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Harmonic quasismetries,  
w/ Yves Benoist.

$X, Y$ : Riemannian mfd.

$X \xrightarrow{f} Y$  smooth is HARMONIC

$\Leftrightarrow f$  is a critical point for  
 $E(h) = \frac{1}{2} \int |Dh|^2$

$\Leftrightarrow f$  is a tension  $\tau(h) = \text{Tr}(D^2h) = 0$

Examples:

- geodesics (constant speed)
- Riemannian immersion

$N \xrightarrow{i} M$  with  
 $i(N) \subset M$  minimal

$\mathbb{R}^n$ : harmonic  $\nrightarrow$  isometric.

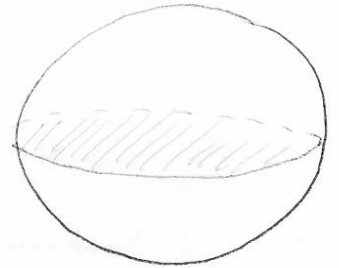
- $\mathbb{R}^n \setminus 0 \rightarrow \mathbb{S}^{n-1}$   
is harmonic.

a quasi isometry  $X \xrightarrow{f} Y$  is a  
map b/w metric spaces st  $\exists c \geq 1$  st

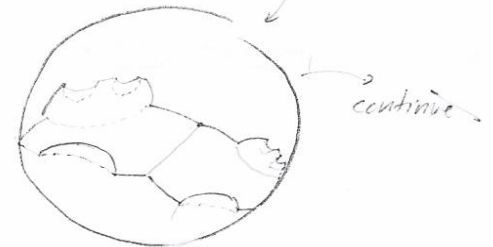
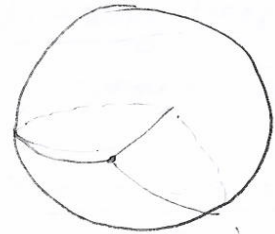
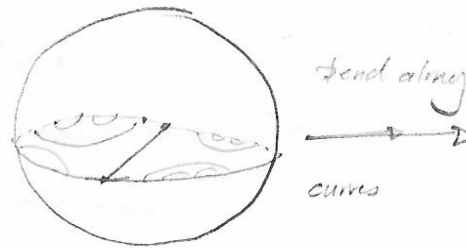
$$\frac{1}{c} d(x, y) - c \leq d(f(x), f(y)) \leq c d(x, y) + c$$

Example.

- $\mathbb{H}^2 \subset \mathbb{H}^3$   
totally geodesic



- quasi-Fuchsian surface,  
(and intermediates)



see image by Jeff Brock.

"bug"

proof sketch:

(1) can smooth  $f$  s.t.  
 $\|Df\| \leq \epsilon$ , and  $\|D^2f\| \leq \epsilon$

(2) for fixed point  $x_0 \in X$ , and  $R > 0$

$\exists$  unique map  $B_R(x_0) \xrightarrow{h_R} Y$

$h_R$  is harmonic, s.t.

$$h_R|_{\partial B_R(x_0)} = f|_{\partial B_R(x_0)}$$

Schoen + Hamilton  $\Rightarrow h_R \in C^\infty(\bar{B}_R)$   
 and  
Schoen + Uhlenbeck

(3)  $d(h_R, f) \leq M$  uniform bound.

(4) compactness result of Luckhaus  $\Rightarrow h_R \rightarrow h$   
 and  
 $d(h, f) \leq M$ .

careful step for

$$X = \mathbb{H}^2, Y = \mathbb{H}^3$$

$$\mathbb{H}^2 \xrightarrow{f} \mathbb{H}^3$$

(1) for  $x \in X$ , smooth  $f$  to

$\tilde{f}: x \mapsto$  "center of mass" of  $f(B(x, 1))$

$$\alpha \in C_c^\infty((-1, 1)), \alpha \geq 0.$$

$$\bar{\Phi}_x: y \in \mathbb{H}^3 \mapsto \int_{\mathbb{H}^2} \underbrace{\alpha(d(x, z))}_{\text{mass} = 1} \cdot d(y, f(z))^2 dz.$$

$\tilde{f}(x) =$  the unique point  $y \in \mathbb{H}^3$  s.t.  
 $\bar{\Phi}_x$  is minimal at  $y$ .

$\bar{\Phi}_x$  is proper  $\mathbb{H}^3 \rightarrow \mathbb{R}$ .

nonpositive curvature:

$$m \in \mathbb{H}^3 \quad d_m(\cdot) = d(\cdot, m)$$

$d_m^2$  is strictly convex,  $D^2 d_m^2 \geq 2g$

exists since.

Claim:  $\tilde{f}$  is smooth

here need bounded second derivative.

- use implicit function theorem.

$$(x, y) \in \mathbb{H}^2 \times \mathbb{H}^2$$

$$\begin{array}{l} \psi \\ \Downarrow \\ \mathcal{D}_y \Xi_x \end{array} \Rightarrow \psi(x, y) = 0 \text{ when } y = f(x). \quad //$$

remains to see  $d(f, \tilde{f}) < \infty$ .

$\mathbb{H}^2$  is non-positively curved.

$\Downarrow$   
geodesic balls are convex

$$\text{so } f(B(x, 1)) \subset B(f(x), 2c).$$

end proof of ① //

proof of ②

$f: \mathbb{H}^2 \rightarrow \mathbb{H}^2$  smooth g.i. map.

$$\text{with } |Df| \leq c, \quad |D^2 f| \leq c.$$

$h_R = \text{map on } B(x, R)$

$$\text{need } d(f, h_R) \leq M.$$

$\Uparrow$

Boundary estimates:

$\exists$  constant  $k$  w.r.t.  $c$ , so that

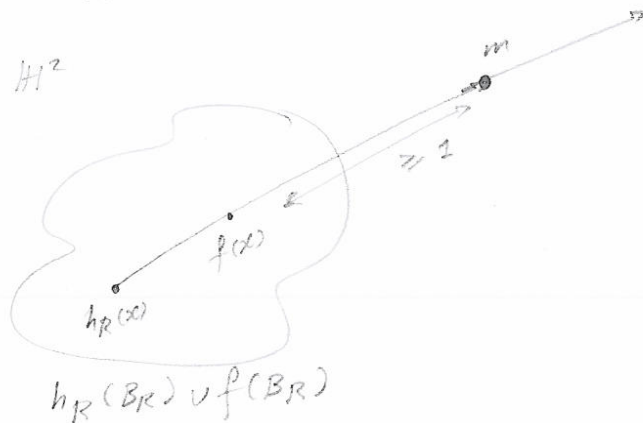
$\forall R > 0$  and  $x \in B(0, R)$

$$d(f(x), h_R(x)) \leq k \cdot d(x, \partial B_R).$$

Rk: need only bounds on 1st and 2nd derivatives, and not that  $f$  is a g.i. map.

Pf // due to Jost.

pick geodesic ray through  $h_R(x)$  and  $f(x)$ .



$$d(f(x), h_R(x)) = d_m(h_R(x)) - d_m(f(x))$$

since convex.

Thus,

$$\text{Let } u: y \in \mathbb{H}^3 \mapsto [d_m(h_R(y)) - d_m(f(y))] - [k \cdot d(y, \partial B_R)]$$

suffices to show  $u(x) \leq 0$ .

can show this on whole ball.

•  $u = 0$  on  $\partial B_R$  by construction.

•  $k$  large enough

$$\Rightarrow \Delta u \leq 0.$$

so

$$\begin{aligned} \mathcal{D}^2(d_m \circ h_R) &= \overbrace{\mathcal{D}^2 d_m(Dh_R, Dh_R)}^{\geq 0} \\ &\quad + \underbrace{\mathcal{D} d_m(D^2 h_R)}_{\text{trace} = 0}. \end{aligned}$$

so

$$\Delta d_0 \geq 1 \quad \text{in weak sense}$$

$$\Delta u = (\Delta \geq 0) - (|\Delta| \leq k)$$

$$- (\Delta \geq k)$$

□