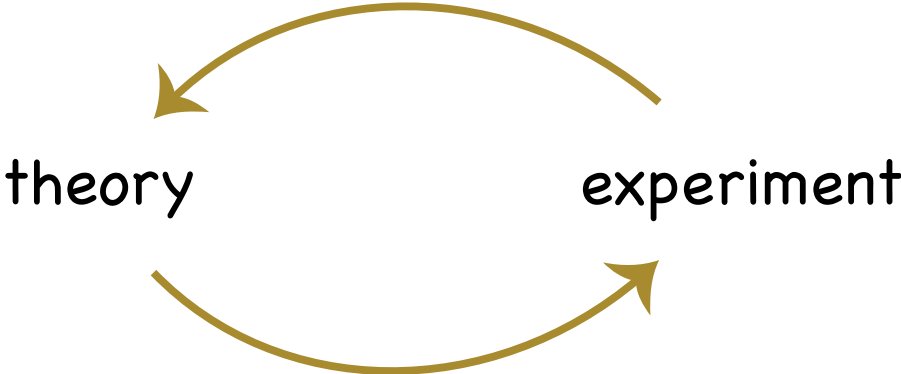


# Bringing math into the loop

Carina Curto  
Dept. of Mathematics &  
Center for Neural Engineering  
Penn State  
ccurto@psu.edu

MSRI Theory of Neural Computation Workshop  
October 7, 2015

# Neuroscience



# Neuroscience



mathematics

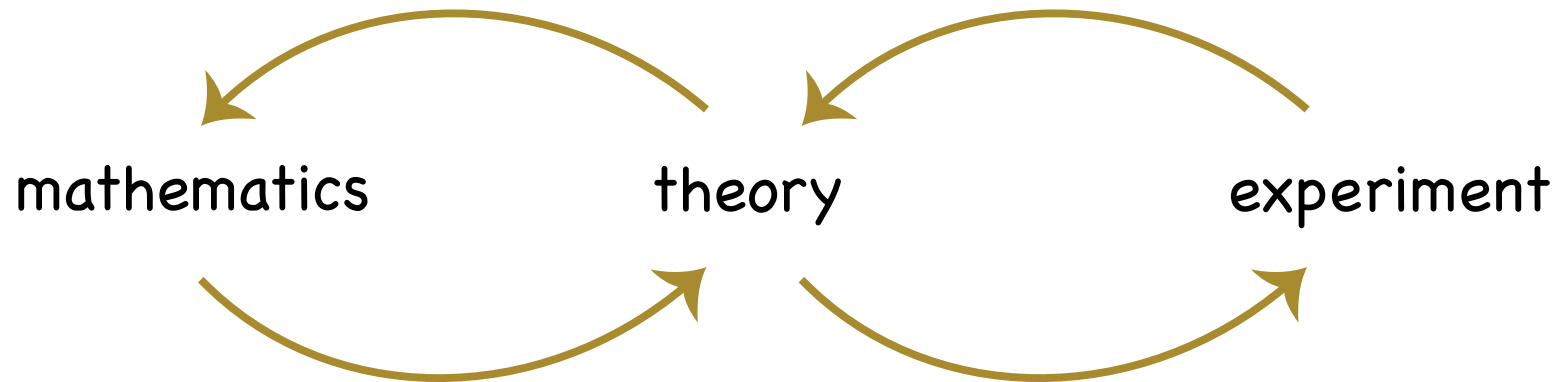


theory

experiment

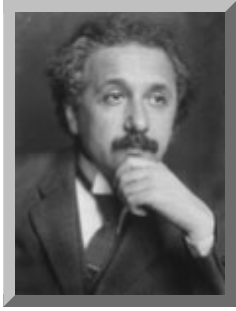


# Physics

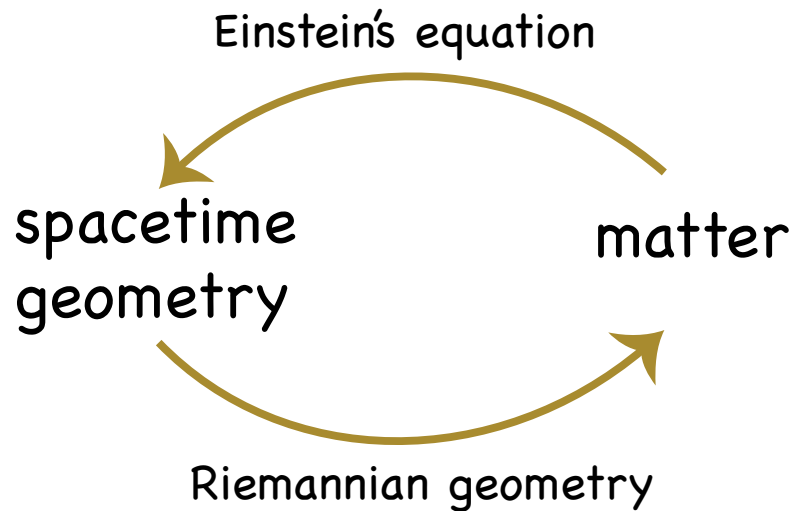


Sometimes the **mathematical technology** was just sitting there, and sometimes it had to be developed in tandem with theory.

# 100<sup>th</sup> anniversary of General Relativity

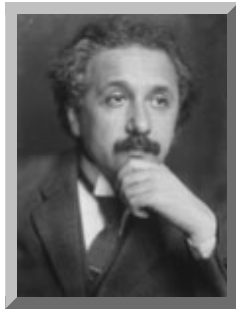


An international conference to celebrate 100 years of general relativity will be held at the University Park campus from Sunday, June 7 through Friday, June 12, 2015 under the auspices of the International Society on General Relativity and Gravitation (ISGRG) and the Topical Group on Gravitation (GGR) of the American Physical Society.

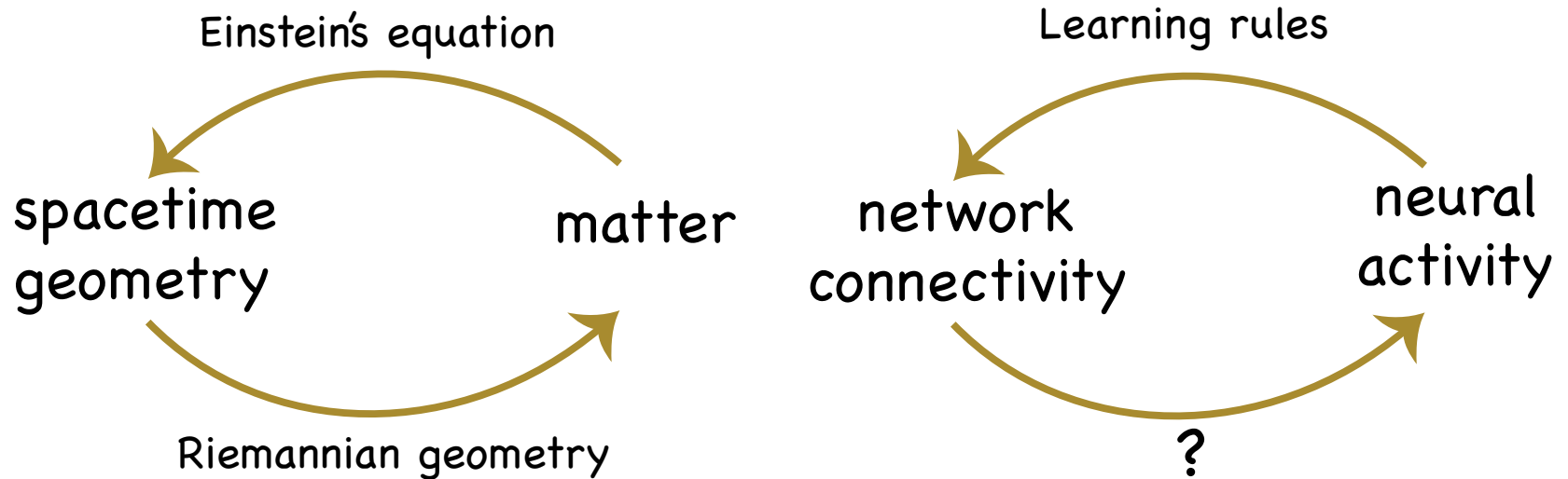


"Spacetime (geometry) tells matter how to move; matter tells spacetime how to curve." - John Archibald Wheeler

# 100<sup>th</sup> anniversary of General Relativity



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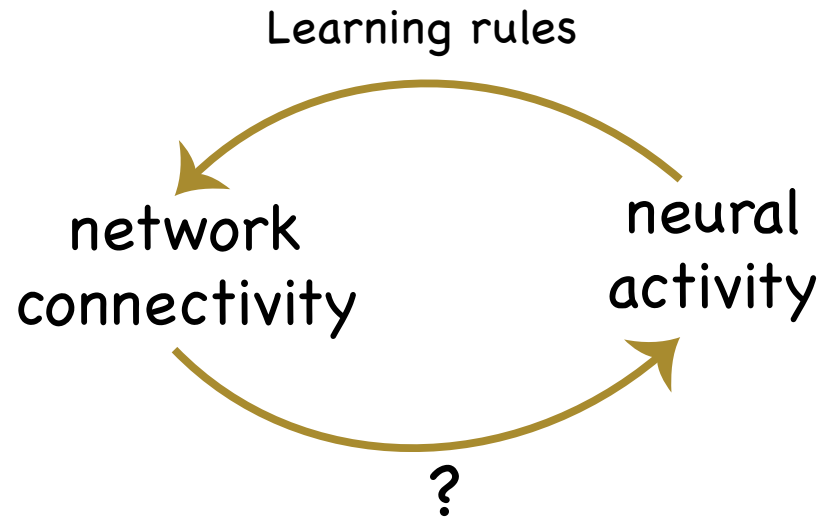
# Plan of the talk

I will present 2 examples where I think we can benefit from bringing mathematics into the loop.

Part I: network dynamics

Part II: data analysis

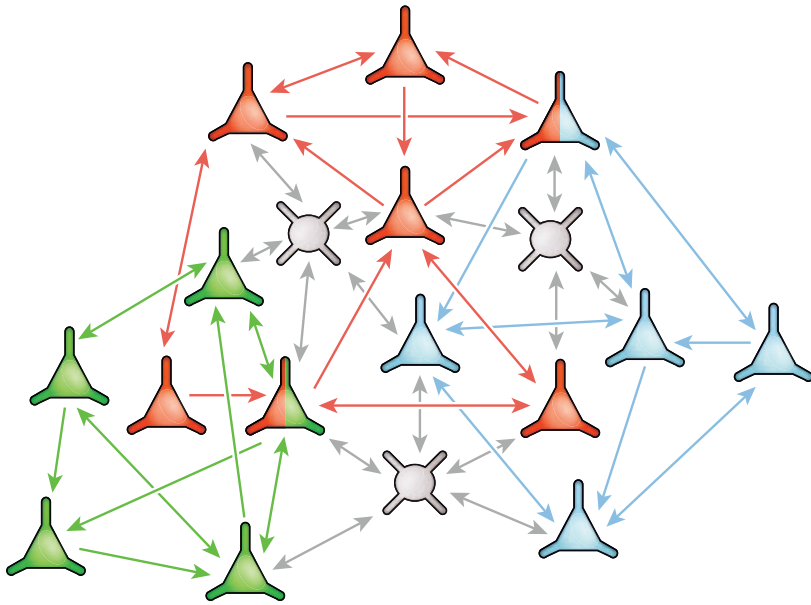
# Part I: network dynamics



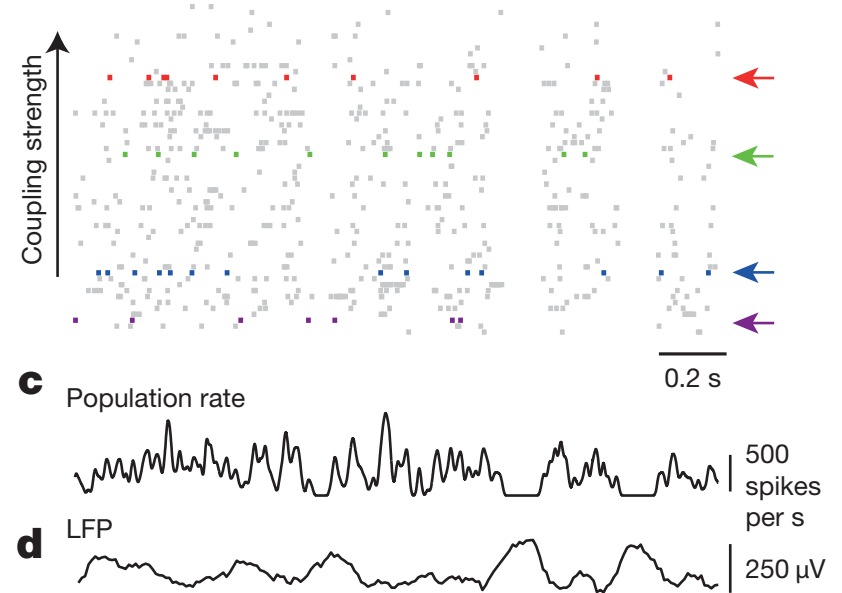
Motivating Question: How does recurrent connectivity shape population activity?



# Recurrent network dynamics (cortex)

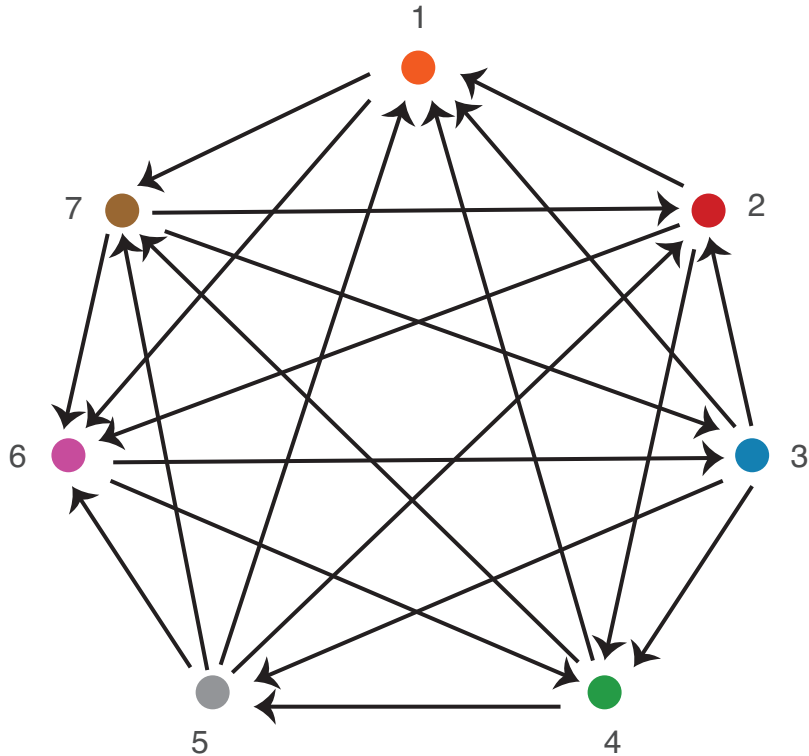


Cortical connectivity and sensory coding  
K.D. Harris & T.D. Mrsic-Flogel, Nature 2013 (Review)



Diverse coupling of neurons to populations  
in sensory cortex. Okun et al., Nature 2015

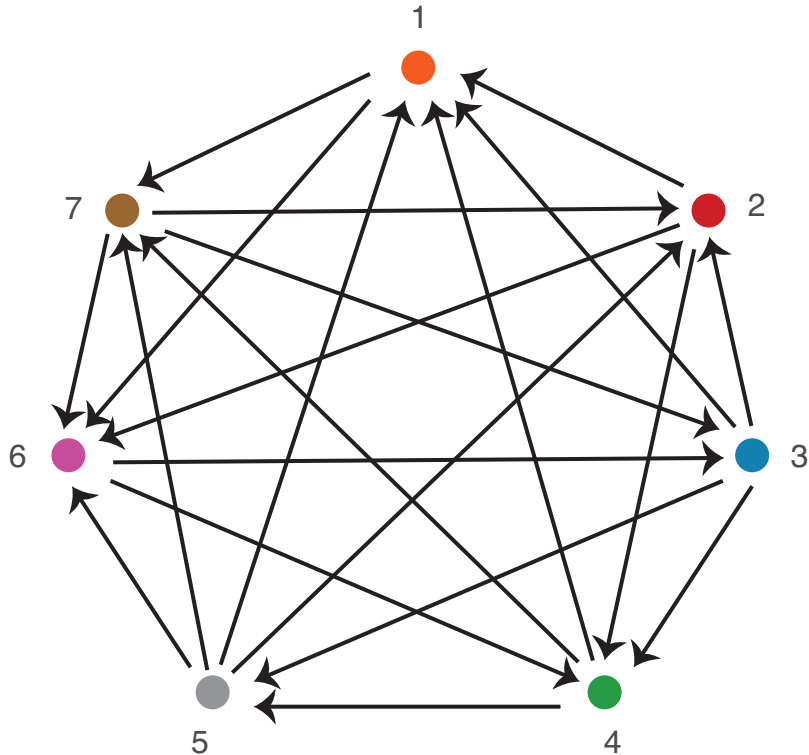
# What does connectivity tell us about dynamics?



Suppose we had the connectome for a network.

Q: What can we say about the dynamics?

# What does connectivity tell us about dynamics?



Suppose we had the connectome for a network.

Q: What can we say about the dynamics?

A: It's complicated.

complex synapses  
intrinsic neuron dynamics  
cell types  
neuromodulators  
dendrites  
stochasticity of spikes  
noise  
etc.

# A mathematician's approach

"If you can't solve a problem, then there is an easier problem you can solve: find it."

- George Polya, How to Solve It (1945)

Often, technology is developed on simple model systems

A good model system has:

Tractability

Transparency

Complex behavior



C elegans

Often, technology is developed on simple model systems

A good model system has:

Tractability

Transparency

Complex behavior



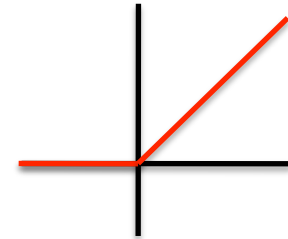
C elegans

We also need to study simple model systems in order to develop **mathematical technology**.

# A toy model of a recurrent network

A threshold-linear network:

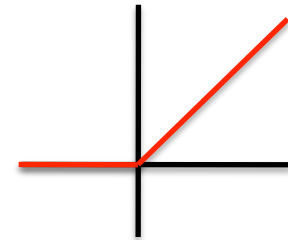
$$\frac{dx_i}{dt} = -x_i + \left[ \sum_{j=1}^n W_{ij} x_j + \theta \right]_+$$



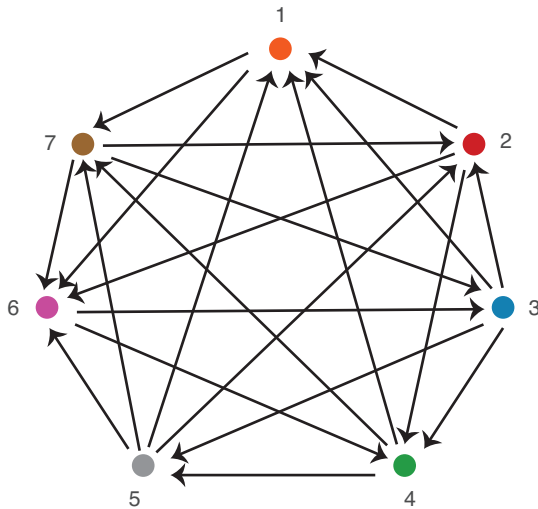
# A toy model of a recurrent network

A threshold-linear network:

$$\frac{dx_i}{dt} = -x_i + \left[ \sum_{j=1}^n W_{ij} x_j + \theta \right]_+$$



determined from a directed graph  $G$ .



$$W_{ij} = \begin{cases} 0 & \text{if } i = j \\ -1 + \varepsilon & \text{if } i \leftarrow j \text{ in } G \\ -1 - \delta & \text{if } i \not\leftarrow j \text{ in } G \end{cases}$$

parameter constraints

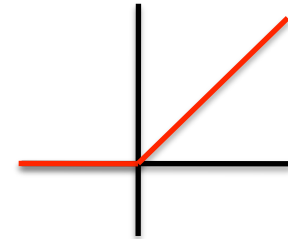
$$\theta > 0 \quad \delta > 0 \quad 0 < \varepsilon < \frac{\delta}{\delta + 1}$$



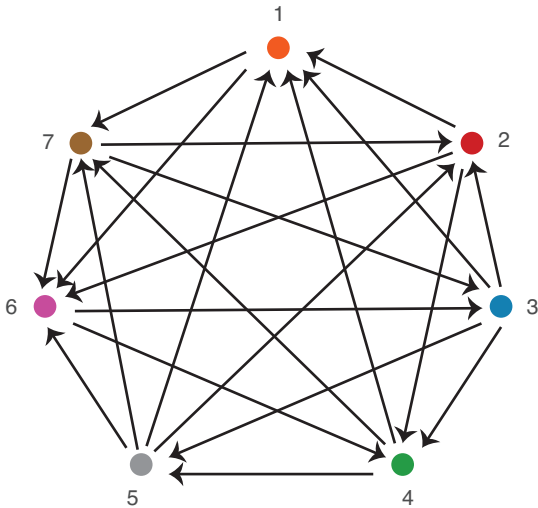
# A toy model of a recurrent network

A threshold-linear network:

$$\frac{dx_i}{dt} = -x_i + \left[ \sum_{j=1}^n W_{ij} x_j + \theta \right]_+$$



determined from a directed graph G.



Is this model...

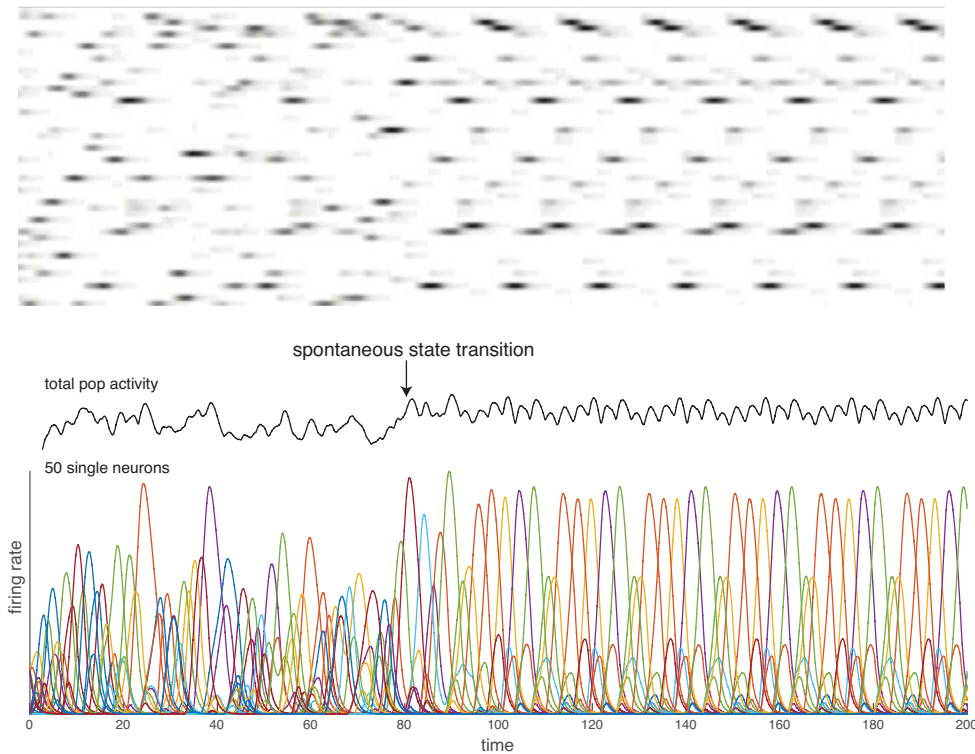
Tractable?

Transparent?

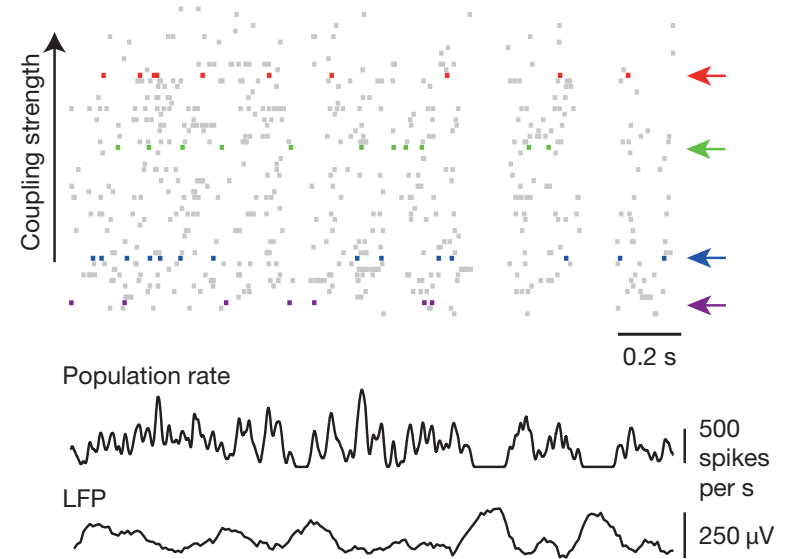
Capable of complex behavior?

# The model (generically) exhibits complex behavior...

## Model (50 neurons)

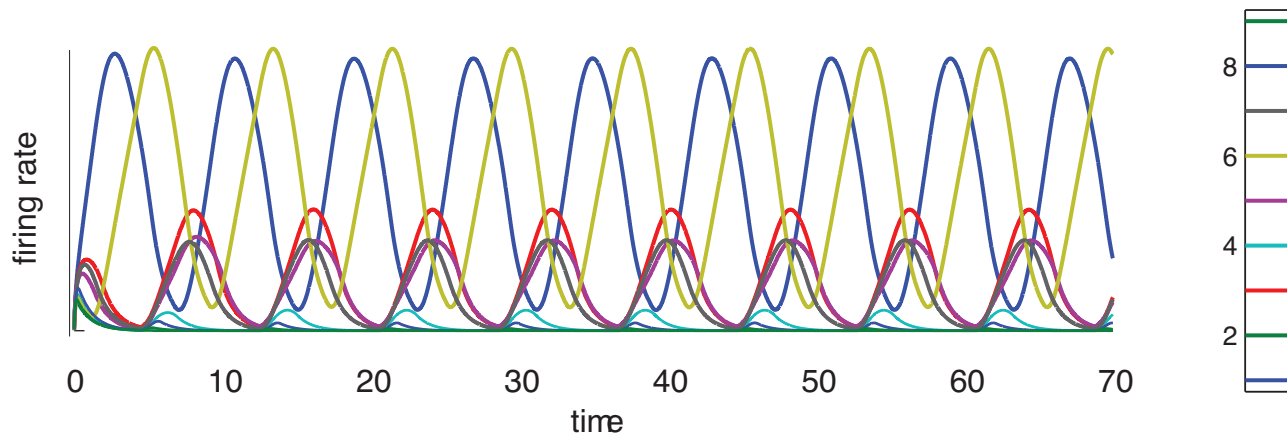


## Data (66 neurons)



Okun et. al., Nature 2015

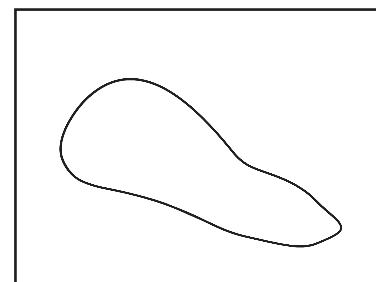
The model (generically) exhibits complex behavior...



Graph adjacency matrix

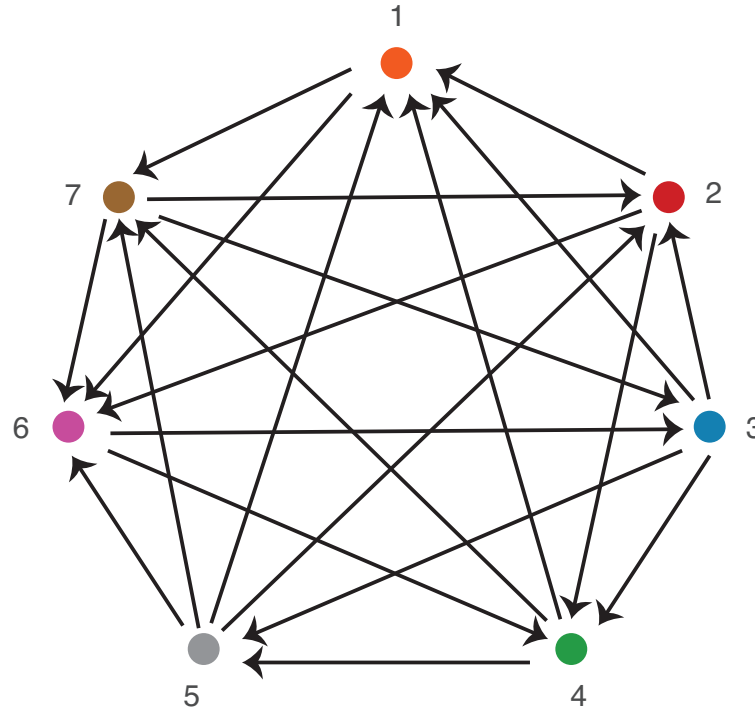
$$\begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 1 & 1 & 1 & 1 & 1 \\ 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 & 0 & 1 & 1 & 0 \\ 1 & 0 & 0 & 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 & 1 & 0 & 1 & 1 & 1 \\ 1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 1 & 0 & 1 & 0 & 0 \\ 1 & 0 & 1 & 1 & 1 & 0 & 1 & 1 & 0 \end{bmatrix}$$

projection of trajectory



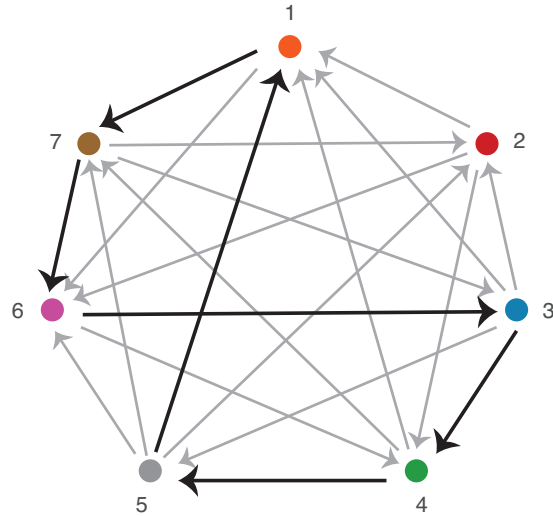
(play song)

Back to our problem...

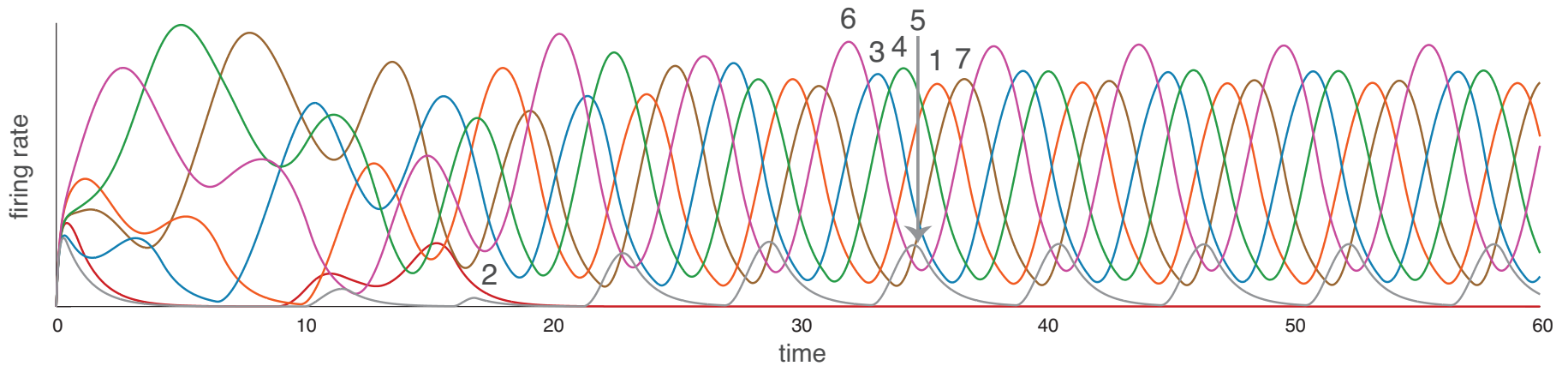


In our toy model, can we figure out what the network is going to do?

# Activity converges to a limit cycle

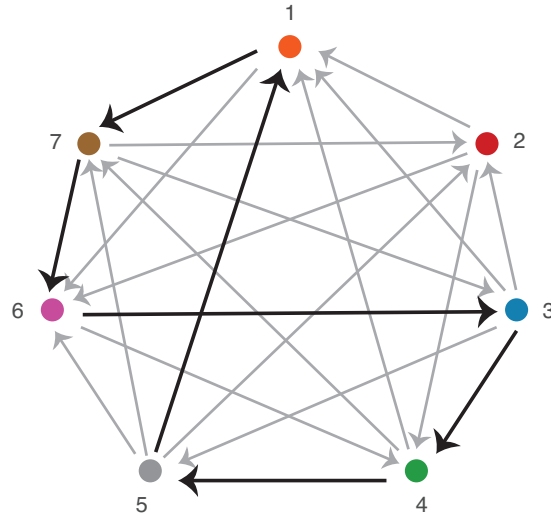


total pop activity

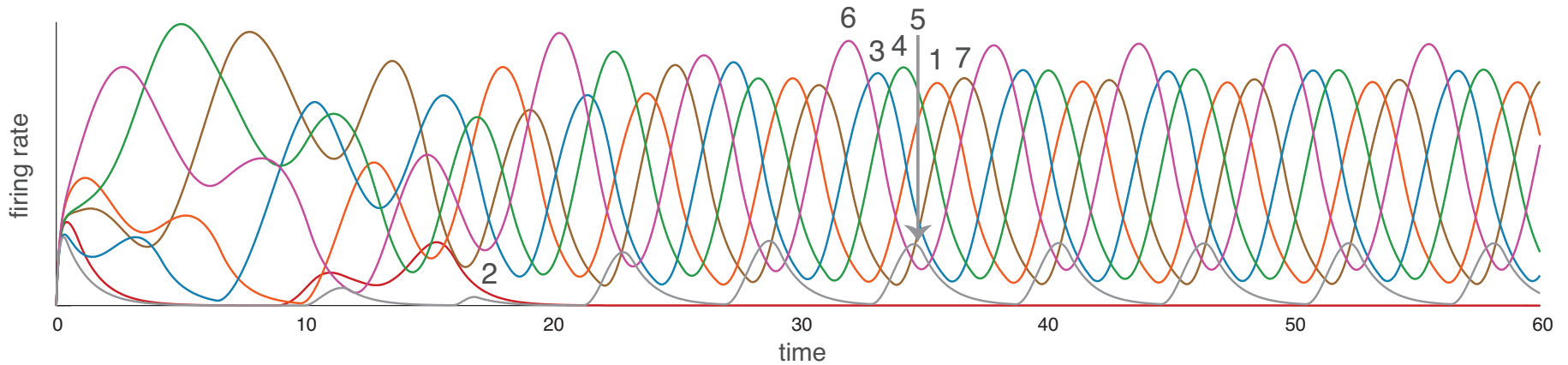


# Activity converges to a limit cycle

Could we have predicted the sequence from the graph?

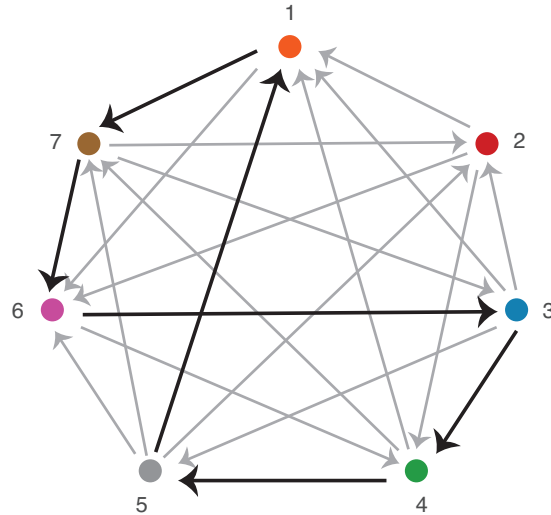


total pop activity

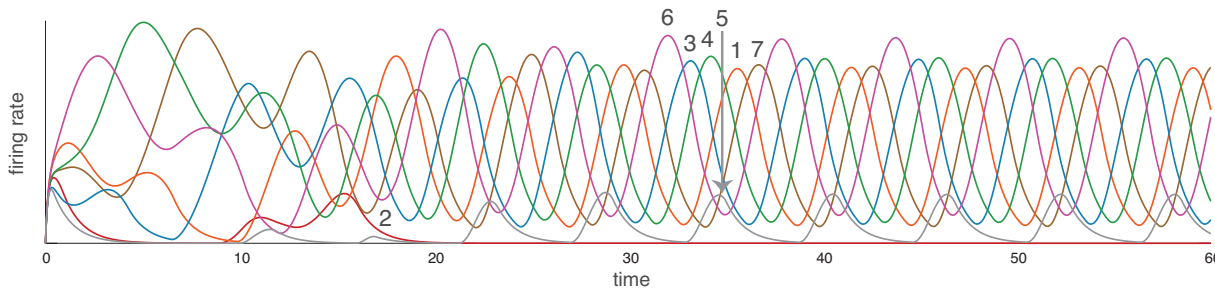
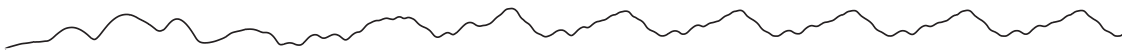


# Activity converges to a limit cycle

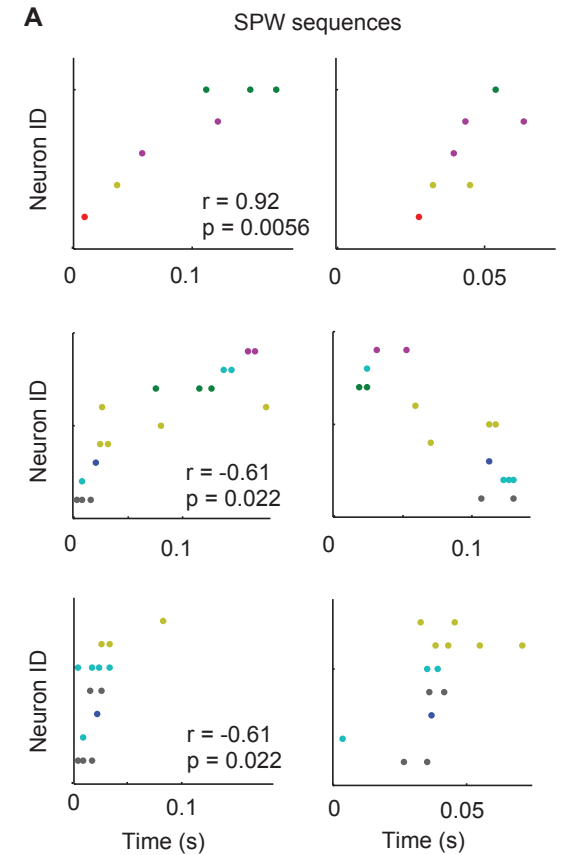
Could we have predicted the sequence from the graph?



total pop activity

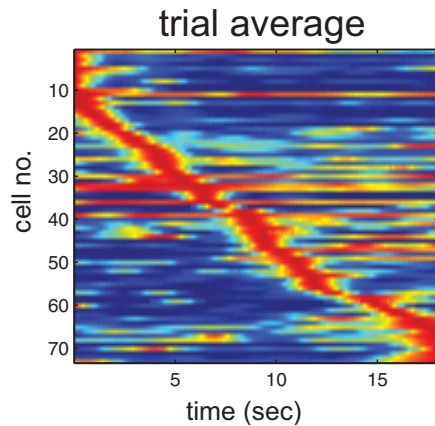


## hippocampal ripple sequences

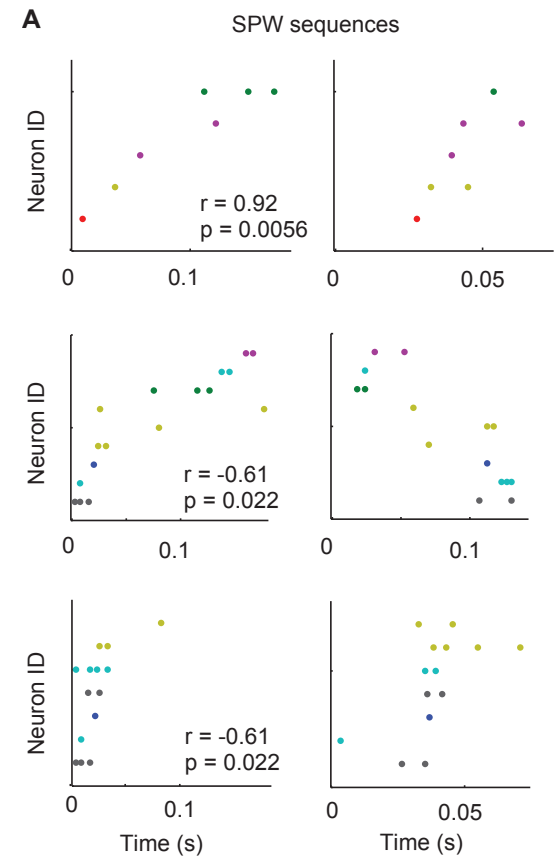
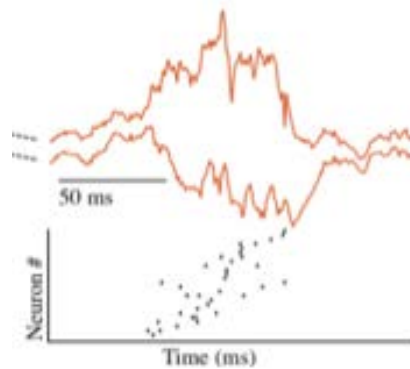


# Diversity of dynamics in hippocampus

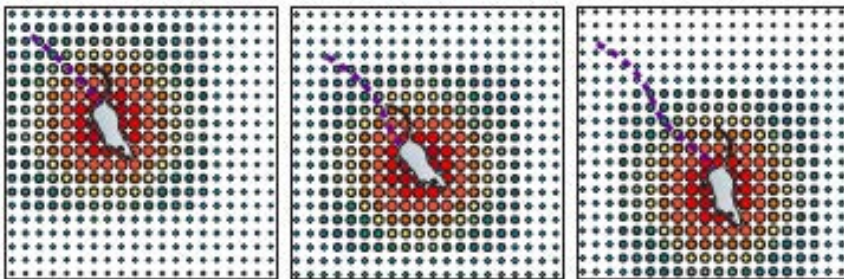
## Cell assembly sequences



## Ripple sequences (fast)



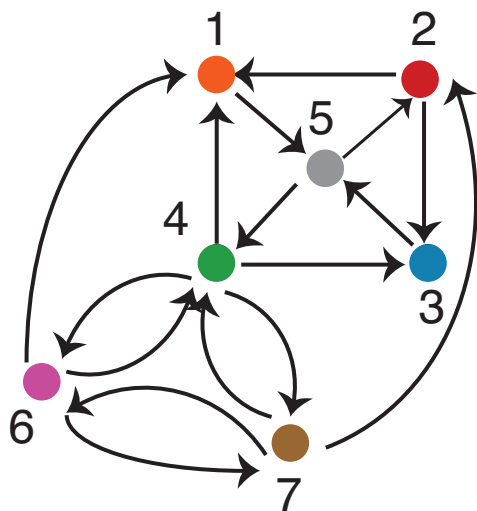
## Associative memory; place coding



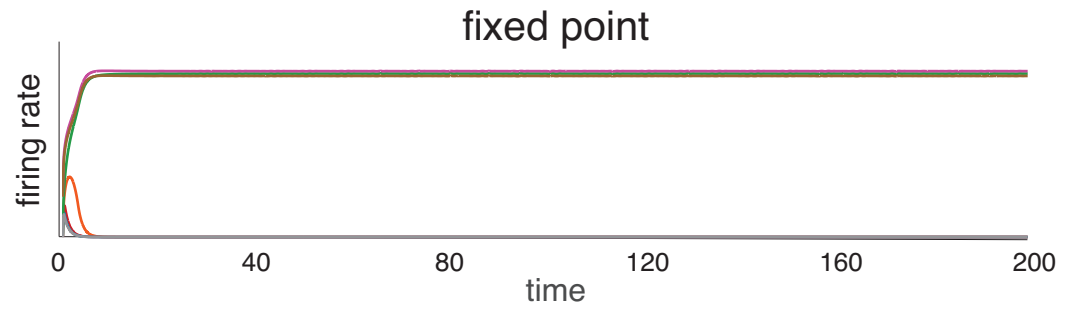
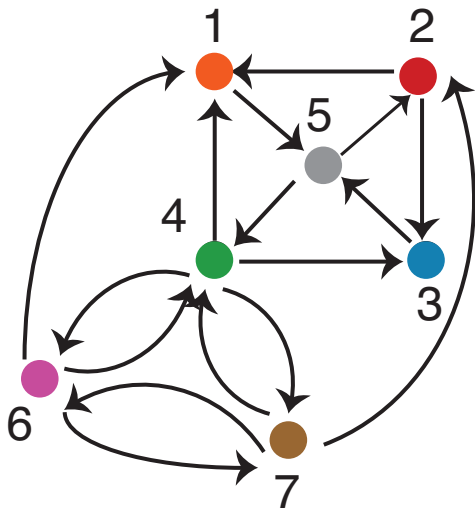
McNaughton et. al., Nature Rev. Neurosci. 2006



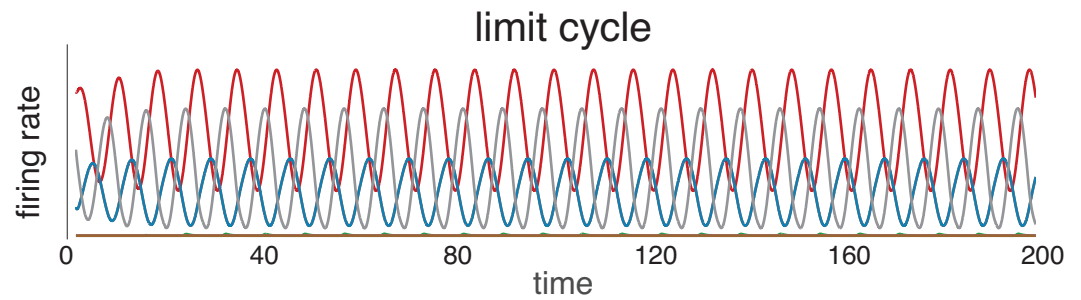
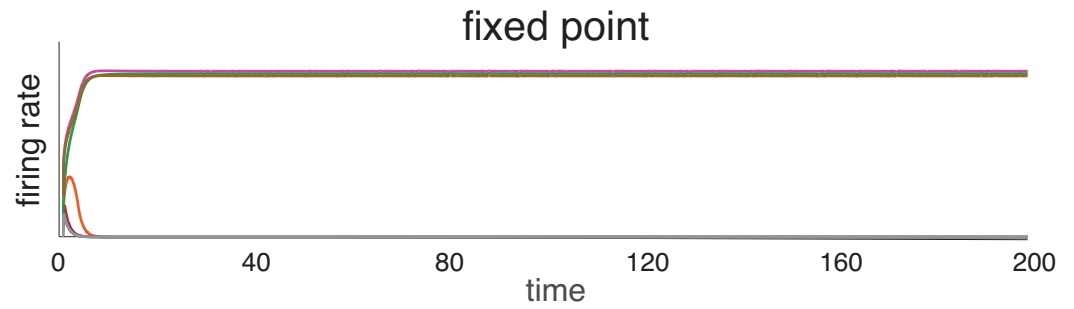
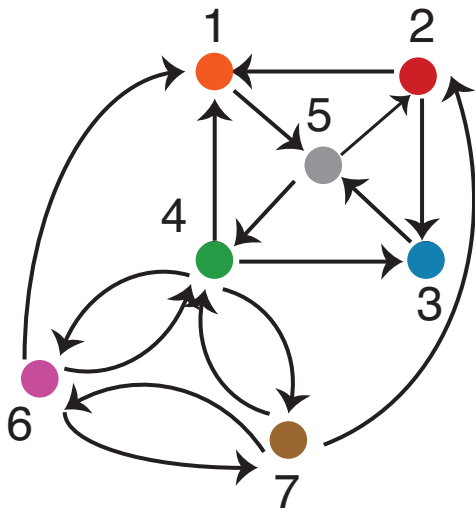
# Multiple dynamic behaviors in the same network



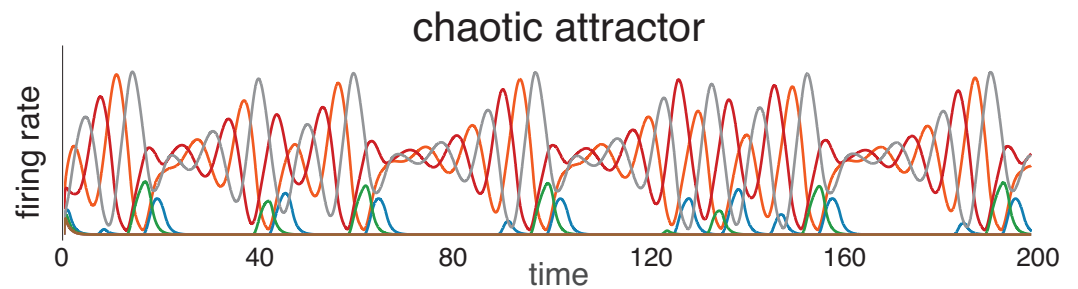
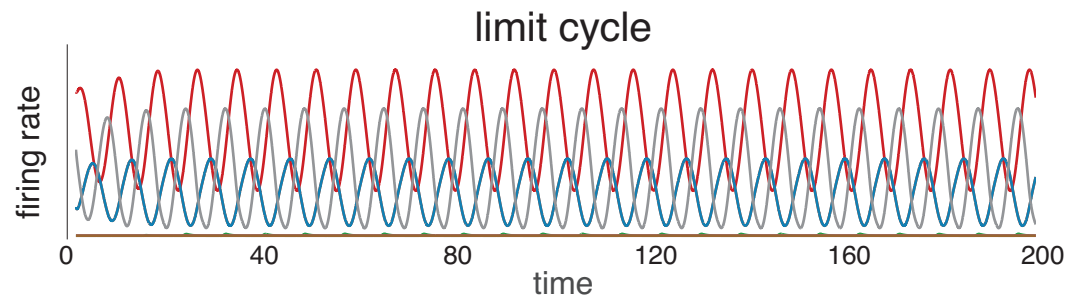
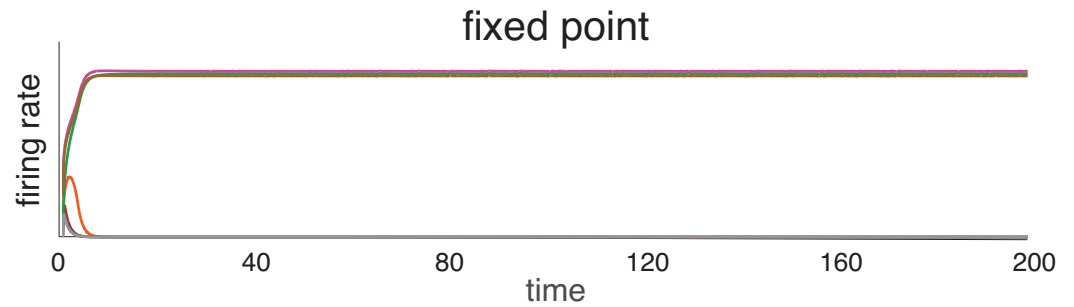
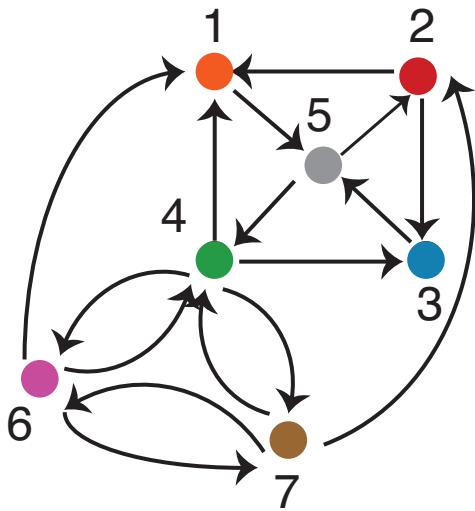
# Multiple dynamic behaviors in the same network



# Multiple dynamic behaviors in the same network



# Multiple dynamic behaviors in the same network



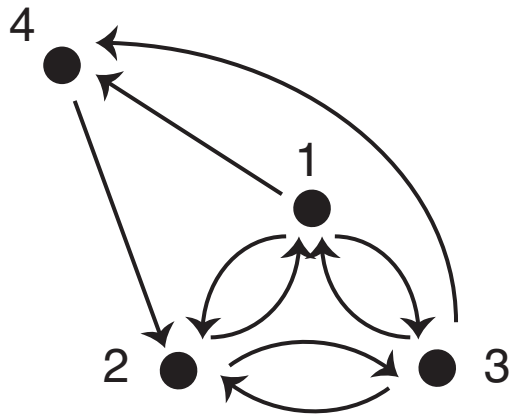
Can we predict these various behaviors from the graph?

# Some mathematical results (tractability)

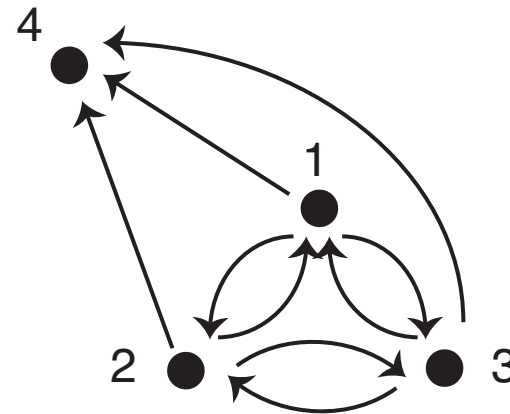
Theorem 1. For any  $G$ , a clique is the support of a stable fixed point if and only if it is a target-free clique.

# Some mathematical results (tractability)

Theorem 1. For any  $G$ , a clique is the support of a stable fixed point if and only if it is a target-free clique.



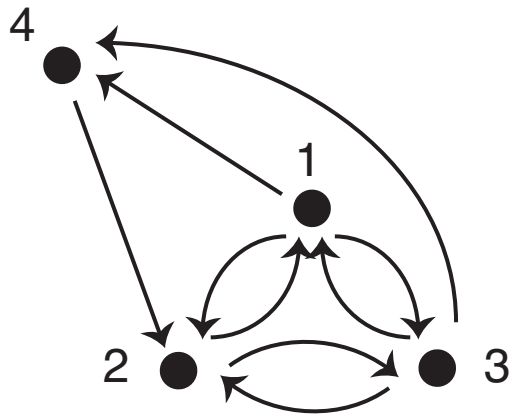
123 is a target-free clique



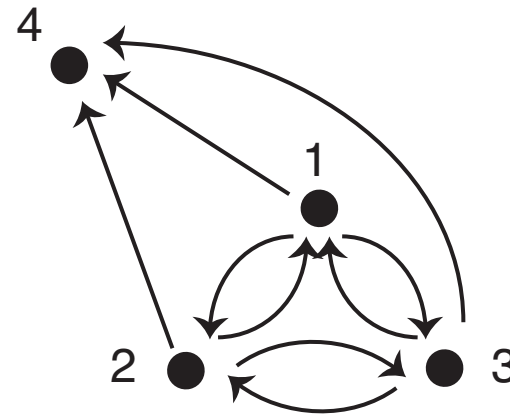
123 is not target-free

# Some mathematical results (tractability)

Theorem 1. For any  $G$ , a clique is the support of a stable fixed point if and only if it is a target-free clique.



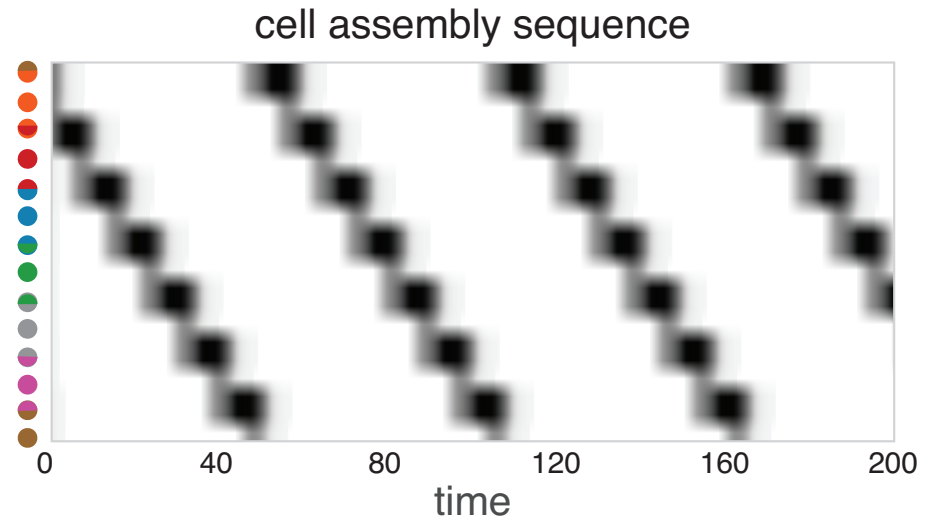
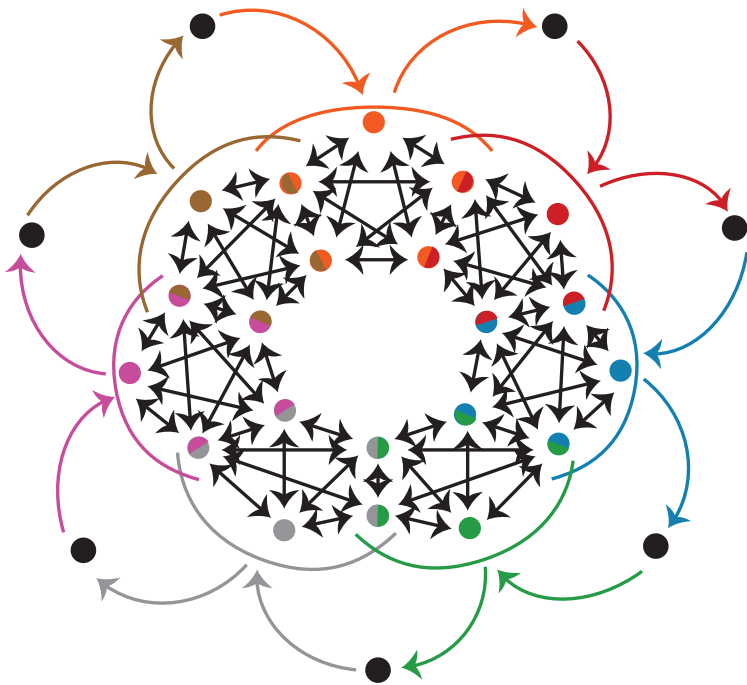
123 is a target-free clique



123 is not target-free

Conjecture. A subset of neurons supports a stable fixed point of the dynamics if and only if it is a target-free clique.

# Sequence of overlapping cell assemblies



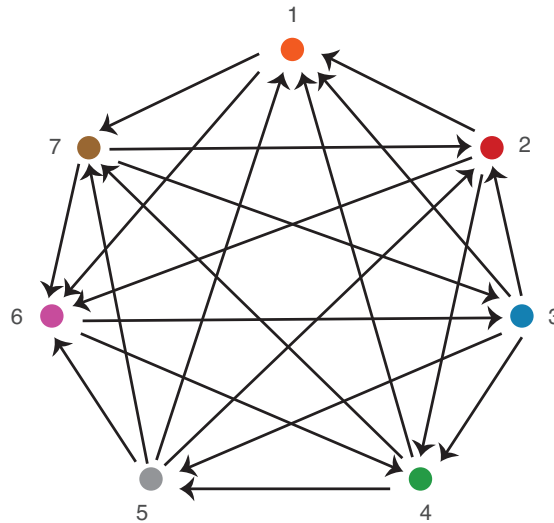


## Some mathematical results

Theorem 2. If  $G$  is an **oriented graph** with **no sinks**, then the network has no stable fixed points.

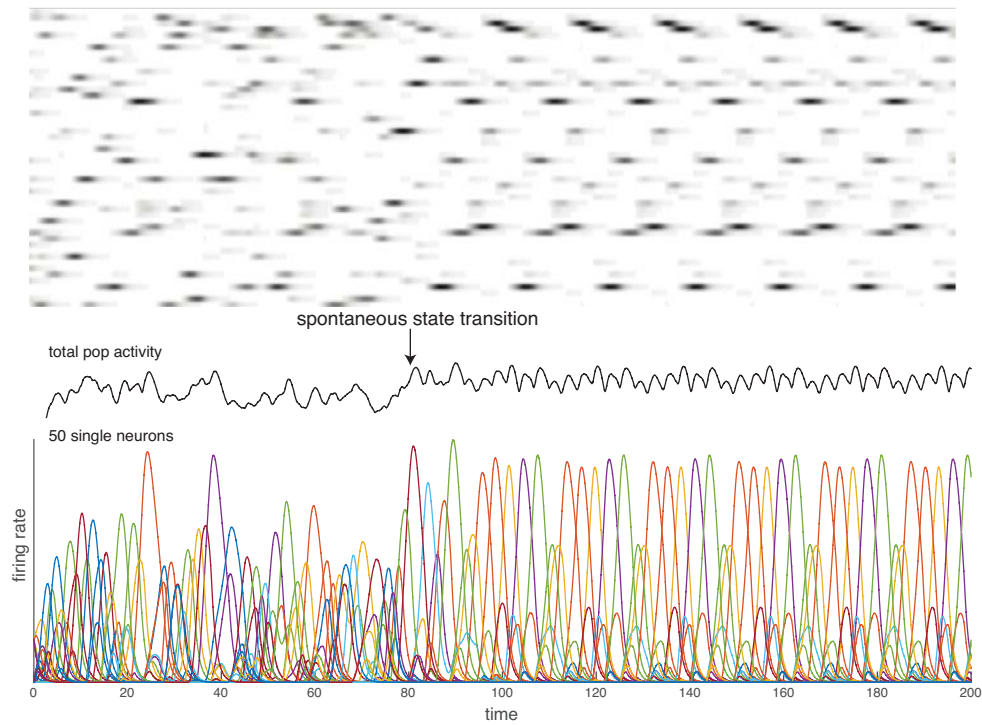
# Some mathematical results

Theorem 2. If  $G$  is an **oriented graph** with **no sinks**, then the network has no stable fixed points.

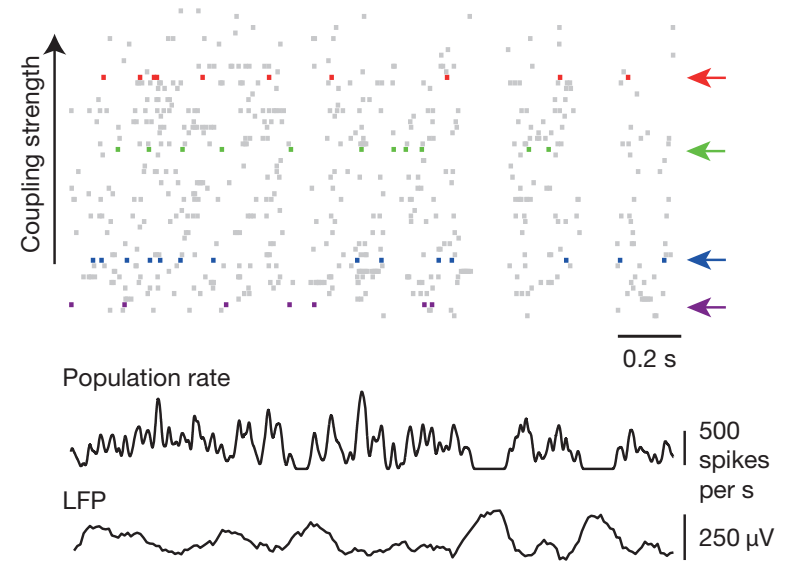


an oriented graph  
with no sinks

## Model (50 neurons)



## Data (66 neurons)



Okun et. al., Nature 2015

# A word on the proofs...

We build on the theory of threshold-linear networks:

X. Xie, R. H. Hahnloser, and H.S. Seung. Selectively grouping neurons in recurrent networks of lateral inhibition. *Neural Computation*, 2002.

R. H. Hahnloser, H.S. Seung, and J.J. Slotine. **Permitted and forbidden sets** in symmetric threshold-linear networks. *Neural Computation*, 2003.

C. Curto, A. Degeratu, and V. Itskov. Flexible memory networks. *Bull. Math. Biol.*, 2012.

C. Curto, A. Degeratu, and V. Itskov. Encoding binary neural codes in networks of threshold-linear neurons. *Neural Computation*, 2013.

C. Curto and K. Morrison. Pattern completion in threshold-linear networks. In prep.

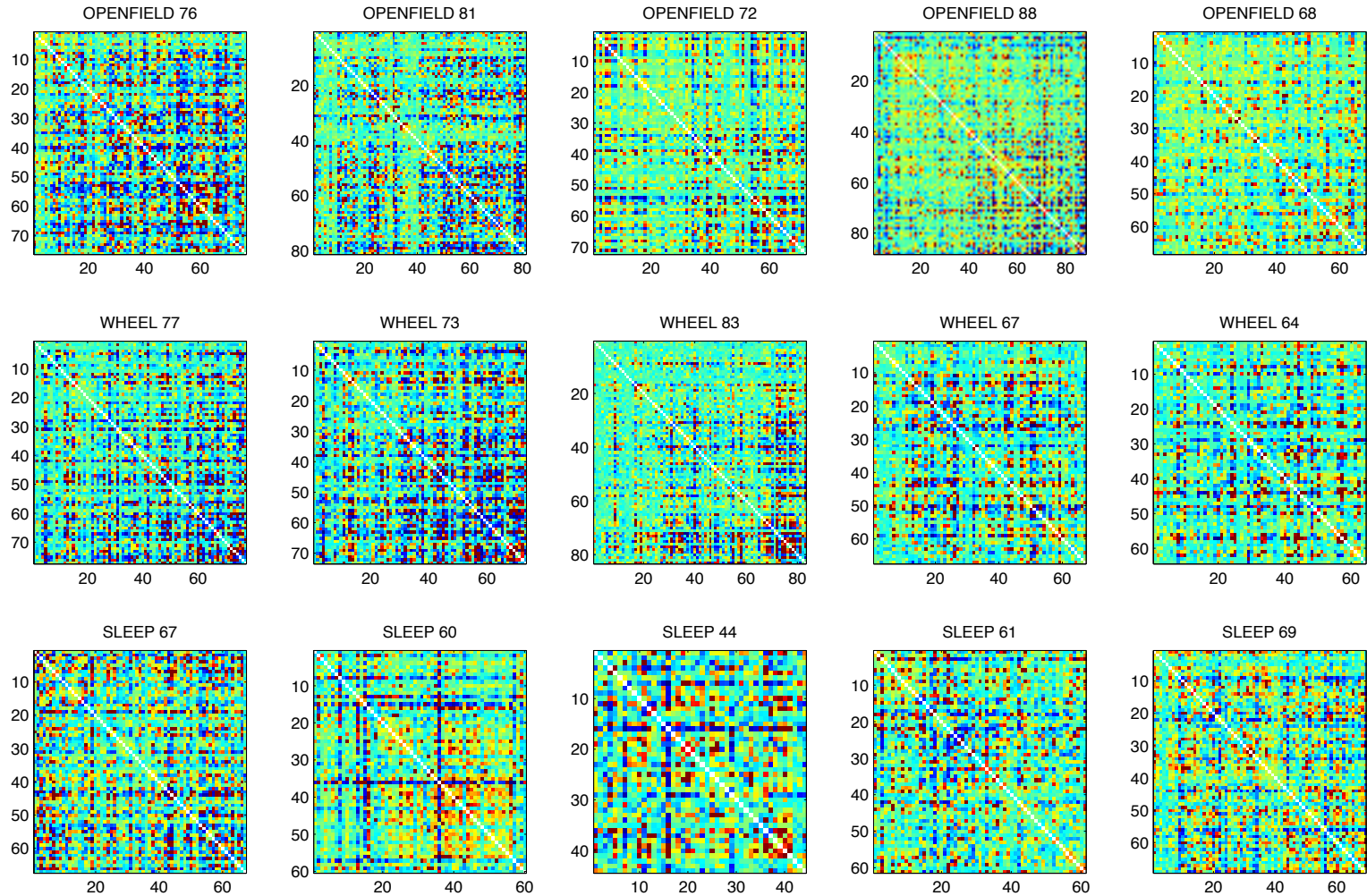
Some mathematical ingredients of this theory:

Combinatorics + matrix theory

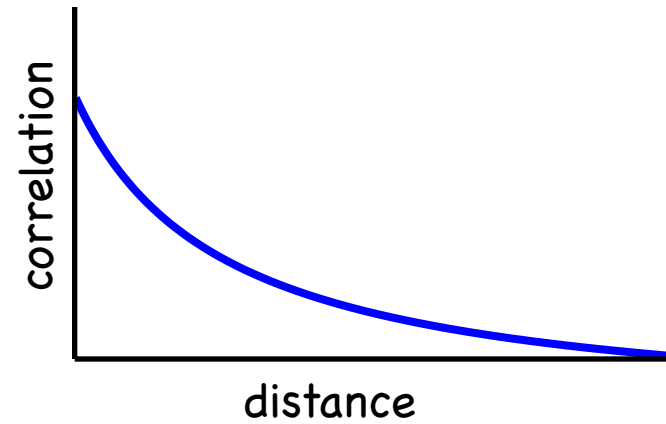
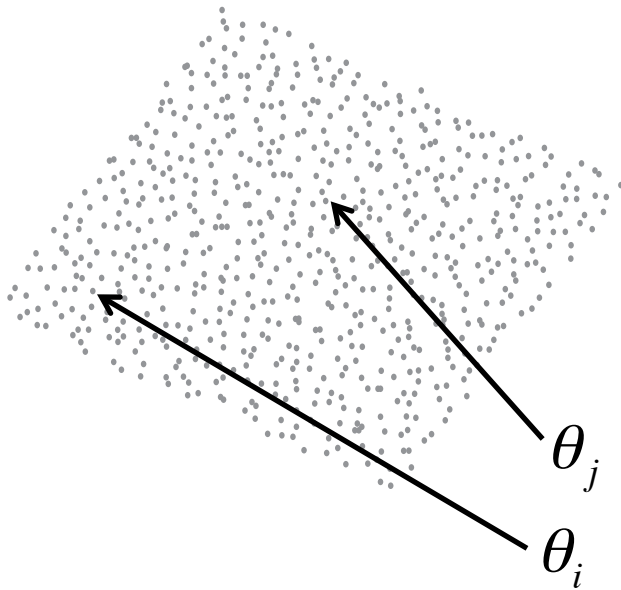
Distance geometry (Cayley-Menger determinants)

## Part II: data analysis

# Hunting for structure in pairwise correlations

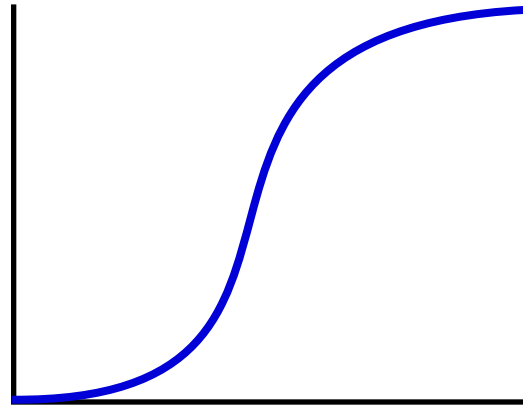
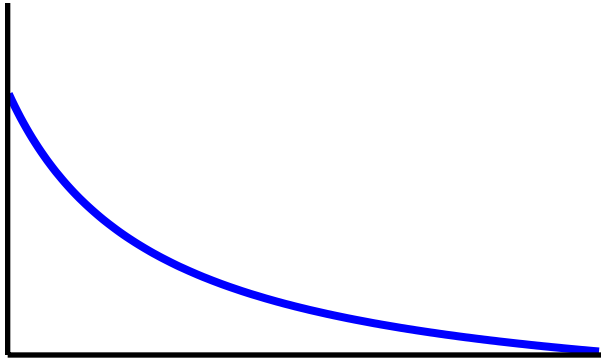


# Geometric structure of correlations



Each neuron has a position in a “*feature space.*”

# Why hunting for structure is hard...

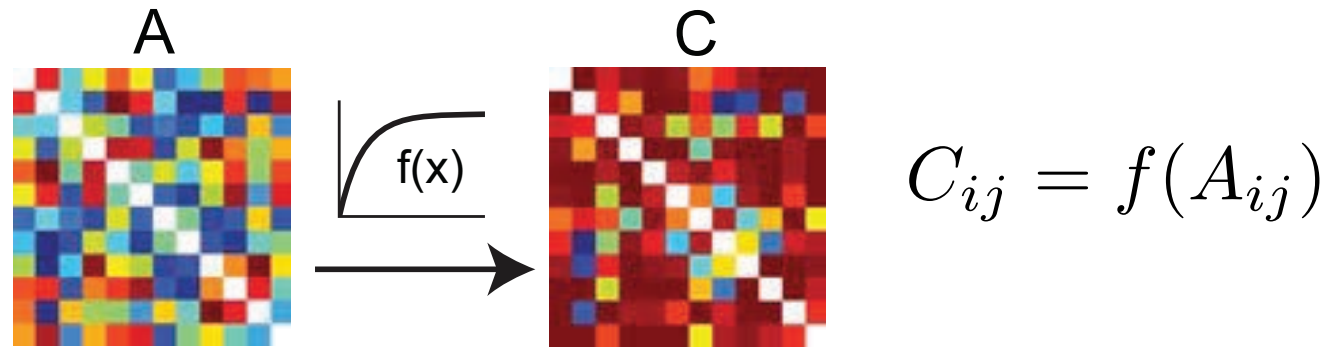


There is often a **nonlinear relationship** between observed variables and underlying “structured” variables.

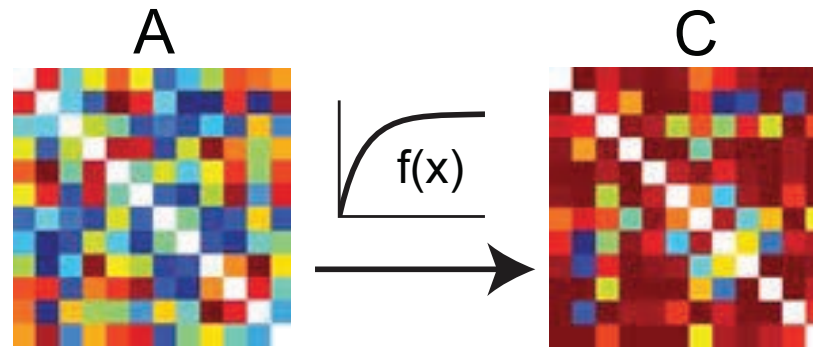
But, this relationship is typically **monotonic**.



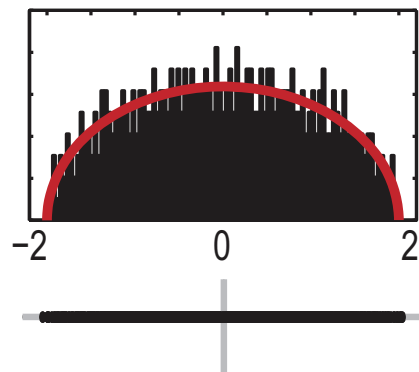
Goal: to detect **random** or **geometric** structure that is invariant under monotone transformations



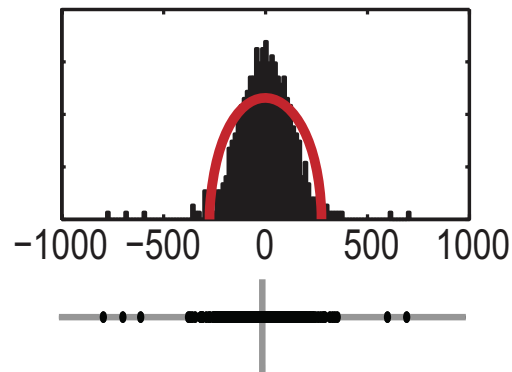
# What isn't invariant: eigenvalues



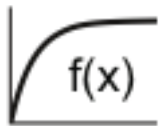
eigenvalues of A



eigenvalues of C



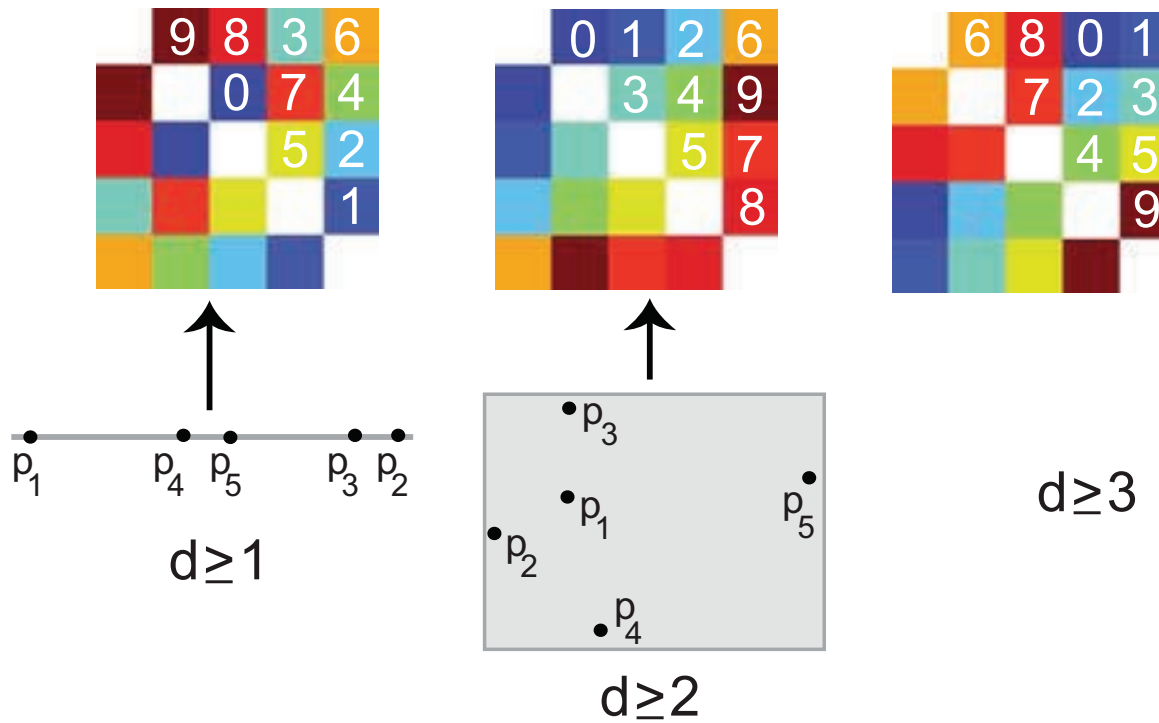
What is invariant: the ordering of matrix entries



$$C_{ij} = f(A_{ij})$$

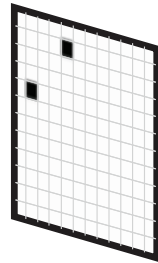
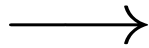
$$C_{ij} < C_{kl} \Leftrightarrow A_{ij} < A_{kl}$$

Maybe surprising: **geometric** structure is encoded in the ordering of matrix entries

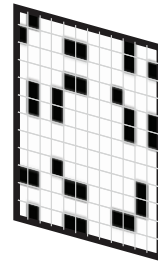


# Repackaging the matrix ordering data...

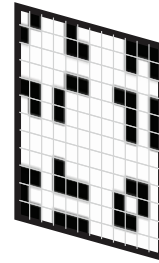
$$G_0 \subset G_1 \subset \dots \subset G_{\binom{n}{2}}$$



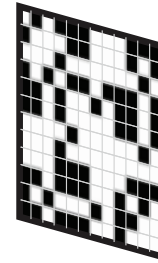
$\rho = 0.008$



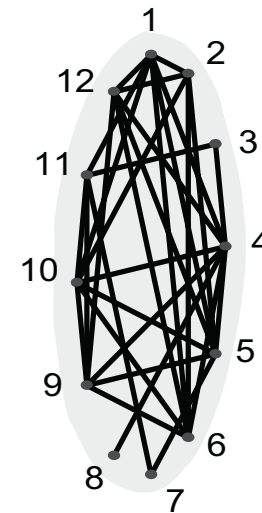
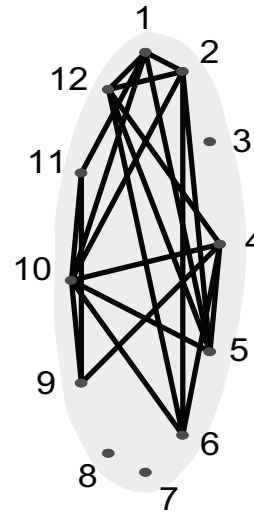
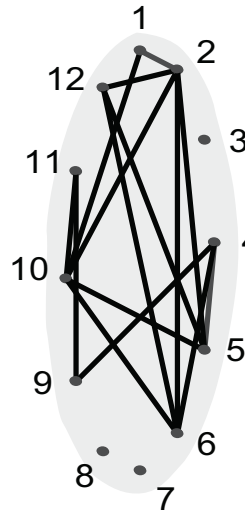
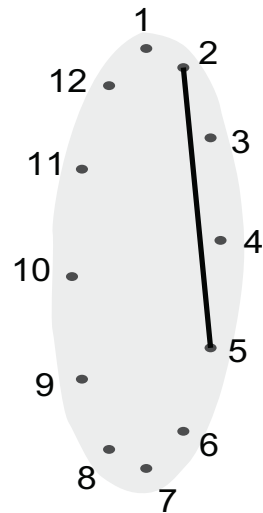
$\rho = 0.1$



$\rho = 0.25$

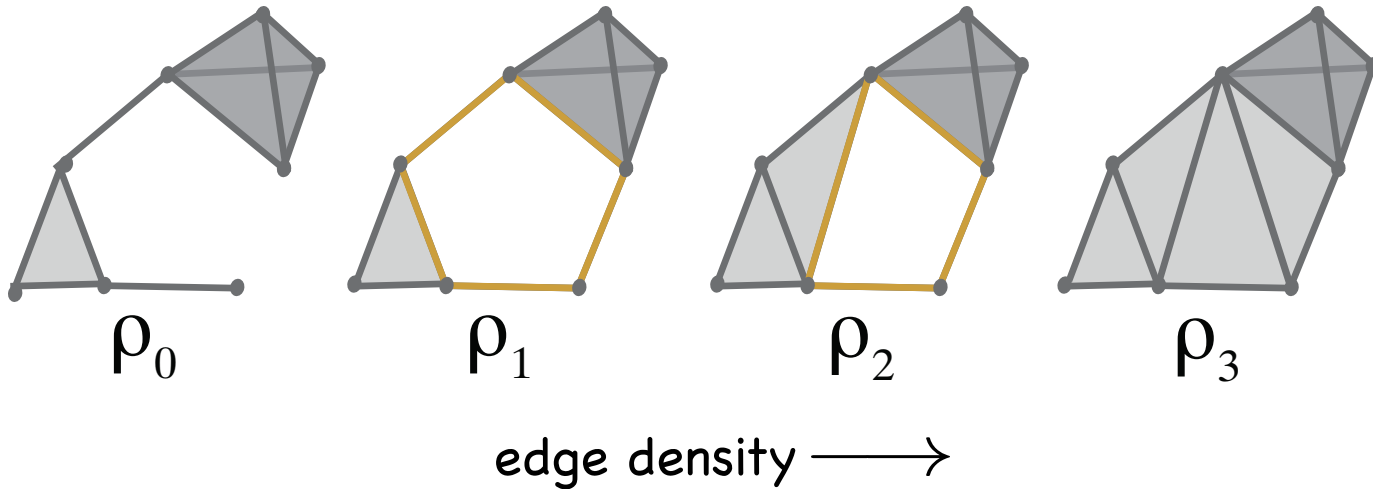


$\rho = 0.45$



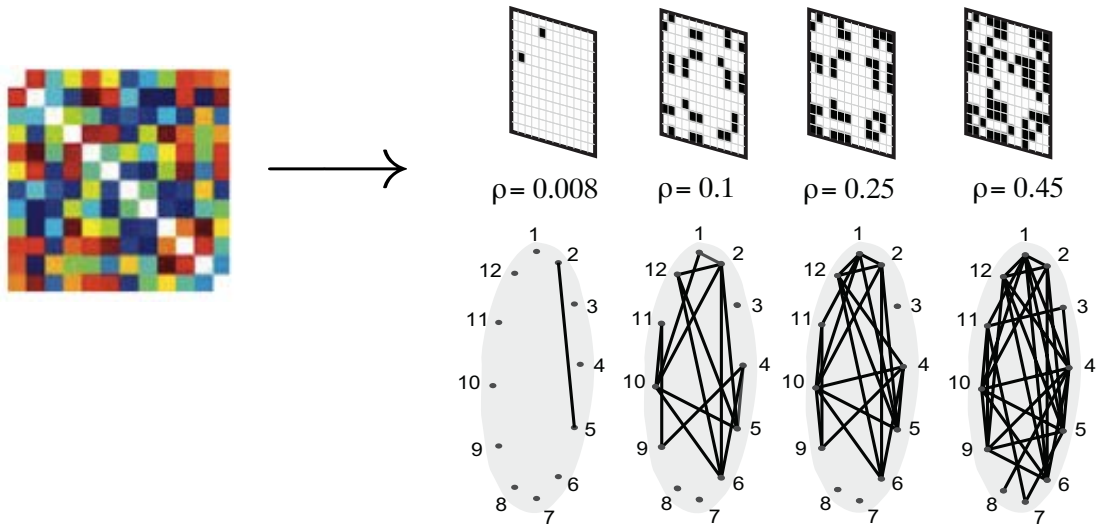
edge density  $\longrightarrow$

Idea: measure the organization of cliques  
across the sequence of graphs



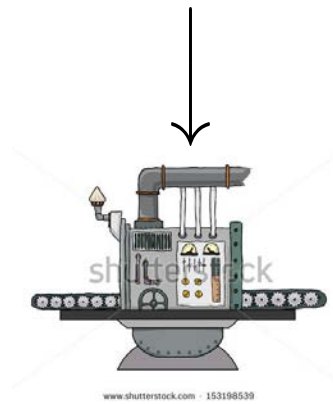
Intuition: **geometric structure** in the matrix  
causes the holes to fill in more quickly

# Idea: measure the organization of cliques across the sequence of graphs

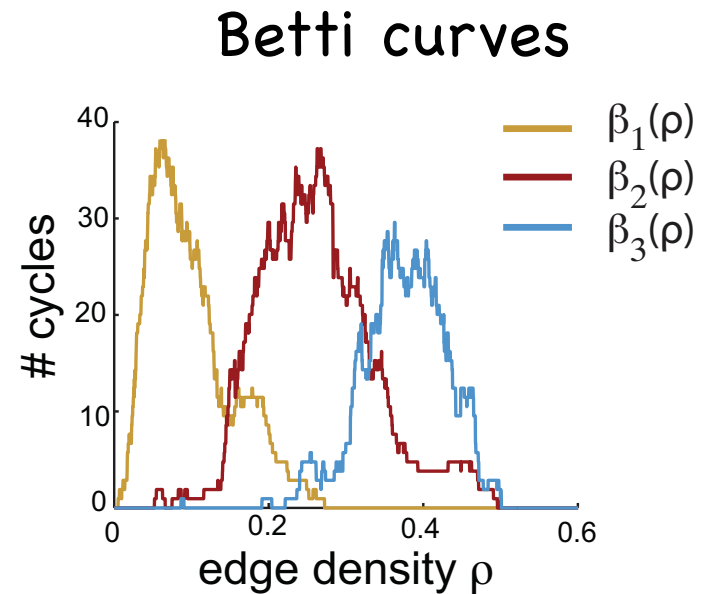


Persistent homology

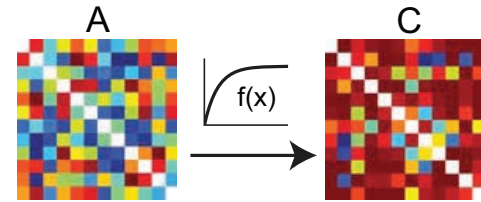
Computational algebraic topology



Topological machine

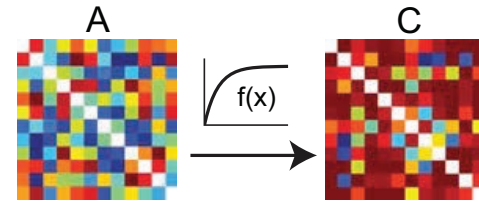


Betti curves are invariant under monotone transformations...





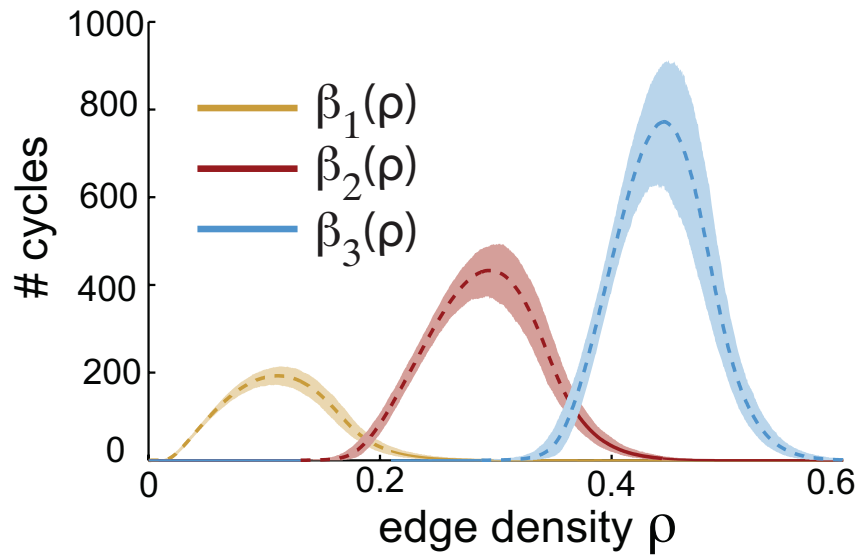
Betti curves are invariant under  
monotone transformations...



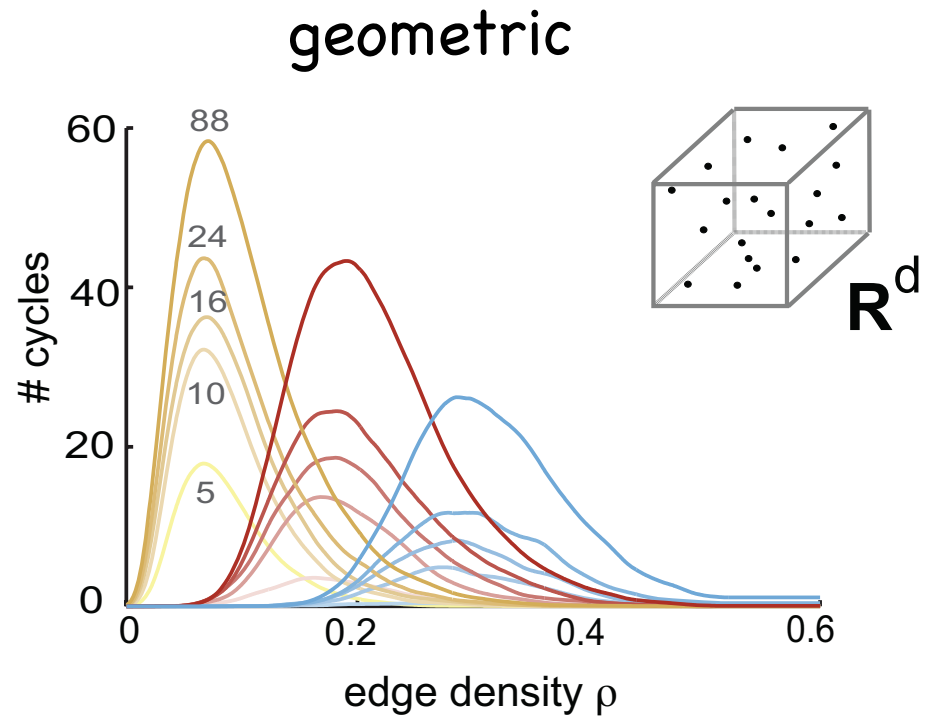
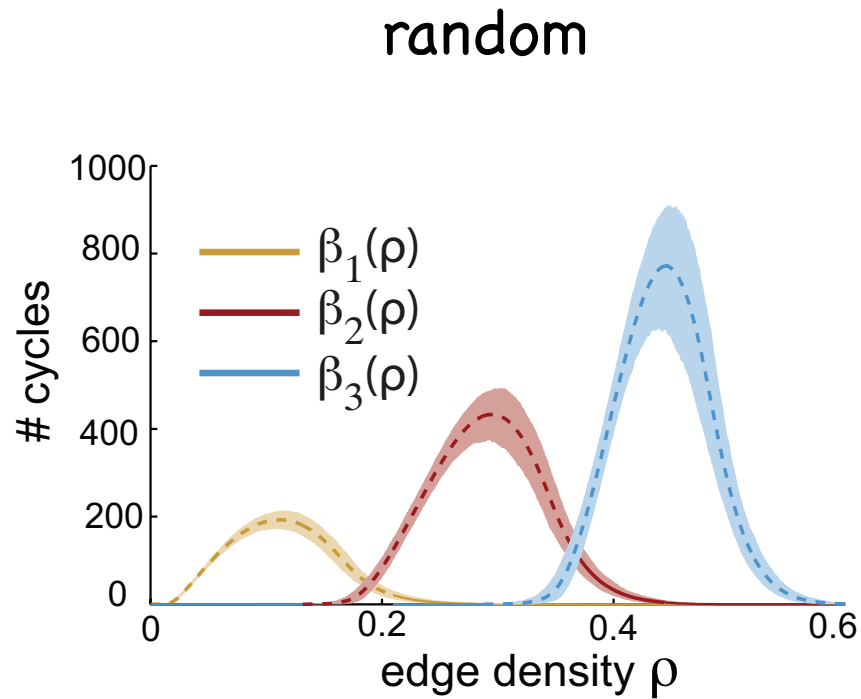
But can they be used to detect  
**random** or **geometric** structure?

# Betti curves of random and geometric matrices

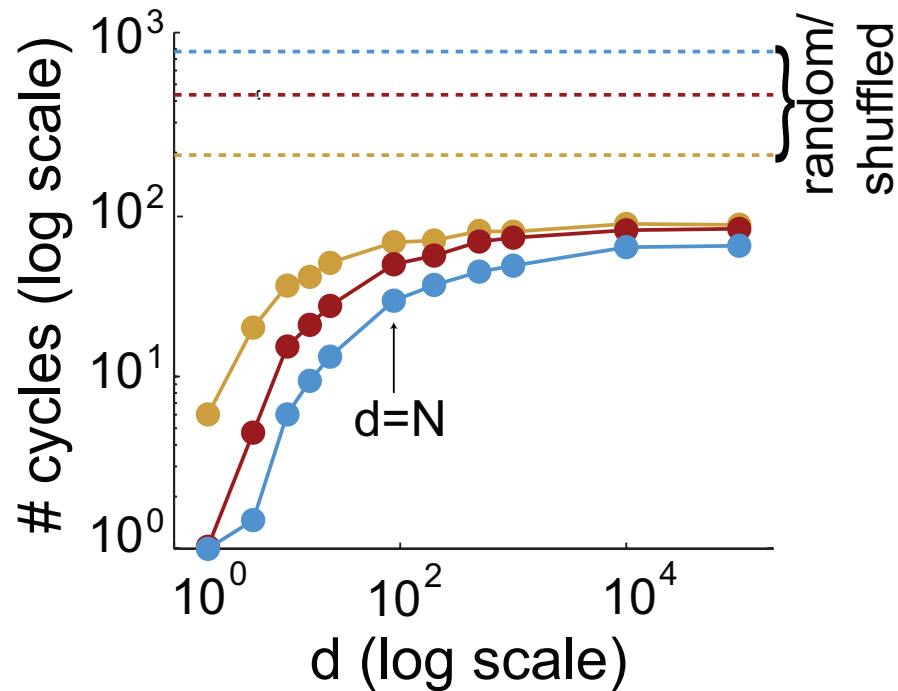
random



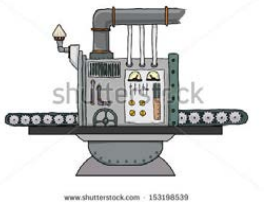
# Betti curves of random and geometric matrices



# Betti curves of random and geometric matrices



Intuition: **geometric structure** in the matrix causes the holes to fill in more quickly



# Software for computing Betti curves for symmetric matrices

- Custom-made software for generating clique complexes (Chad Giusti).
- **Perseus** software for computing homology groups of clique complexes. Vidit Nanda (while a student of Konstantin Mischaikow).
- **Software** on GitHub:

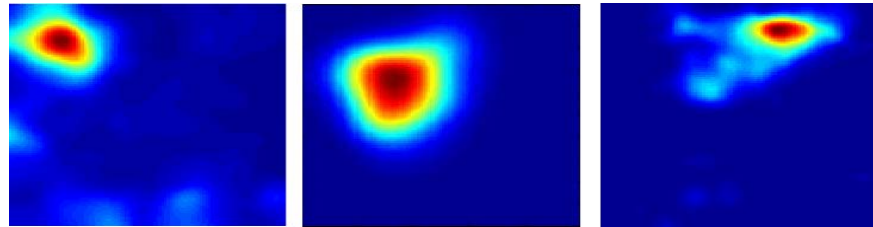
<https://github.com/nebneuron/clique-top>

# What happens when we feed in real data?

place cell



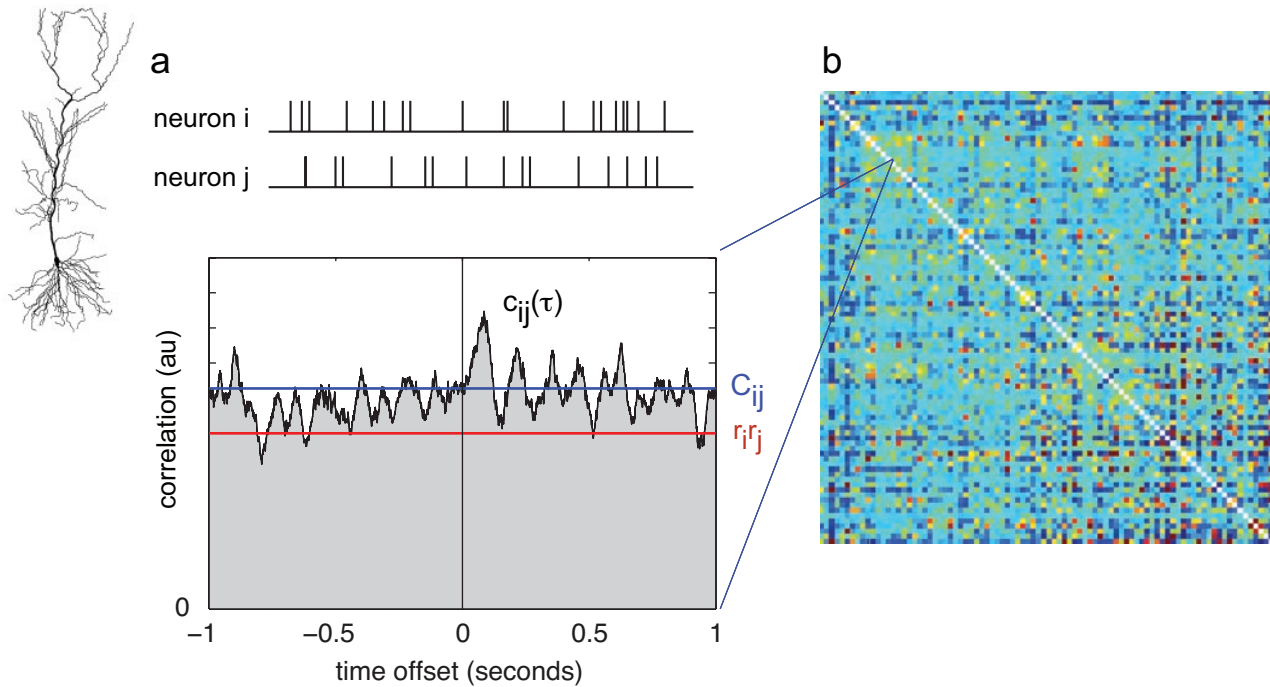
place fields



We used multi-unit electrophysiological recordings of CA1 pyramidal cells in rat hippocampus during open field exploration.

Data provided by Eva Pastalkova's lab at Janelia Research Campus, HHMI.

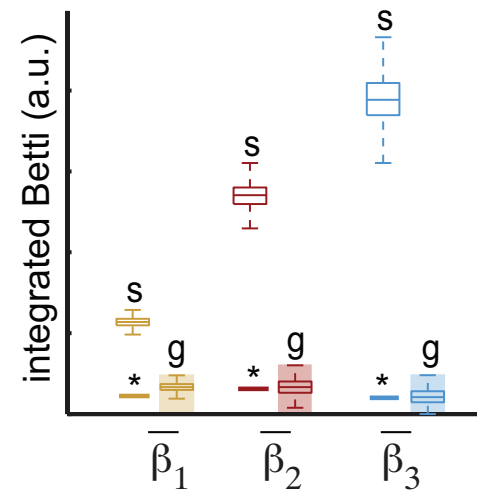
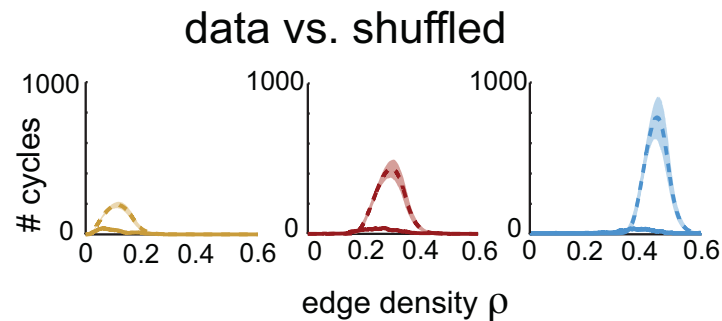
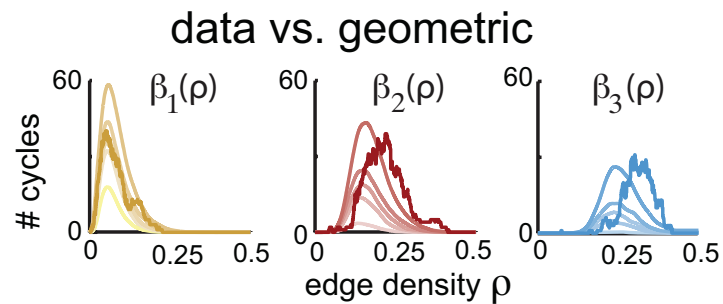
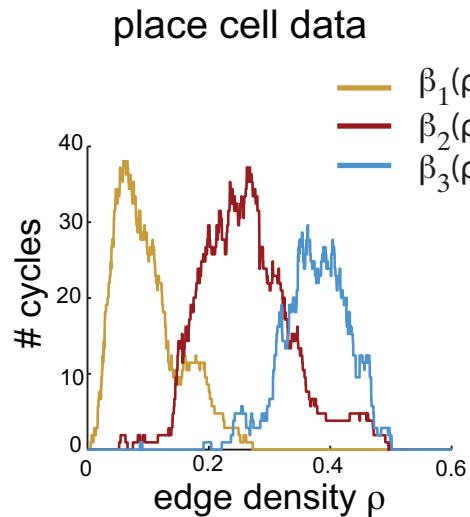
# Pairwise correlations for place cells (open field)



$$c_{ij}(\tau) = \frac{1}{T} \int_0^T f_i(t) f_j(t + \tau) dt$$



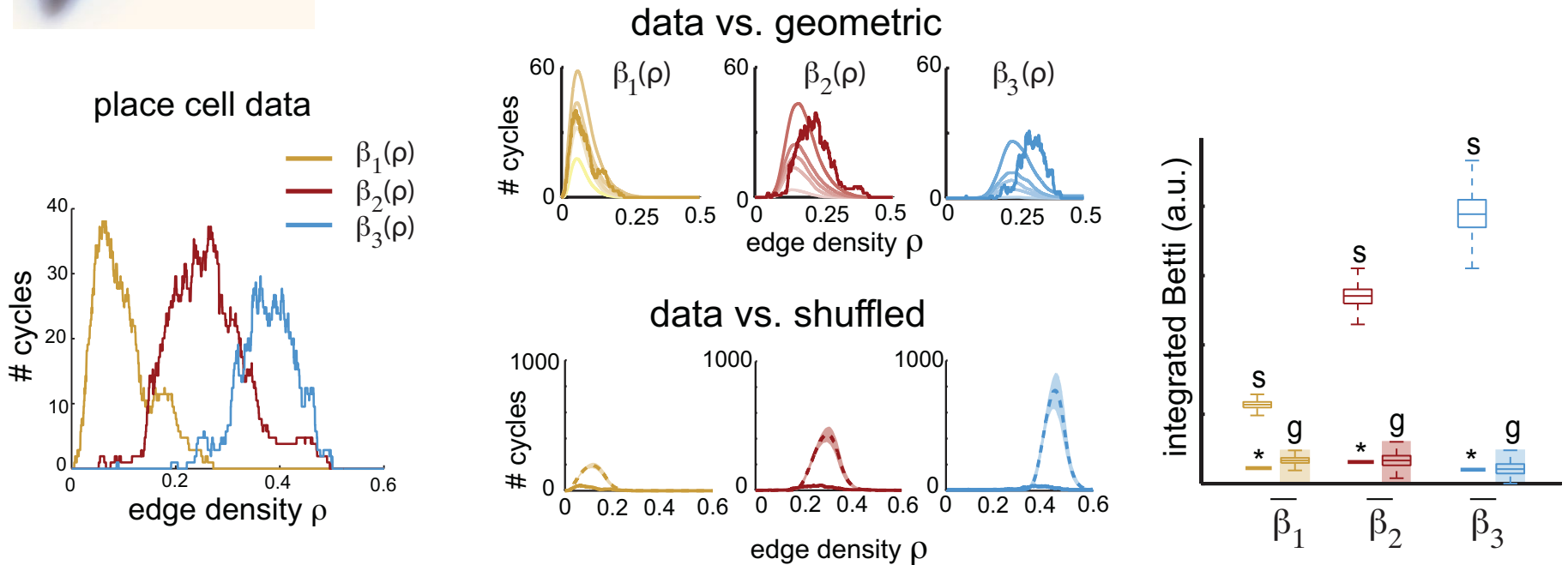
# Betti curves for open field data



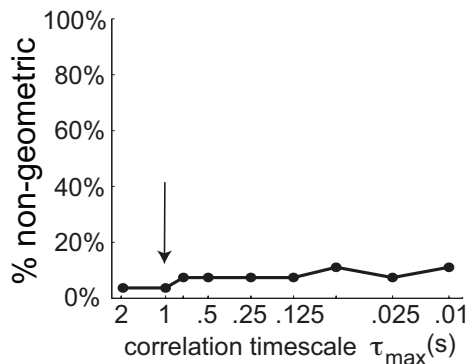




# Betti curves for open field data

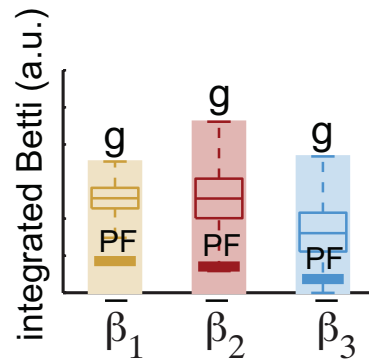
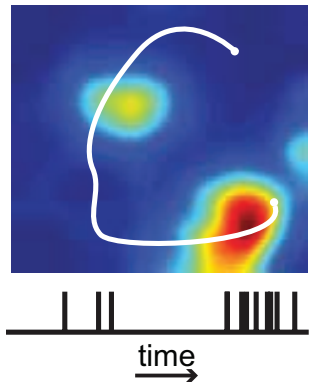


Results are consistent across data sets, and correlation timescales



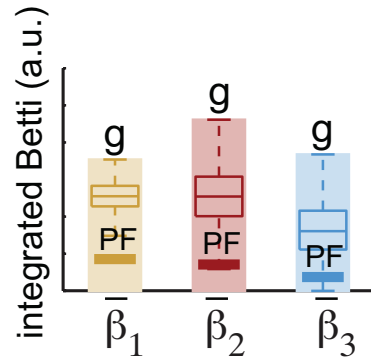
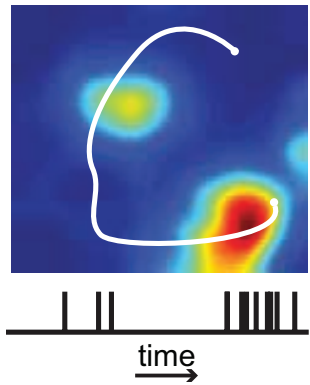
# Simulated data from a simple PF model

place field model

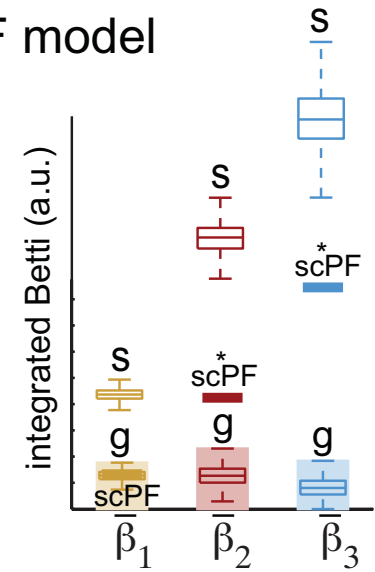
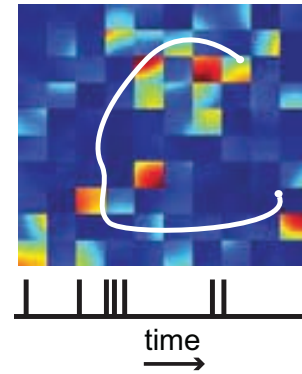


# Simulated data from a simple PF model

place field model

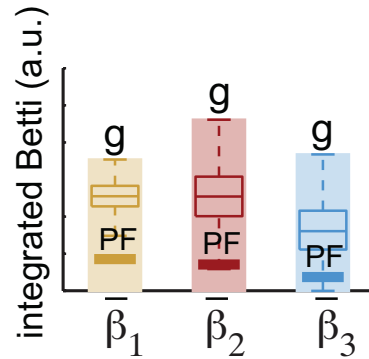
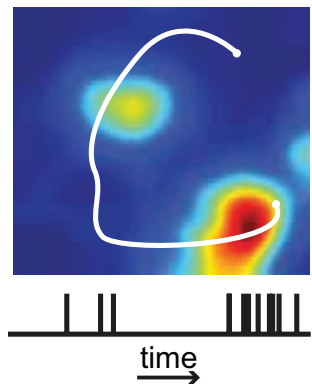


scrambled PF model

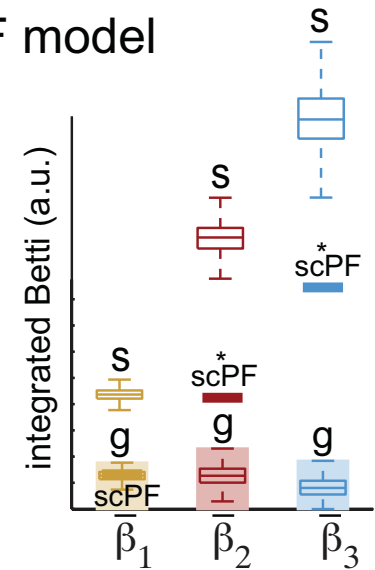
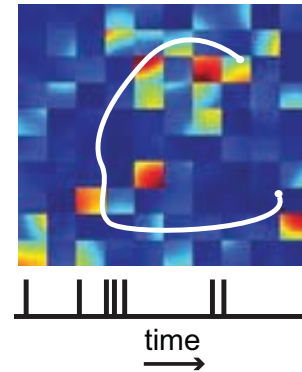


# Simulated data from a simple PF model

place field model



scrambled PF model



Geometric structure of correlations can be explained by place fields alone, but not if they are scrambled and non-geometric.

# Thanks!

## Collaborators on this work:

Katie Morrison (University of Northern Colorado)

Anda Degeratu (Freiberg)

Chad Giusti (former postdoc at UNL, now at UPenn)

Vladimir Itskov (Penn State)

Eva Pastalkova (Janelia Research Campus, HHMI)

# What about non-spatial behaviors?

running wheel



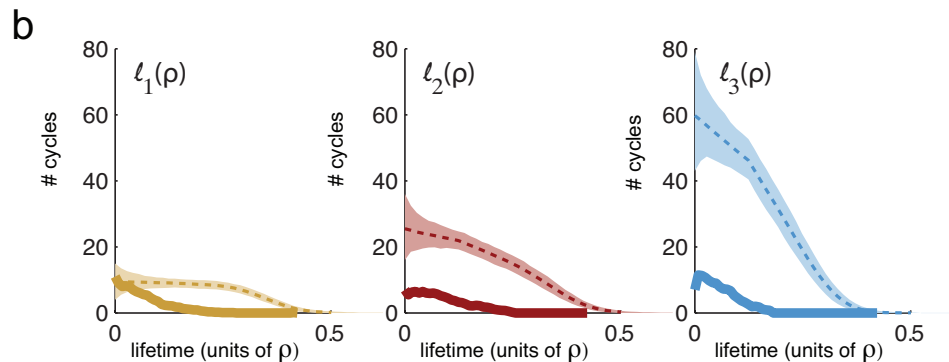
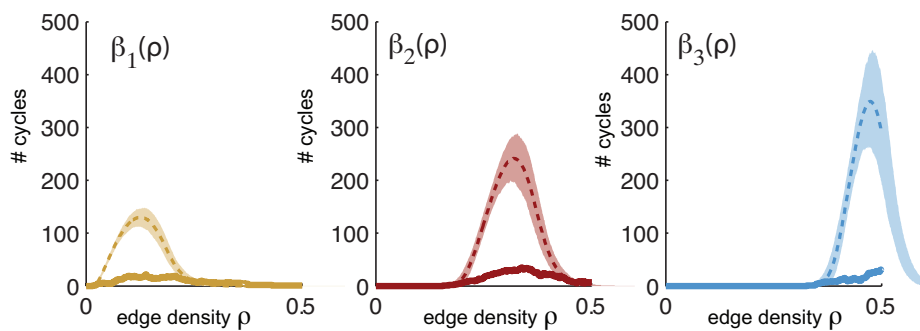
REM sleep



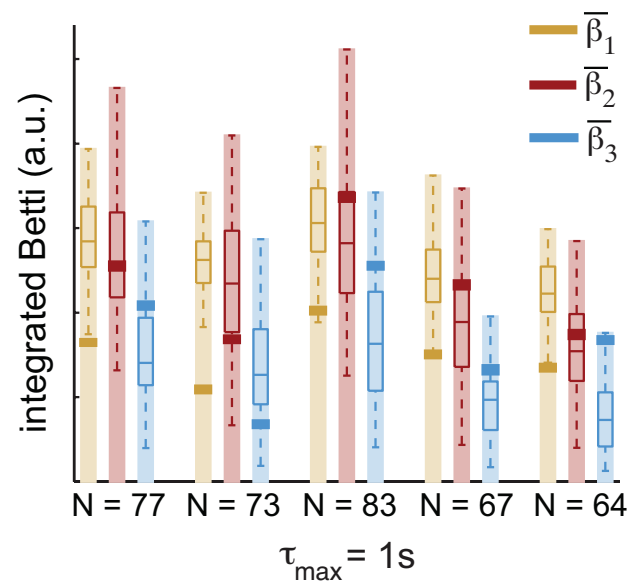
# Betti curves: wheel running vs. controls



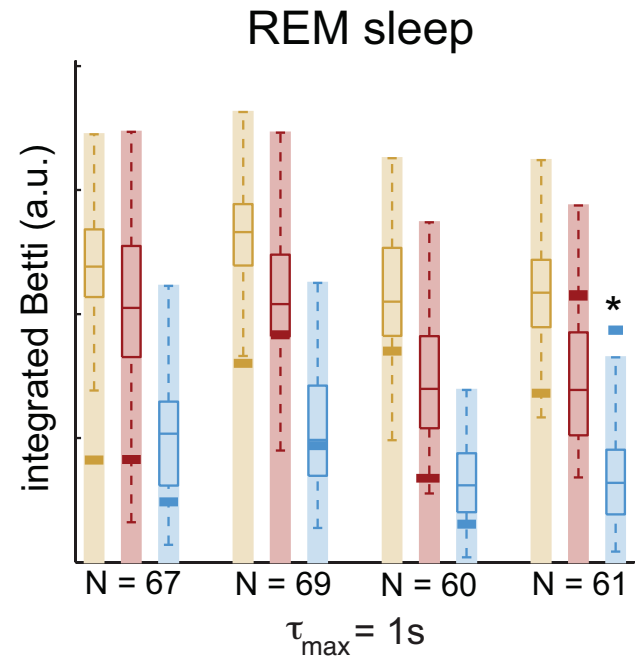
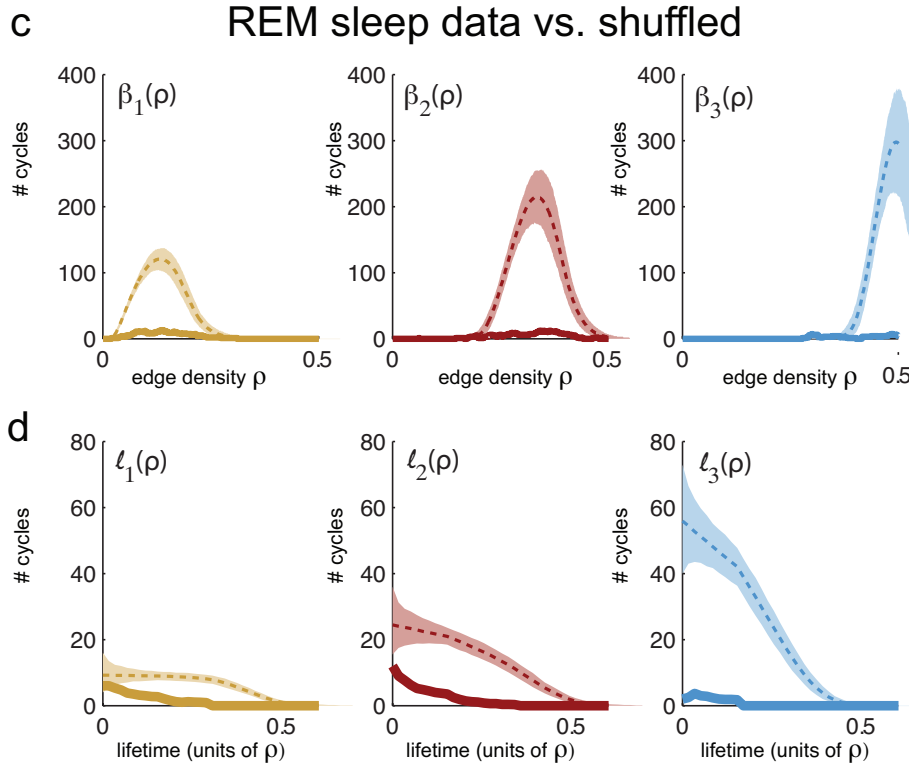
a Wheel-running data vs. shuffled



wheel running



# Betti curves: REM sleep vs. controls





The results look very similar across behavioral conditions...

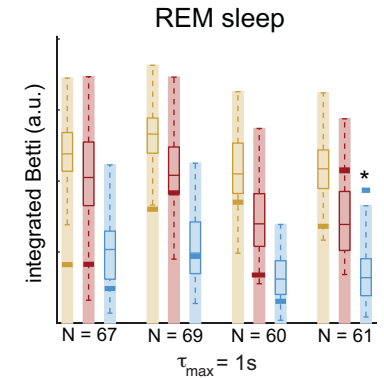
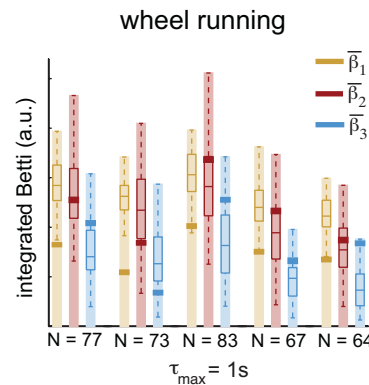
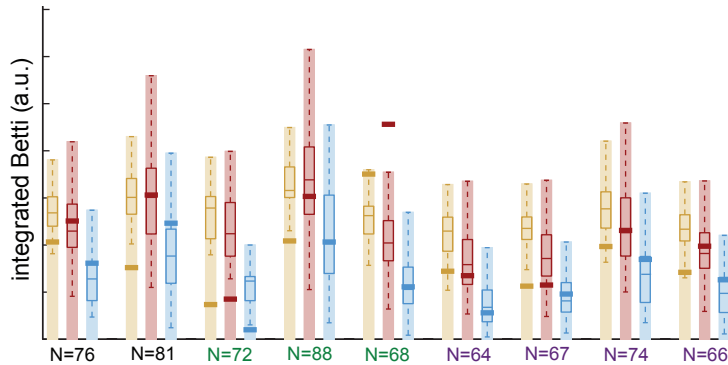
open field



wheel running



REM sleep



## Conclusion:

The "geometric" correlation structure appears to be a property of the network, not just of the inputs.

The results look very similar across behavioral conditions...

open field



wheel running



REM sleep

