

how far can bayesian theories of vision take us?

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It takes just one quick glance to see the fox, a tree trunk, some grass and background twigs.

but the longer we look the more we see...

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“One can see that there is an animal, a fox--in fact a baby fox. It is emerging from behind the base of a tree not too far from the viewer, is heading right, high-stepping through short grass, and probably moving rather quickly. Its body fur is fluffy, reddish-brown, relatively light in color, but with some variation. It has darker colored front legs and a dark patch above the mouth. Most of the body hairs flow from front to back...and what a cute smile, like a dolphin.”

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two computational problems



Ambiguity: To be sure about any small piece, the visual system has to understand the larger context

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two computational problems



Versatility: To make an unlimited variety of inferences, to generalize, the visual system needs to represent and access information across multiple scales, feature types and transformations

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Inferences about the fox picture involved various:

- levels of abstraction
- spatial scales
- feature types (shape, material)
- relationships between parts, objects, and viewer

A strong “bayesian” assumption is that reliable and versatile visual inferences are based on structured generative, probabilistic knowledge of how virtually any natural image could be produced

...but doesn't specify what the generative factors are, how they should be used, structured in the brain, or the mechanisms that underly their inferences

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working hypothesis

Hierarchical computations within and between visual cortical areas reflects

- the rich, probabilistic, generative structure of image input,

constrained by

- the generative factors important for behavioral outcomes (hardwired or dynamic)

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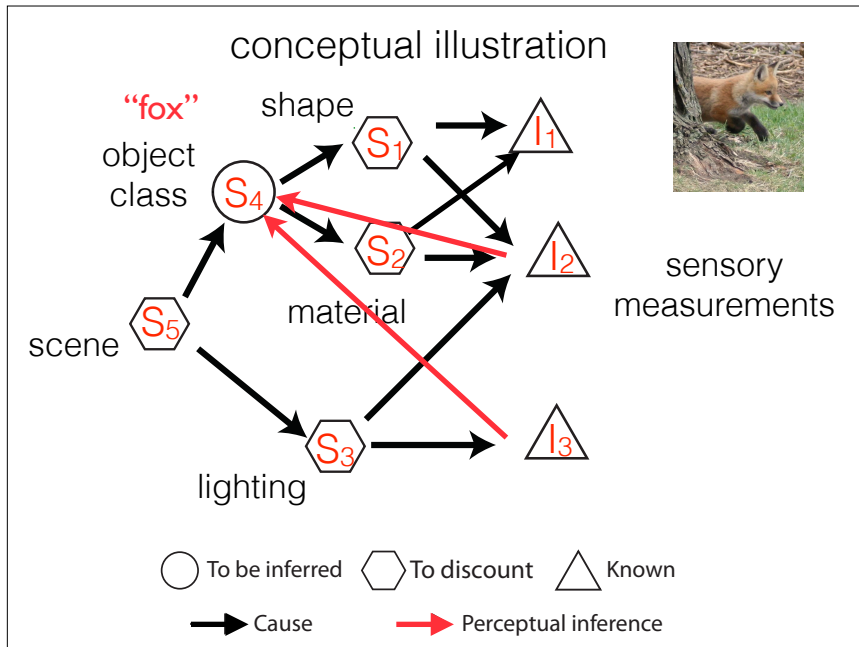
the basics

knowledge of the relationships between generative factors, $S = (S_1, S_2, \dots)$ and image patterns $I = (I_1, I_2, \dots)$ are represented probabilistically:

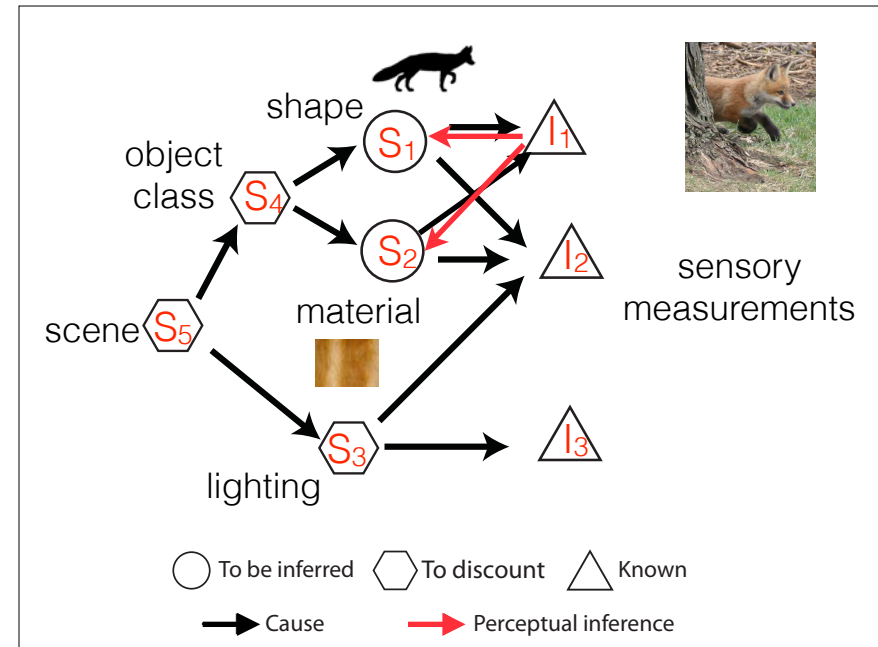
joint $p(S_1, S_2, \dots; I_1, I_2, \dots)$
posterior $p(S_1, S_2, \dots | I_1, I_2, \dots)$
 \propto likelihood x prior $p(I_1, I_2, \dots | S_1, S_2, \dots) \times p(S_1, S_2, \dots)$

- conditional dependencies structure complex distributions
- the task determines which variables to discount and thus sum over, and the image measurements which variables to fix, and thus condition the posterior
- factoring the posterior into likelihood and prior makes the generative knowledge explicit
- decisions are based on operations over the resulting “simplified” posterior

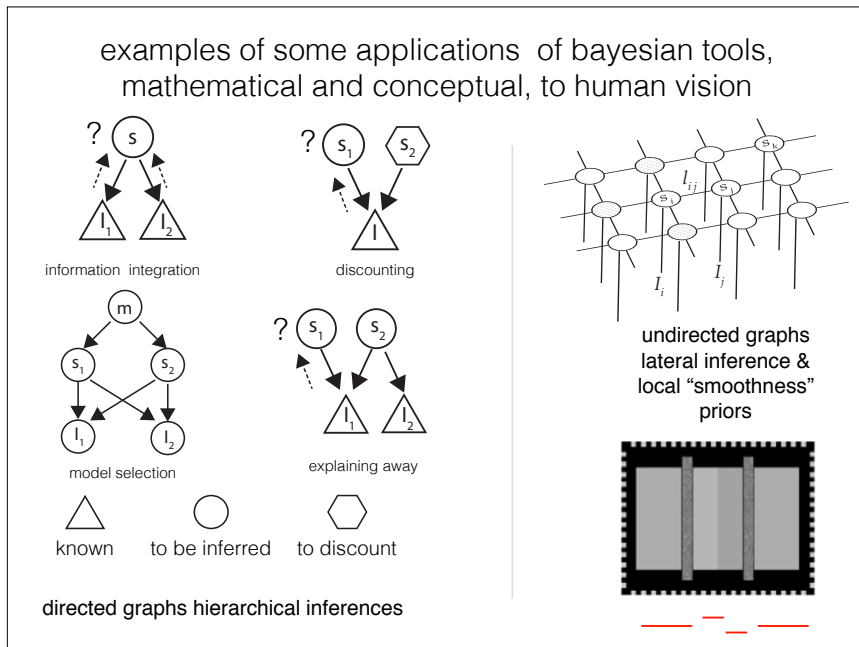
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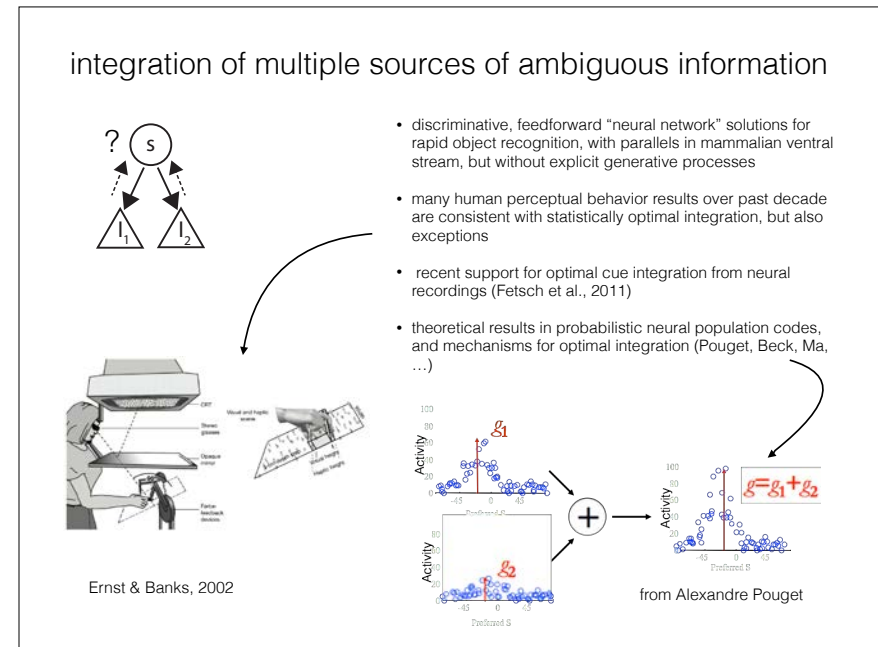
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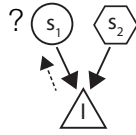


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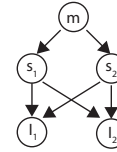
integrating out unwanted information



- core problem of “object constancy”, recognition, ...
- implicit in training of feedforward “neural network” solutions for object recognition, e.g. discounting variations in appearance.
- long history in ideal observer analysis of human vision, with applications, e.g. human color constancy
- theoretical results in active marginalization using probabilistic neural population codes (Beck et al., 2011)

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model-dependent human parameter estimation

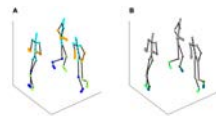
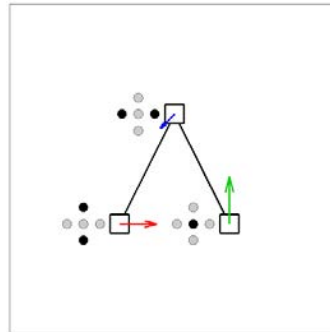


slant of the scree field?

- human estimation of surface slant from texture—model averaging of isotropic and homogeneous texture models (Knill, 2003)
- vision/auditory localization of sound — model selection (Kording et al., 2007)
- conditioned perception. (Stocker & Simoncelli, 2008)
- human velocity estimation depends on the optic flow category. Wu, S., Lu, H., & Yuille, A. (2008)

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flexible summaries of hierarchical motion structure

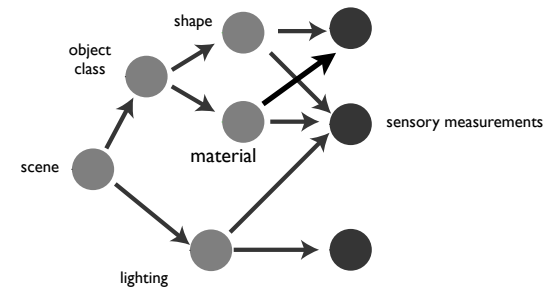


<https://sites.google.com/site/hierarchicalmotionperception/home>

Gershman, S. J., Tenenbaum, J. B., & Jakiel, F. (2015). Discovering hierarchical motion structure. *Vision Research*, 1–10. <http://doi.org/10.1016/j.visres.2015.03.004>

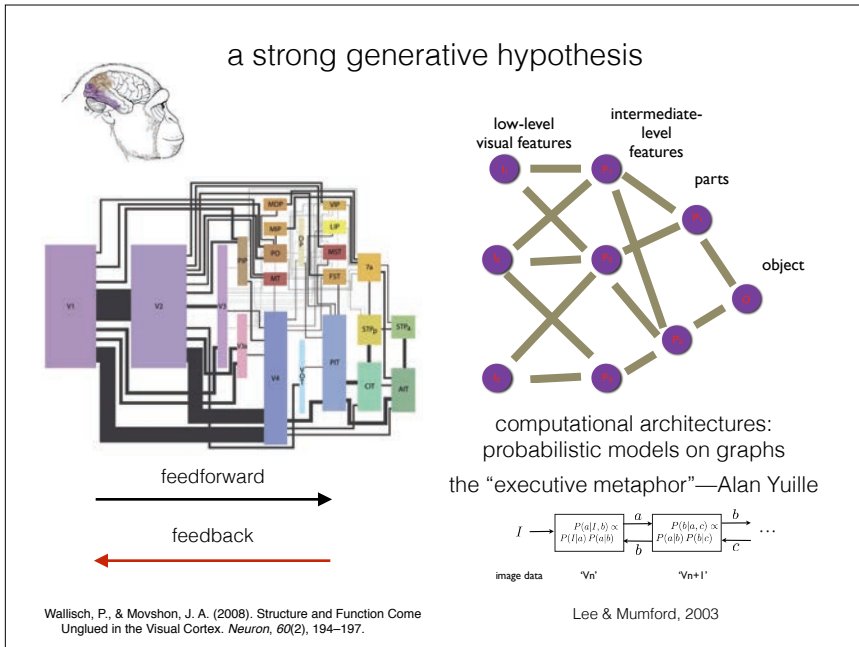
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so far these are applications of bayesian concepts/tools to model perceptual behavior

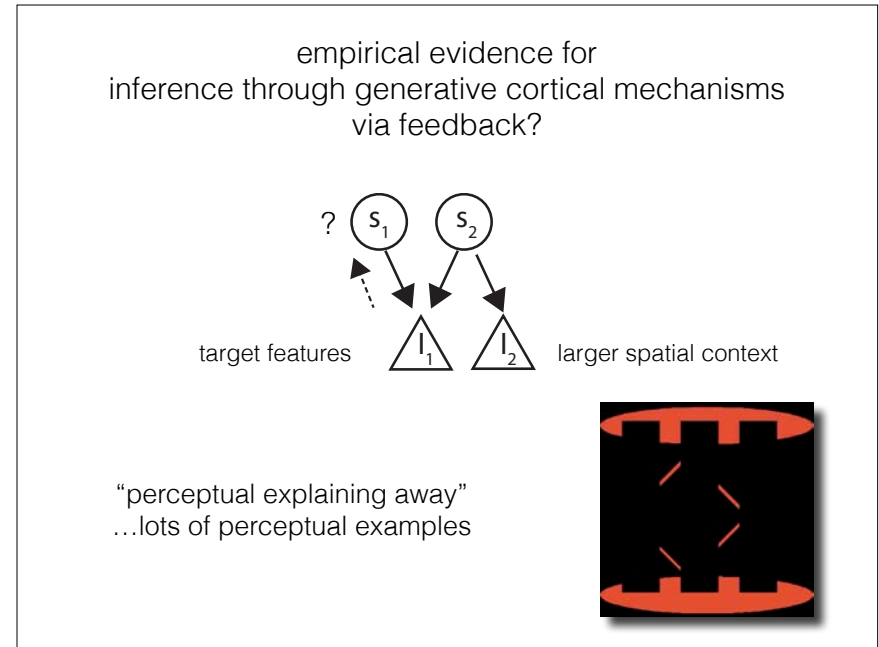


Can the black arrows just be used to represent the confounding variables for the problem to be solved? Or are human visual inferences based on feedback mechanisms that operate on internal generative models of the world?

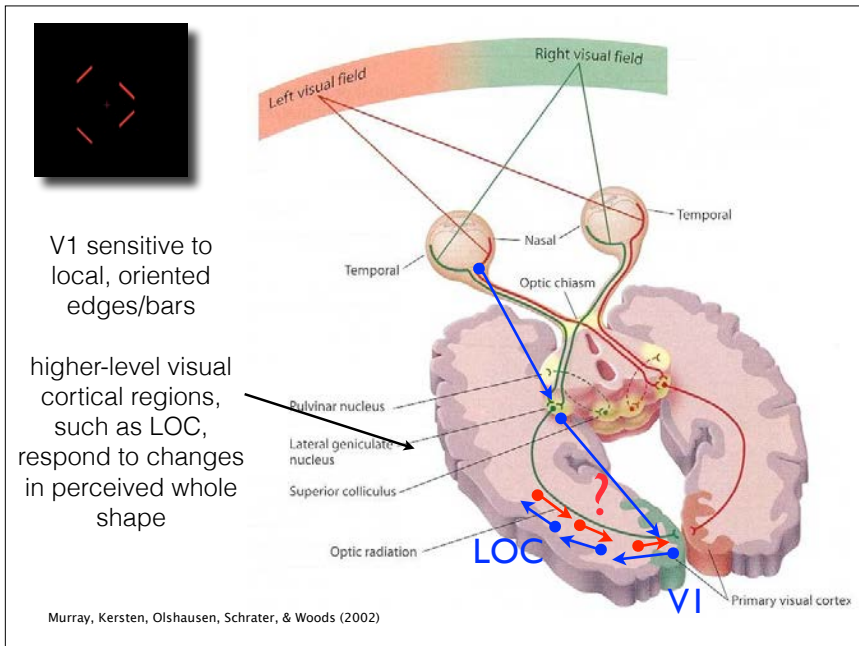
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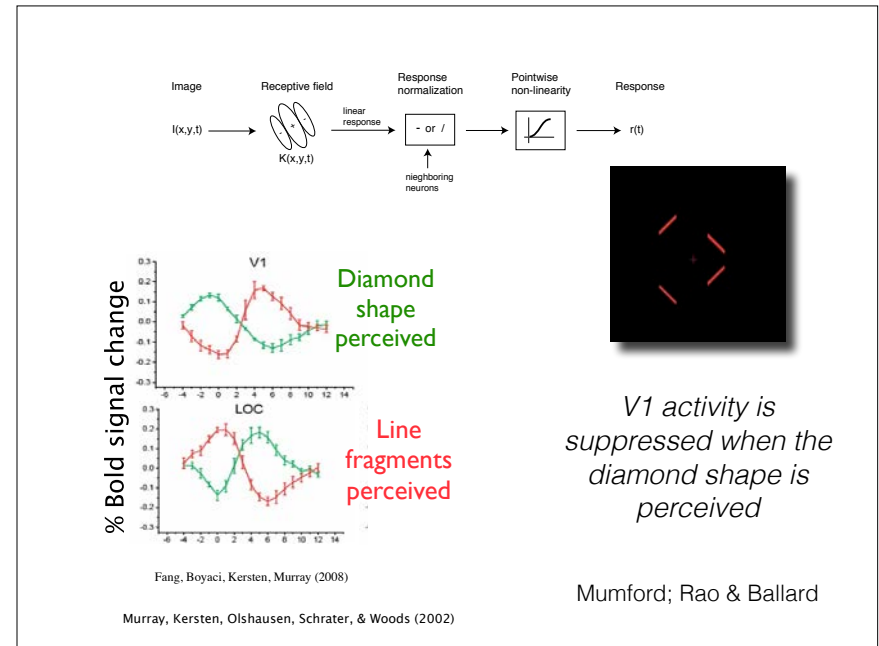
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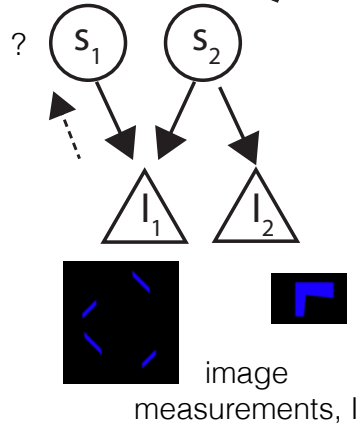
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“explanations”, S



stimulus

diamond percept
also coupled with
illusory bar contours
that rotate



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...but is modulation spatially localized to voxels in V1 that correspond retinotopically to the target features?

.. some fMRI results suggest not (cf. Wit et al., 2012)

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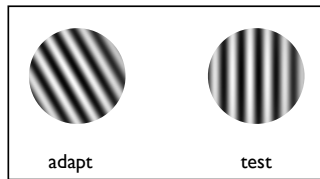
psychophysical test of modulation?

use adaptation--psychophysicist's “electrode”

assumption:
adapts neurons
in early cortical
areas, V1

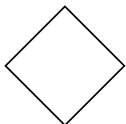


vertical
appearance

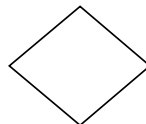
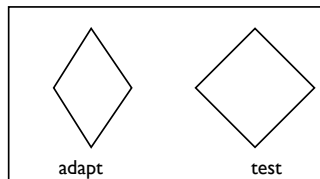


tilted
appearance

assumption:
adapts high-
level cortical
areas



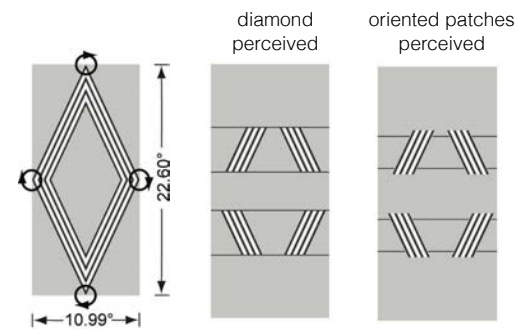
normal
appearance



fattened
appearance

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We found opposite modulation of high- and low-level visual aftereffects as a consequence of perceptual grouping



Perceptual grouping (“diamond percept”) reduces the strength of adaptation to local tilt, while amplifying the effect of adaptation to a whole shape, consistent with localized lower-level, feature-specific modulation.

He, D., Kersten, D., & Fang, F. (2012). Opposite modulation of high- and low-level visual aftereffects by perceptual grouping. *Current Biology*, 22(11), 1040–1045.

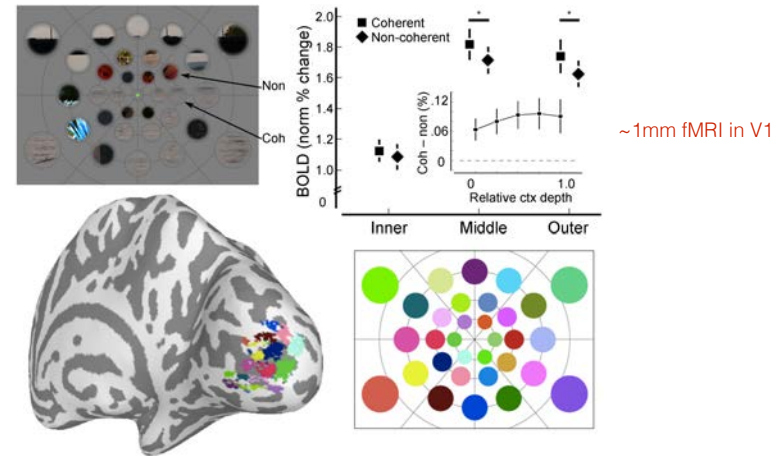
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...but we haven't always found localized suppression when local patches "fit" the larger context



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some patches are consistent with scene (Coh) and some not (Non)

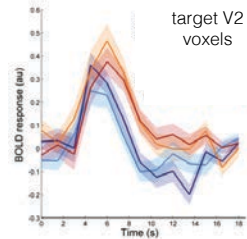
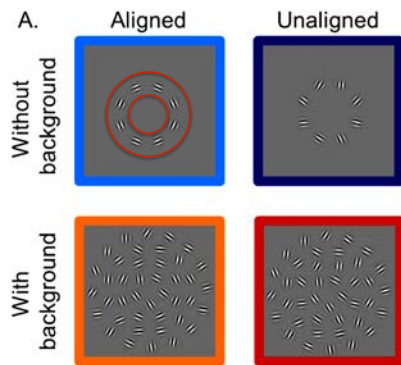


Mannion, Kersten & Olman

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perhaps context-dependent suppression of V1 voxel activity depends the complexity of the parsing/segmentation problem?

~2mm fMRI in V1

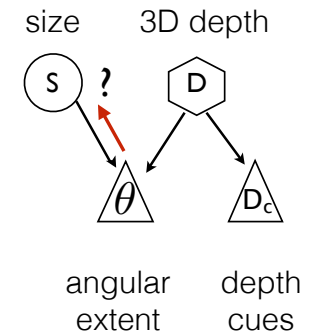
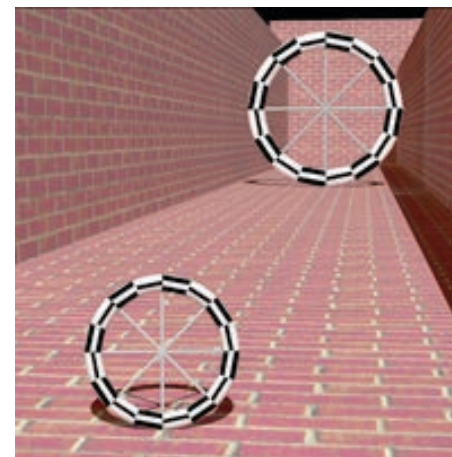


With background clutter, there was evidence of increased V1-V2 correlations when perceiving aligned versus when perceiving unaligned contours.

Responses in early visual areas to contour integration are context dependent. Cheng Qiu, Philip Burton, Daniel Kersten, Cheryl A. Olman

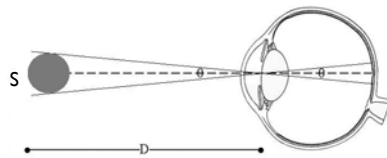
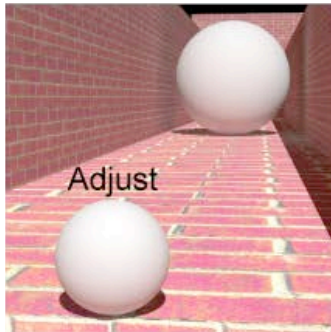
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inferring the size of an object



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perceptual estimation of the size of an object



$$\theta \approx S/D$$

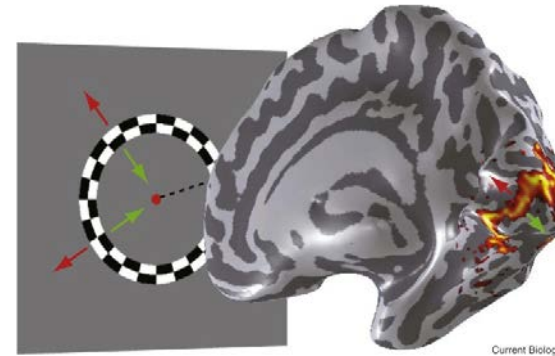
Perceptual effect: ~17%

<http://vision.psych.umn.edu/users/boyaci/Vision/SizeAppletLarge.html>

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does 3D context modulate the size of the “neural image” in human V1?

V1 has a retinotopic map, so for an actual increase in ring size in the image, we expect:

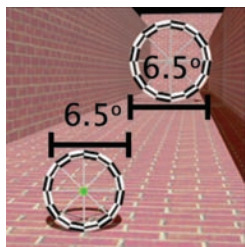


Current Biology

Huk, A. C. (2008) Visual Neuroscience: Retinotopy meets Percept-otopy, Current Biology, 18, 21, R1005-1007.

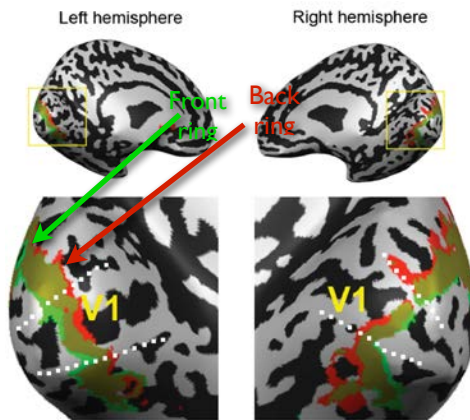
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what was found for an illusory increase in ring size



Fang, Boyaci, Kersten, & Murray, S. O. (2008). Attention-dependent representation of a size illusion in human V1. Current Biology

Ni, A. M., Murray, S. O., & Horwitz, G. D. (2014). Object-Centered Shifts of Receptive Field Positions in Monkey Primary Visual Cortex. Curbio, 1-6



attend-to-ring condition

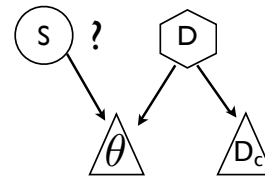
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in terms of inference, what might be going on?

two possible representational assumptions:
physical or angular size?

$$\theta \approx S/D$$

object size depth



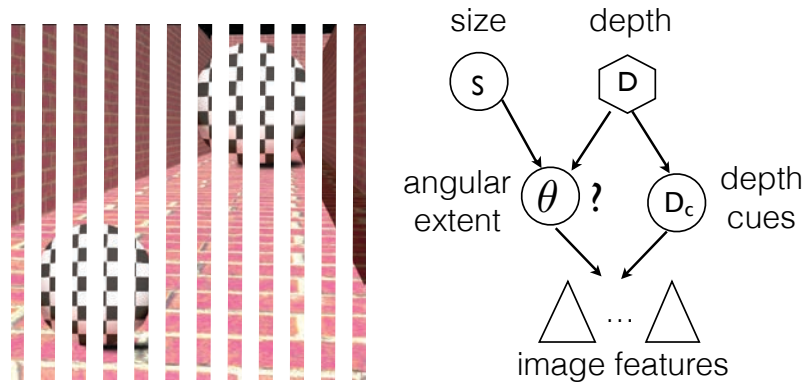
angular extent

depth cues

Does the shift of spatial extent in V1 represent the neural representation of an estimate of physical size (S) or a bias in the estimate of angular size (θ)?

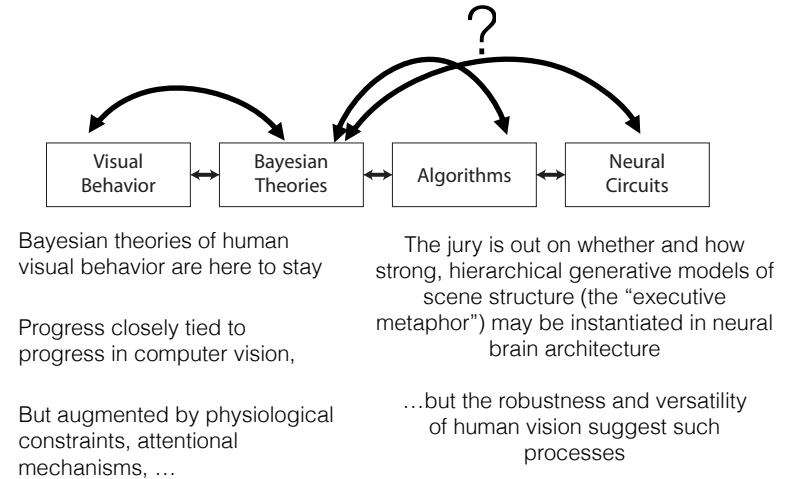
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estimating angular size is also a non-trivial inference



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how far can bayesian theories of vision take us?



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Bayes provides conceptual tools for managing uncertainty given specific task requirements at an abstract level...but we need more.

In particular, a better understanding of human-oriented generative models, compositional structure, and the algorithms/control structures for accessing information for a enormously diverse range of tasks



To explain how the longer we look, the more we see

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 Cheng Qiu, U Minnesota
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