  $(\eta|_{t=0}, \psi|_{t=0}) = (\eta_{in}, \psi_{in})$  has a unique solution

$$
(\eta,\psi) \in C^0([0,T];H^{s+\frac{1}{2}}_0(\mathbb{T})\times H^s(\mathbb{T}))
$$

satisfying

$$
(\eta|_{t=T}, \psi|_{t=T}) = (\eta_{final}, \psi_{final}).
$$

The proof uses in a crucial way known results about the Cauchy problem :

Nalimov, Yoshihara, Craig, Wu, Beyer–Günther

To quote only results concerning gravity-capillary waves :

Ambrose–Masmoudi, Shatah–Zeng, Coutand–Shkoller, Córdoba–Córdoba–Gancedo, Masmoudi–Rousset, Lannes, Pusateri, Christianson–Hur–Staffilani, A.– Burq–Zuily, Germain–Masmoudi–Shatah, Castro–Córdoba–Fefferman–Gancedo–Gómez Serrano, Fefferman–Ionescu–Lie, Coutand –Shkoller, Ifrim–Tataru, Ionescu–Pusateri, Shatah–Walsh–Zeng, de Poyferré–Nguyen, Deng–Ionescu–Pausader–Pusateri.

Linearized equation (neglect gravity):

$$
u = \psi - i|D_x|^{\frac{1}{2}}\eta
$$

satisfies the **dispersive** equation

$$
\partial_t u + i \left| D_x \right|^{\frac{3}{2}} u = P_{ext}.
$$

Similar diagonalization of the nonlinear equations, based on

- study in Eulerian coordinates (Zakharov, Craig-Sulem, Lannes)
- complete paralinearization of the equations (A-Métivier)
- Symmetrization (A-Burg-Zuily)
- normal forms (A-Delort; A-Baldi)

(Oversymplifying) One can rewrite the WW system as:

$$
\frac{\partial u}{\partial t} + V(u)\partial_x u + i |D_x|^{\frac{3}{4}} (c(u) |D_x|^{\frac{3}{4}} u) = P_{ext}
$$

where  $V, c$  are real-valued functions.

T. Alazard (ENS) [Control water-waves](#page-0-0) MSRI 11 / 23

The linearized system at the origin has constant coefficient and can be controlled by means of Fourier analysis, Reid (1995) or multipliers Biccari (2015). But this is not enough since the problem is quasi-linear. We seek  $P_{ext}$  as the limit of solutions to approximate control problems with variable coefficients.

The linearized system at the origin has constant coefficient and can be controlled by means of Fourier analysis, Reid (1995) or multipliers Biccari (2015). But this is not enough since the problem is quasi-linear. We seek  $P_{ext}$  as the limit of solutions to approximate control problems with variable coefficients.

Fix  $u = u(t, x)$  and consider

$$
P = \partial_t + V \partial_x + i \left| D_x \right|^{\frac{3}{4}} \left( c \left| D_x \right|^{\frac{3}{4}} \cdot \right)
$$

where  $V = V(\underline{u})$  and  $c = c(\underline{u})$  are real-valued and  $c - 1$  is small enough. Using a change of variables (preserving the  $L^2$ -norm in  $x$ )

$$
(1 + \partial_x \kappa(t, x))^{\frac{1}{2}} h(t, x + \kappa(t, x))
$$

we replace  $P$  by

 $Q = \partial_t + W\partial_x + i\,|D_x|^\frac{3}{2} + R\quad R$  is of order zero.

where one can further assume that  $\int_{\mathbb{T}} W(t,x)\,dx = 0$  .

• Nontrivial since the equation is nonlocal and cancellation of the term of order  $1/2$ .

To study  $\left. \partial_t + W \partial_x + i \left| D_x \right|^{\frac{3}{2}} + R'$  , we seek an operator  $A$  such that  $i\bigl[A,|D_{x}|^{\frac{3}{2}}\,\bigr]+W\partial_{x}A\quad$  is a zero order operator

We find (study of the standing wave problem A.-Baldi) an operator of the form 1

$$
A = \text{Op}\left(q(t, x, \xi)e^{i\beta(t, x)|\xi|^{\frac{1}{2}}}\right)
$$

with

$$
\beta = \beta_0(t) + \frac{2}{3}\partial_x^{-1}W.
$$

Then

$$
\left(\partial_t + W\partial_x + i\left|D_x\right|^{\frac{3}{2}}\right)A = A\left(\partial_t + i\left|D_x\right|^{\frac{3}{2}} + R''\right)
$$

with  $R''$  of order  $0$ .

To study  $\left. \partial_t + W \partial_x + i \left| D_x \right|^{\frac{3}{2}} + R'$  , we seek an operator  $A$  such that  $i\bigl[A,|D_{x}|^{\frac{3}{2}}\,\bigr]+W\partial_{x}A\quad$  is a zero order operator

We find (study of the standing wave problem A.-Baldi) an operator of the form 1

$$
A = \text{Op}\left(q(t, x, \xi)e^{i\beta(t, x)|\xi|^{\frac{1}{2}}}\right)
$$

with

$$
\beta = \beta_0(t) + \frac{2}{3}\partial_x^{-1}W.
$$

Then

$$
\left(\partial_t + W\partial_x + i\left|D_x\right|^{\frac{3}{2}}\right)A = A\left(\partial_t + i\left|D_x\right|^{\frac{3}{2}} + R''\right)
$$

with  $R''$  of order  $0$ 

Notice that  $A\in \mathrm{Op}\, S^0_{\rho,\rho}$  with  $\rho=1/2$  (quasi-linear). For Benjamin-Ono one has a similar conjugation but with  $A\in \mathrm{Op}\, S^0_{1,0}$  (semi-linear).

# Ingham type inequality

For some given real-valued function  $\,\beta \in C^3(\mathbb{R})$  , set

$$
\mu_n(t) = \text{sign}(n) \left[ |n|^{\frac{3}{2}}t + \beta(t)|n|^{\frac{1}{2}} \right].
$$

For any  $T \in (0,1]$  there are  $C(T)$  and  $\delta(T)$  such that, if

$$
\left\|(\partial_t \beta, \partial_t^2 \beta, \partial_t^3 \beta)\right\|_{L^\infty} \le \delta(T)
$$

then

$$
C(T) \sum_{n \in \mathbb{Z}} |w_n|^2 \le \int_0^T \left| \sum_{n \in \mathbb{Z}} w_n e^{i\mu_n(t)} \right|^2 dt.
$$

For  $\beta = 0$  : Ingham, Kahane, Ball-Slemrod, Haraux.  $\beta(t)|n|^{\frac{1}{2}}$  is sub-principal but not perturbative.

## Corollary (Observability)

Consider  $\omega \subset \mathbb{T}$  and  $T > 0$ . Assume v solves

$$
\partial_t v + V \partial_x v + i |D_x|^{\frac{3}{4}} (c |D_x|^{\frac{3}{4}} v) = 0, \quad v(0) = v_0
$$

with

$$
||V||_{C^0([0,T];H^s)} + ||c-1||_{C^0([0,T];H^s)} \leq \varepsilon_0.
$$

Then

$$
\int_0^T \int_{\omega} |v(t,x)|^2 \ dx dt \geq K \int_{\mathbb{T}} |v_0(x)|^2 \ dx.
$$

To obtain an Ingham inequality we used in an essential way the fact the equation is dispersive and the infinite speed of propagation  $(3/2 > 1)$ :

$$
\mu_n(t) = \text{sign}(n) \left[ |n|^{\frac{3}{2}}t + \beta(t)|n|^{\frac{1}{2}} \right].
$$

Now we consider the case without surface tension : Then one finds a similar equation with an exponent  $1/2 < 1$  and one does not expect the same result (high frequencies travel at a low speed).

## Microlocal  $(x,\xi) \rightarrow$  Global  $\int f(x)dx$

Some computations inspired by the works by Benjamin–Olver of the conservation laws for WW.

The only known coercive quantity is the energy :

$$
\mathcal{H} = \frac{g}{2} \int \eta^2(t, x) \, dx + \frac{1}{2} \iint_{\Omega(t)} |\nabla_{x,y} \phi(t, x, y)|^2 \, dx dy.
$$



The only known coercive quantity is the energy :

$$
\mathcal{H} = \frac{g}{2} \int \eta^2(t, x) \, dx + \frac{1}{2} \iint_{\Omega(t)} |\nabla_{x,y} \phi(t, x, y)|^2 \, dx dy.
$$



Estimate  $H$  by looking only at the motion of some of the curves of contact between the free surface and the vertical walls?

## Theorem (A. 2015)

Recall  $\psi(t, x) = \phi(t, x, \eta(t, x))$ . Set  $\Theta := -\eta \partial_t \psi - \frac{g}{2}$  $rac{9}{2}\eta^2$ . Let  $\chi \in C_0^{\infty}((0,\pi)^2)$ . There exist  $K_0,\kappa,c$  s.t., for any  $N$  in  $\mathbb N$ , it  $\eta_0, \psi_0 = \chi(x) \quad \sum \quad a_{nm} \cos{(nx_1)} \cos{(mx_2)} \quad \textit{with} \quad |a_{nm}| \le c N^{-\kappa},$  $|n|+|m|\leq N$ 

then the solution exists on  $[0,T_N]$  with  $T_N=K_0+K_0 N^{\frac{1}{2}+\varepsilon}$  and

$$
\int_0^{T_N} \left[ \int_0^{\pi} \Theta(t, \pi, x_2) dx_2 + \int_0^{\pi} \Theta(t, x_1, \pi) dx_1 \right] dt \ge \mathcal{H}.
$$

Sharp: a wave-packet travels at a speed  $\,1/$ √ Sharp: a wave-packet travels at a speed  $1/\sqrt{N}$  and might take a time  $\sqrt{N}$  to reach the boundary.



Consider a smooth enough solution of the water waves equations which is independent of  $x_2$ . Introduce

$$
m(t)=\eta(t,\pi).
$$

Then

$$
\Theta(t,\pi) := \Big( -\eta \partial_t \psi - \frac{g}{2} \eta^2 \Big) (t,\pi) = \frac{1}{2} \big[ gm(t)^2 - m(t) m'(t)^2 \big].
$$

Example: consider the 1D wave eq with Dirichlet boundary condition:

$$
\partial_t^2 u - \partial_x^2 u = 0
$$
,  $u(t, 0) = u(t, 1) = 0$ .

Multiply the equation by  $x\partial_x u$  and integrate by parts

$$
\int_0^T (\partial_x u(t,1))^2 dt = 2 \int_0^1 (\partial_t u)(x \partial_x u) dx \Big|_0^T + \iint_S \left[ (\partial_t u)^2 + (\partial_x u)^2 \right] dx dt
$$

where  $S = (0, T) \times (0, 1)$ . Since

$$
\left| \int_0^1 (\partial_t u)(x \partial_x u) dx \right| \leq \mathcal{E} := \frac{1}{2} \int_0^1 \left[ (\partial_t u)^2 + (\partial_x u)^2 \right] dx,
$$

and  $d\mathcal{E}/dt = 0$ , one has

$$
\int_0^T (\partial_x u(t,1))^2 dt \ge (T-2) \int_0^1 \left[ (\partial_t u)^2 + (\partial_x u)^2 \right] (0,x) dx.
$$

#### Lemma

For smooth enough solutions, the following property holds: With  $m(t) = \eta(t, \pi)$  and  $\Theta(t, \pi) = \frac{1}{2}$  $\left[gm(t)^2 - m(t)m'(t)^2\right]$  one has

$$
\pi \int_{0}^{T} \Theta(t,\pi) dt = \frac{T}{2} \mathcal{H}
$$
\n
$$
+ \frac{\pi}{2} \int_{0}^{T} \int_{-h}^{m(t)} (\partial_{y} \phi)^{2} (t, \pi, y) dy dt
$$
\n
$$
+ \frac{1}{2} \int_{0}^{T} \int_{0}^{\pi} \left( h + \frac{7}{4} \eta \right) (\partial_{x} \phi)^{2} (t, x, -h) dx dt
$$
\npositive  
\n
$$
- \frac{1}{4} \int_{0}^{\pi} \eta \psi dx \Big|_{t=0}^{t=T} - \int_{0}^{\pi} x \eta \partial_{x} \psi dx \Big|_{t=0}^{t=T}
$$
\nboundary  
\n
$$
- \frac{7}{4} \int_{0}^{T} \iint_{\Omega(t)} (\partial_{x} \eta) (\partial_{x} \phi) (\partial_{y} \phi) dx dy dt
$$
\nremainder.

Multiplier method used in this way: Compute, by two different methods,  $I := \int$  $[0,T]\times[0,\pi]$  $[(\partial_t \eta)(x \partial_x \psi) - (\partial_t \psi)(x \partial_x \eta)] dx dt$ 

Method 1: Integration by parts / Method 2 : write

(Craig-Sulem-Zakharov) 
$$
\partial_t \eta = \frac{\delta \mathcal{H}}{\delta \psi}, \quad \partial_t \psi = -\frac{\delta \mathcal{H}}{\delta \eta},
$$

to observe that

$$
I = \iint_{[0,T] \times [0,\pi]} \left[ x \psi_x \frac{\delta \mathcal{H}}{\delta \psi} + x \eta_x \frac{\delta \mathcal{H}}{\delta \eta} \right] dx dt.
$$

Then use Lannes' derivative formula for the DN to obtain

$$
\frac{1}{2} \int \left[ m(t)^2 - m(t) m'(t)^2 \right] dt = \frac{T}{2} \mathcal{H}
$$
  

$$
- \frac{1}{4} \int \eta \psi \, dx \Big|_{t=0}^{t=T} - \int x \eta \partial_x \psi \, dx \Big|_{t=0}^{t=T}
$$
  
+ R

with

$$
R := \iint \left[ \frac{3}{8} \eta \left( V^2 + 2B V \partial_x \eta - B^2 \right) + \frac{1}{2} (G(\eta) \psi) x V + \frac{1}{2} B(x \psi_x) \right] dx dt.
$$

with

$$
R := \iint \left[ \frac{3}{8} \eta \left( V^2 + 2B V \partial_x \eta - B^2 \right) + \frac{1}{2} (G(\eta) \psi) x V + \frac{1}{2} B(x \psi_x) \right] dx dt.
$$

Guided by Benjamin–Olver, use

$$
\int u(x, \eta(x)) dx + \int f(x, \eta(x)) \partial_x \eta dx
$$
  
= 
$$
\iint (\partial_y u - \partial_x f) dy dx + \int u(x, -h) dx + \int f dy \Big|_{x=0}^{x=\pi}.
$$

Then

$$
R = \frac{1}{2} \int_0^T \int_{-h}^{m(t)} (\partial_y \phi)^2(t, 1, y) dy dt
$$
  
+ 
$$
\frac{1}{2} \int_0^T \int_0^1 \left( h + \frac{7}{4} \eta \right) (\partial_x \phi)^2(t, x, -h) dx dt
$$
  
- 
$$
\frac{7}{4} \int_0^T \iint_{\Omega(t)} (\partial_x \eta) (\partial_x \phi) (\partial_y \phi) dx dy dt.
$$

$$
\int_0^{\pi} \left| |D_x|^{\frac{1}{2}} \psi \right|^2 dx \lesssim \frac{1}{2} \iint_{\Omega(t)} |\nabla_{x,y} \phi(t,x,y)|^2 dx dy \le \mathcal{H}.
$$

## **Corollary**

 $\tau$ 

Assume that

$$
|\partial_x \eta(t,x)| \le \frac{1}{7}, \quad T \ge 4 + \frac{20\pi}{\sqrt{g}}A, \quad ||\partial_x \psi||_{L^2} \le \sqrt{2}A |||D_x|^{\frac{1}{2}} \psi||_{L^2}.
$$
  
then  

$$
\pi \int_0^T \Theta(t,\pi) dt \ge \mathcal{H}.
$$

<span id="page-33-0"></span>The assumption for  $\left\|\partial_x\psi\right\|_{L^2}$  holds at  $t = 0$  with  $A = K$ √  $N$  if the Fourier transform of  $\psi(0)$  is supported in  $[-N, N]$ . Moreover, for small data, one can propagate the estimate  $\|\partial_x\psi(0)\|_{L^2}\lesssim K\sqrt{N}\,\|\psi(0)\|_{\dot{H}^{1/2}}$  on large time intervals of size  $\sqrt{N}$ . Thank you!