#### ELLIPTIC VARIATIONAL PROBLEMS

David Jerison (MIT)

Jan 2017

**MSRI** Lecture 1

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## **Elliptic Variational Problems**

1st variation and singular limits2nd variation and stability

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- Ist variation and singular limits
- 2nd variation and stability
- Free boundary regularity n = 3, 4

## **Elliptic Variational Problems**

- Ist variation and singular limits
- 2nd variation and stability
- Free boundary regularity n = 3, 4
- Higher critical points, topology
- Higher dimensions;  $n \rightarrow \infty$  ?

$$J(v) := \int [|\nabla v|^2 + F(v)]$$
  
First variation  $J'(u) = -2\Delta u + F'(u)$ 

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$$J(\mathbf{v}) := \int [|\nabla \mathbf{v}|^2 + F(\mathbf{v})]$$
  
First variation  $J'(u) = -2\Delta u + F'(u)$ 

$$J(u + \varepsilon v) =$$

$$J(u) + \varepsilon \int [2\nabla u \cdot \nabla v + F'(u)v] + O(\varepsilon^{2})$$

$$= J(u) + \varepsilon \langle -2\Delta u + F'(u), v \rangle + O(\varepsilon^{2}).$$

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# **CRITICAL POINTS** $J'(u) = -2\Delta u + F'(u) = 0$

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## **CRITICAL POINTS** $J'(u) = -2\Delta u + F'(u) = 0$

## Euler-Lagrange eq'n: $2\Delta u = F'(u)$

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## Blow down limit

$$F(v) = 0, v \leq 0, F(v) = 1, v \geq a.$$
  
 $v_R(y) = \frac{1}{R}v(Ry) \longrightarrow v_{\infty}(y), R \to \infty$ 

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## Blow down limit

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 $v_R(y) = \frac{1}{R}v(Ry) \longrightarrow v_{\infty}(y), R \to \infty$ 

$$\int_{B_R} [|\nabla v|^2 + F(v)] \frac{dx}{R^n}$$
$$\longrightarrow \int_{B_1} [|\nabla v_{\infty}|^2 + \mathbb{1}_{\{v_{\infty}>0\}}] dy$$

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## **Alt-Caffarelli functional**

# $J_{\infty}(v,\Omega) = \int_{\Omega} [|\nabla v|^2 + 1_{\{v>0\}}] dy$ $F_{\infty}(v) = 1_{\{v>0\}}$

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## **Optimal Insulation**

$$\mathsf{Cost} = c_1 \int_R |\nabla u|^2 + c_2 \, \operatorname{vol}(R)$$

Equilibrium temperature u:

$$\Delta u = 0$$
 on  $R = \{T_0 < u < T_1\}$ 

## **Optimal Insulation**

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Equilibrium temperature u:

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 on  $R = \{T_0 < u < T_1\}$ 

## $\partial u/\partial v = \text{const}$ on $\{u = T_0\}$

## **Global Minimizers**

Functions  $u: \mathbf{R}^n \to \mathbf{R}$  such that

$$J(u,\Omega) = \min_{v} J(v,\Omega)$$
 and all  $\Omega \subset \subset \mathbf{R}^{n}$ ,

min over all v such that v = u on  $\partial \Omega$ .

$$J(\boldsymbol{v},\Omega) = \int_{\Omega} (|\nabla \boldsymbol{v}|^2 + \mathbf{1}_{\{\boldsymbol{v}>0\}}) \, d\boldsymbol{x}$$

## Rescaled Euler-Lagrange Equation $u_R(x) := u(Rx)/R$ $2\Delta u_R = RF'(Ru_R) \longrightarrow "2\Delta u_{\infty} = \delta(u_{\infty})"$

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Rescaled Euler-Lagrange Equation  

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One phase:  $u^- \equiv 0$ . Two phase:  $u^- \not\equiv 0$ .

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## How about $\Delta u = f(u)$ , $\int f du = 0$ ?

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## How about $\Delta u = f(u)$ , $\int f \, du = 0$ ? 2 wells: F > 0, |u| < a, F(u) = 0, $|u| \ge a$ .

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## How about $\Delta u = f(u)$ , $\int f \, du = 0$ ? 2 wells: F > 0, |u| < a, F(u) = 0, $|u| \ge a$ .

$$w_R(y) = v(Ry) \longrightarrow w_{\infty}(y), \quad R \to \infty$$
  
 $\int_{B_R} [|\nabla v|^2 + F(v)] \frac{dx}{R^{n-1}}$   
 $\longrightarrow c \operatorname{vol}_{n-1}(B_1 \cap \{|w_{\infty}| < a\})$ 

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## How about $\Delta u = f(u)$ , $\int f \, du = 0$ ? 2 wells: F > 0, |u| < a, F(u) = 0, $|u| \ge a$ .

$$w_{R}(y) = v(Ry) \longrightarrow w_{\infty}(y), \quad R \to \infty$$
$$\int_{B_{R}} [|\nabla v|^{2} + F(v)] \frac{dx}{R^{n-1}}$$
$$\longrightarrow c \operatorname{vol}_{n-1}(B_{1} \cap \{|w_{\infty}| < a\})$$

 $J_{\infty}$  is the area of the  $\pm a$  interface.

#### **Euler-Lagrange equation**

If F has "one hump", and

$$\int_{\mathbf{R}} F(w) \, dw = 1, \quad \text{then}$$

 $2\Delta w_R = R^2 F'(Rw_R) \longrightarrow "2\Delta w_{\infty} = \delta'(w_{\infty})"$ 

 $w_{\infty} = \pm a$  and H = 0 on the interface.

#### **Euler-Lagrange equation**

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## What can minimal surface theory teach us?

**Def'n.** Area-minimizer  $M \subset B_1 \subset \mathbb{R}^n$  $\operatorname{vol}_{n-1}(M) \leq \operatorname{vol}_{n-1}(N)$  all  $N, \ \partial N = \partial M$ 

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**Def'n.** Area-minimizer  $M \subset B_1 \subset \mathbb{R}^n$   $\operatorname{vol}_{n-1}(M) \leq \operatorname{vol}_{n-1}(N)$  all  $N, \ \partial N = \partial M$ **Theorem.** (J. Simons 1967 + )

Area-minimizers are smooth for  $n \le 7$ . But for n = 8,

$$x_1^2 + \dots + x_4^2 = x_5^2 + \dots + x_8^2$$
 minimizes.

## Universal bounds, $n \le 7$

Suppose M is area-minimizing in  $B_1$ ,  $0 \in M$ . After rotation, in  $B_{1/100}$ ,

$$M = \{x_n = g(x')\}$$
$$|\nabla g| + |D^2 g| \le 100$$

## **Theorem.** Energy-minimizing free boundaries are smooth in $\mathbb{R}^n$ , n = 3, 4. (Caffarelli, J-, Kenig 2002; J-, Savin 2015)

**Theorem.** Energy-minimizing free boundaries are smooth in  $\mathbb{R}^n$ , n = 3, 4. (Caffarelli, J-, Kenig 2002; J-, Savin 2015) There are singular minimizing cones  $n \ge 7$ . (De Silva, J-, 2006)

Dimensions n = 5, 6 are open.

#### **STABILITY**

$$\frac{d^2}{d\varepsilon^2} \frac{J(u+\varepsilon v)|_{\varepsilon=0}}{= \int (2|\nabla v|^2 + F''(u)v^2) \, dx \ge 0}$$

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## **STABILITY**

$$\frac{d^2}{d\varepsilon^2} \frac{J(u+\varepsilon v)|_{\varepsilon=0}}{= \int (2|\nabla v|^2 + F''(u)v^2) \, dx \ge 0}$$

Linearization of  $2\Delta u - F'(u) = 0$ 

$$\langle (-2\Delta + F''(u))v, v \rangle \geq 0$$

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## SUBSOLUTION METHOD

Positive subsolution  $\iff$  instability.  $Lv = (-2\Delta + F''(u))v < 0; v > 0 \text{ on } \Omega,$ and v = 0 on  $\partial\Omega$ , then  $0 > \int (Lv)v = \int (2|\nabla v|^2 + F''(u)v^2)$ 

$$0 > \int_{\Omega} (Lv)v = \int_{\Omega} (2|\nabla v|^2 + F''(u)v^2)$$

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$$\int_M f^2 |A|^2 \, d\mathrm{vol} \leq \int_M |\nabla f|^2 \, d\mathrm{vol}$$

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$$\int_M f^2 |A|^2 d\operatorname{vol} \leq \int_M |\nabla f|^2 d\operatorname{vol}$$

Instability  $\iff$  Positive subsolution:

 $\Delta f > |A|^2 f, \quad f \ge 0, \quad f \in C_0^\infty(M)$ 

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$$\int_M f^2 |A|^2 \, d ext{vol} \leq \int_M |
abla f|^2 \, d ext{vol}$$

Instability  $\iff$  Positive subsolution:

 $\Delta f > |A|^2 f, \quad f \ge 0, \quad f \in C_0^\infty(M)$ 

Simons: On cones

 $f=|A|\psi(|x|), \hspace{1em} \psi\in C_0^\infty({f R}_+)$ 

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$$\int_M f^2 |A|^2 \, d \operatorname{vol} \leq \int_M |\nabla f|^2 \, d \operatorname{vol}$$

Stability for energy-minimizing *u*:

$$\int_{\partial \Gamma} \phi^2 H \, d\sigma \leq \int_{\Gamma} |\nabla \phi|^2 \, dx$$
$$(\Gamma = \{u > 0\})$$

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Area instability  $\iff$  Positive subsolution:  $\Delta f > |A|^2 f, f \ge 0, f \in C_0^{\infty}(M)$ 

Energy instability  $\iff$  Pos. subsolution:  $\Delta \phi > 0$  in  $\Gamma$ ;  $\phi_v \ge H\phi$  in  $\partial \Gamma$ ;  $\phi \in C^{\infty}(\overline{\Gamma})$  $(\phi \ge 0)$
Simons: On cones  $f = |A|\psi(|x|), \quad \psi \in C_0^{\infty}(\mathbf{R}_+)$ Energy functional analogue:  $\varphi = |D^2 u|^{\alpha} \psi(|x|), \quad \psi \in C_0^{\infty}(\mathbf{R}_+)$ 

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Simons: On cones  $f = |A|\psi(|x|), \quad \psi \in C_0^{\infty}(\mathbf{R}_+)$ **Energy functional analogue:**  $\phi = |D^2 u|^{lpha} \psi(|x|), \quad \psi \in C_0^{\infty}(\mathsf{R}_+)$ Goal:  $\phi > 0$ ,  $\Delta \phi > 0$  on  $\Gamma$ ;  $\phi_v > H\phi$  on  $\partial \Gamma$ 

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## Plan

- Ist and 2nd variations
- Stability and subsolutions
- Free boundary regularity for n = 3, 4
- Higher critical points, topology
- Higher dimensions;  $n \rightarrow \infty$  ?

## **WARM-UP:** Optimal $\alpha > 0$ for which $\Delta u = 0 \implies \Delta |D^k u|^{\alpha} \ge 0$ (Cald.-Zyg)

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# **WARM-UP:** Optimal $\alpha > 0$ for which $\Delta u = 0 \implies \Delta |D^k u|^{\alpha} \ge 0$ (Cald.-Zyg) $w = |Du| \implies \Delta w^{\alpha} \ge 0, \quad \alpha = 1 - \frac{1}{n-1}$ $(\Delta(\log w) \ge 0, n = 2.)$

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$$w^{2} = \sum_{j} u_{j}^{2} \implies 2ww_{k} = 2\sum_{j} u_{j}u_{jk}$$
$$w\Delta w + |\nabla w|^{2} = |D^{2}u|^{2}$$

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$$w\Delta w + |\nabla w|^{2} = |D^{2}u|^{2}$$

$$D^2 u = \operatorname{diag}[\lambda_1, \ldots, \lambda_n]$$

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$$w\Delta w + |\nabla w|^{2} = |D^{2}u|^{2}$$

$$D^2 u = \operatorname{diag}[\lambda_1, \ldots, \lambda_n]$$

$$w_k = \lambda_k u_k / w \implies |\nabla w|^2 \le \max_k \lambda_k^2$$

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Since  $\Delta u = 0$ ,

$$\lambda_n^2 = (\lambda_1 + \cdots + \lambda_{n-1})^2 \leq (n-1)(\lambda_1^2 + \cdots + \lambda_{n-1}^2)$$

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Since 
$$\Delta u = 0$$
,  
 $\lambda_n^2 = (\lambda_1 + \dots + \lambda_{n-1})^2 \le (n-1)(\lambda_1^2 + \dots + \lambda_{n-1}^2)$   
 $\lambda_n^2 = \frac{1}{n}\lambda_n^2 + \frac{n-1}{n}\lambda_n^2 \le \frac{n-1}{n}(\lambda_1^2 + \dots + \lambda_n^2)$   
 $= \frac{n-1}{n}|D^2u|^2$ 

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Since 
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 $\lambda_n^2 = \frac{1}{n}\lambda_n^2 + \frac{n-1}{n}\lambda_n^2 \le \frac{n-1}{n}(\lambda_1^2 + \dots + \lambda_n^2)$   
 $= \frac{n-1}{n}|D^2u|^2$   
 $|\nabla w|^2 \le \max_k \lambda_k^2 \le \frac{n-1}{n}|D^2u|^2$ 

$$w\Delta w + |\nabla w|^2 = |D^2 u|^2 \ge \frac{n}{n-1} |\nabla w|^2$$

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$$egin{aligned} & w\Delta w + |
abla w|^2 = |D^2 u|^2 \geq rac{n}{n-1} |
abla w|^2 \ & w\Delta w \geq rac{1}{n-1} |
abla w|^2 \ & \Delta w^lpha \geq 0, \quad lpha = 1 - rac{1}{n-1}. \end{aligned}$$

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#### MSRI Lecture 2: Free Boundary Regularity

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# Regularity of free boundary energy minimizers

n = 2, Alt, Caffarelli, Friedman (ACF) 1984 n = 3, Caffarelli, Jerison, Kenig (CJK) 2002 n = 4, Jerison, Savin 2015

## **Theorem** If $n \le 4$ and u minimizes $J(v) := \int_{B} [|\nabla v|^{2} + 1_{v>0}] dx, \quad B \subset \mathbf{R}^{n},$

among all v = u on  $\partial B$ , then

$$\begin{split} B \cap \partial \{u > 0\} & \text{is smooth;} \\ \Delta u = 0 & \text{in } \{u > 0\} \text{ and } \{u \leq 0\}^{\circ}; \\ |\nabla u^+|^2 - |\nabla u^-|^2 = 1 & \text{on } B \cap \partial \{u > 0\}. \end{split}$$

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## **Proof Outline**

- Blow up limits exist (ACF monotonicity)
- Limits are cones (Weiss monotonicity)
- Two-phase limits are planar (ACF)
- Characterize one-phase limits
- Flat implies smooth (Caffarelli)

## **Proof Outline**

- Blow up limits exist (ACF monotonicity)
- Limits are cones (Weiss monotonicity)
- Two-phase limits are planar (ACF)
- One-phase limits are planar!
- Flat implies smooth (Caffarelli)

## **One-phase Limit: Stable Cone** $\Gamma$ $\Delta u = 0, u > 0, u(rx) = ru(x)$ in $\Gamma$ . u = 0 and $|\nabla u|^2 = 1$ on $\partial \Gamma$ .

$$\int_{\partial \Gamma} H \varphi^2 d\sigma \leq \int_{\Gamma} |
abla \varphi|^2 dx$$

By induction,  $S^{n-1} \cap \partial \Gamma$  is smooth. Moreover, we will only need test functions  $\varphi \ge 0$ ,

$$\varphi \in C_0^{\infty}(U \cap \overline{\Gamma}),$$
$$U = \{0 < a < |x| < b\}.$$

## Mean Curvature H

Rotate and translate so locally

$$egin{aligned} & \Gamma = \{x_n > g(x')\}, \quad 
abla g(0) = 0. \end{aligned}$$
 Then  $u(x',g(x')) = 0$  implies for  $i, j < n, u_j = 0, \quad u_{ij} = -u_n g_{ij} = -g_{ij} \quad ext{at } 0. \end{aligned}$ 

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## Mean Curvature H

Rotate and translate so locally

$$\Gamma = \{x_n > g(x')\}, \quad \nabla g(0) = 0.$$
  
Then  $u(x', g(x')) = 0$  implies for  $i, j < n$ ,  
 $u_j = 0, \quad u_{ij} = -u_n g_{ij} = -g_{ij}$  at 0.  
$$\Delta u = 0 \implies u_{nn} = \sum_i g_{jj} = :-H.$$

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# $\Delta | abla u|^2 \ge 0$ and $| abla u|^2$ bounded in $\Gamma$ imply $| abla u|^2 \le 1$ (Maximum principle)

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 $\Delta |
abla u|^2 \ge 0$  and  $|
abla u|^2$  bounded in  $\Gamma$  imply $|
abla u|^2 \le 1$  (Maximum principle)

## $\partial_n |\nabla u|^2 < 0$ (Hopf lemma)

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 $\Delta |
abla u|^2 \ge 0$  and  $|
abla u|^2$  bounded in  $\Gamma$  imply $|
abla u|^2 \le 1$  (Maximum principle)

$$\partial_n |\nabla u|^2 < 0$$
 (Hopf lemma)

$$\partial_n |\nabla u|^2 = \sum_j 2u_j u_{nj} = 2u_{nn} = -2H.$$
  
Hence  $-u_{vv} = H > 0.$ 

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$$u_{\varepsilon} = (u - \varepsilon \varphi)^{+}, \ S_{\varepsilon} = \{0 < u < \varepsilon \varphi\}.$$
  
$$J(u_{\varepsilon}) = J(u) - 2\varepsilon \int_{\Gamma} \nabla u \cdot \nabla \varphi + \varepsilon^{2} \int_{\Gamma} |\nabla \varphi|^{2}$$
  
$$- \int_{S_{\varepsilon}} [|\nabla u|^{2} + 1] + 2\varepsilon \int_{S_{\varepsilon}} \nabla u \cdot \nabla \varphi + O(\varepsilon^{3}).$$

$$u_{\varepsilon} = (u - \varepsilon \varphi)^{+}, \ S_{\varepsilon} = \{0 < u < \varepsilon \varphi\}.$$
  
$$J(u_{\varepsilon}) = J(u) + 2\varepsilon \int_{\partial \Gamma} \varphi \, d\sigma + \varepsilon^{2} \int_{\Gamma} |\nabla \varphi|^{2}$$
  
$$- \int_{S_{\varepsilon}} [|\nabla u|^{2} + 1] + 2\varepsilon \int_{S_{\varepsilon}} \nabla u \cdot \nabla \varphi + O(\varepsilon^{3}).$$

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$$u_{\varepsilon} = (u - \varepsilon \varphi)^{+}, \ S_{\varepsilon} = \{0 < u < \varepsilon \varphi\}.$$
  
$$J(u_{\varepsilon}) = J(u) + 2\varepsilon \int_{\partial \Gamma} \varphi \, d\sigma + \varepsilon^{2} \int_{\Gamma} |\nabla \varphi|^{2}$$
  
$$- \int_{S_{\varepsilon}} [|\nabla u|^{2} + 1] + 2\varepsilon^{2} \int_{\partial \Gamma} \varphi \phi_{v} \, d\sigma + O(\varepsilon^{3}).$$

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 $egin{aligned} x_t &= x_0 - t 
u \ (
u ext{ inner unit normal}) \ dx &= (1 + t H + O(t^2)) dt d\sigma, \ |
abla u(x_t)|^2 &= 1 - 2t H + O(t^2). \end{aligned}$ 

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 $S_{\varepsilon}: 0 < u < \varepsilon \phi \iff 0 < t < \overline{t},$  $\overline{t} = \varepsilon \phi + \varepsilon^2 \left( \frac{H}{2} \phi^2 - \phi \phi_{\nu} \right) + O(\varepsilon^3).$ 

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### **SUMMARY**

If *u* is a critical point and  $u_{\varepsilon} = (u - \varepsilon \phi)^+$ ,

$$J(u_{\varepsilon}) - J(u) = \varepsilon^{2} \int_{\Gamma} |\nabla \varphi|^{2} - \varepsilon^{2} \int_{\partial \Gamma} H \varphi^{2} d\sigma + O(\varepsilon^{3})$$

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## **SUBSOLUTION:** $U = \{a < |x| < b\}$ . $\phi \in C_0^{\infty}(U), \ \phi \ge 0.$

 $\Delta \phi \geq 0 \text{ in } U \cap \Gamma, \quad \phi_v \geq -H \phi \text{ on } \partial \Gamma.$ 

**SUBSOLUTION:**  $U = \{a < |x| < b\}$ .  $\phi \in C_0^{\infty}(U), \ \phi \ge 0.$ 

 $\Delta \phi \geq 0$  in  $U \cap \Gamma$ ,  $\phi_v \geq -H\phi$  on  $\partial \Gamma$ .

$$\begin{split} \int_{U\cap\Gamma} |\nabla \varphi|^2 &= -\int_{U\cap\Gamma} \varphi \Delta \varphi - \int_{\partial\Gamma} \varphi \varphi_{\nu} \, d\sigma \\ &\leq \int_{\partial\Gamma} H \varphi^2 \, d\sigma. \end{split}$$

For instability, we need strictness somewhere.

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$$w^2 := |D^2 u|^2 = \sum_{k\ell} u_{k\ell}^2$$
.  
 $\phi = w^{lpha} \psi(|x|), \quad 0 \le \psi \in C_0^{\infty}(\mathbf{R}_+)$   
If  $n = 3$ ,  
 $(w^{lpha})_{v} = -2\alpha H w^{lpha} \implies \phi_{v} = -2\alpha H \phi$   
Hence  $\phi_{v} \ge -H\phi$  for  $\alpha \le 1/2$ .

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## Rotate so $D^2g(x_0)$ is diagonal. Differentiating $|\nabla u(x',g(x'))|^2 = 1$ gives

$$u_{in} = 0, \quad u_{ijn} = 0 \quad i, j < n, i \neq j,$$
  
 $u_{iin} = u_{nn}u_{ii} - u_{ii}^{2}, \quad u_{nnn} = \sum u_{kk}^{2}.$ 

Rotate so  $D^2g(x_0)$  is diagonal. Differentiating  $|\nabla u(x',g(x'))|^2 = 1$  gives

$$u_{in} = 0, \quad u_{ijn} = 0 \quad i, j < n, i \neq j,$$
  
 $u_{iin} = u_{nn}u_{ii} - u_{ii}^2, \quad u_{nnn} = \sum u_{kk}^2.$ 

 $\partial_n \sum u_{k\ell}^2 = 2 \sum u_{k\ell} u_{k\ell n} = 2 \sum u_{kkn} u_{kk}.$ 

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Rotate so  $D^2g(x_0)$  is diagonal. Differentiating  $|\nabla u(x',g(x'))|^2 = 1$  gives

$$u_{in} = 0, \quad u_{ijn} = 0 \quad i, j < n, i \neq j,$$
  
 $u_{iin} = \lambda_n \lambda_i - \lambda_i^2, \quad u_{nnn} = \sum \lambda_k^2.$ 

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 $\partial_n(w^2) = -4Hw^2 - 2\sum \lambda_k^3 \ (= -4Hw^2, \ n=3).$ 

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# $egin{aligned} & \phi = w^lpha \psi(|x|), \quad 0 \leq \psi \in C_0^\infty(\mathbf{R}_+) \ & ext{If } n = 3, ext{ there is } \psi ext{ such that } \Delta \phi \geq 0 ext{ iff} \ & \Delta(w^lpha) \geq (lpha - 1/2)^2 w^lpha/|x|^2 \end{aligned}$

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 $egin{aligned} & \phi = w^lpha \psi(|x|), \quad 0 \leq \psi \in C_0^\infty(\mathbf{R}_+) \ & ext{If } n = 3, ext{ there is } \psi ext{ such that } \Delta \phi \geq 0 ext{ iff} \ & \Delta(w^lpha) \geq (lpha - 1/2)^2 w^lpha/|x|^2 \end{aligned}$ 

 $\Delta(w^{lpha}) \ge (lpha+1) lpha w^{lpha}/|x|^2, \quad lpha > 0.$ Hence  $\phi$  is a subsolution iff  $1/8 \le lpha \le 1/2$ .

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Compare our inequality for  $w = |D^2u|$ ,

$$\Delta(w^lpha) \geq lpha(lpha+1)rac{w^lpha}{|x|^2},$$

with Simons's inequality for w = |A|:

$$(\Delta+|A|^2)w\geq 2\frac{w}{|x|^2}.$$

 $\Delta$ , Laplace-Beltrami; A, 2nd fund. form

**Lemma** If *u* is harmonic,  $w = |D^2u|$ , then

$$w\Delta w \geq \frac{2}{n} |\nabla w|^2.$$

If, in addition, u(rx) = ru(x), then

$$w\Delta w \ge \frac{2}{n-1} |\nabla w|^2 + 2 \frac{n-2}{n-1} \frac{w^2}{|x|^2}.$$

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### **Bochner identities**

### $w^2 := \sum u_{k\ell}^2, \quad \Delta u = 0.$ $w\Delta w + |\nabla w|^2 = \Delta(w^2) = 2\sum u_{k\ell m}^2.$

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### **Bochner identities**

$$w^2 := \sum u_{k\ell}^2, \quad \Delta u = 0.$$
  
 $w\Delta w + |\nabla w|^2 = \Delta(w^2) = 2\sum u_{k\ell m}^2.$ 

$$w_m = \sum_{k\ell} u_{k\ell} u_{k\ell m} / w = \sum_k \lambda_k u_{kkm} / w.$$

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### For n = 4, $\alpha \ge 1/3$ works: $\Delta w^{1/3} \ge \frac{4}{9} \frac{w^{1/3}}{|x|^2}$

yields  $\Delta \phi \ge 0$  for appropriate  $\psi(|x|)$ .

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### For n = 4, $\alpha \ge 1/3$ works: $\Delta w^{1/3} \ge \frac{4}{9} \frac{w^{1/3}}{|x|^2}$

yields  $\Delta \phi \ge 0$  for appropriate  $\psi(|x|)$ . Unfortunately,

 $\phi_{\nu} \geq - \mathcal{H} \phi \quad \text{fails!}$ 

It's even worse for  $n \ge 5$ : no multiple of  $H\phi$  is a lower bound for  $\phi_v$ .

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# n=4: $\phi = w^{1/3} \psi(|x|)$ , new w $w = \left(\sum_{\lambda_j > 0} \lambda_j^2 + 4 \sum_{\lambda_k < 0} \lambda_k^2\right)^{1/2}$

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Lemma. Suppose 
$$\Delta u = 0$$
 and  $u(rx) = ru(x)$ . Let  $w = S(\lambda_1, \dots, \lambda_n)$ 

with S symmetric, convex and homogeneous degree 1, and  $\lambda_j$  the eigenvalues of  $D^2 u$ . Then

$$w\Delta w + |\nabla w|^2 \ge \frac{2}{n-1}|\nabla w|^2 + \frac{2(n-2)}{n-1}\frac{w^2}{|x|^2}$$

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### Eigenvalues of





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### Eigenvalues of





(and  $\lambda \pm \epsilon$ , if  $\lambda_1 = \lambda_2 = \lambda$ )

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### **Open Questions.**

Suppose that  $u: \Omega \to \mathbf{R}, \ \Omega \subset \mathbf{R}^n$ , and  $\Delta u = f(u).$ 

### What do level sets of *u* look like?

In Lecture 3, we will discuss n = 2, n = 3, and  $n \rightarrow \infty$  by analogy with minimal surfaces.

### Higher critical points, Isoperimetric sets

#### David Jerison (MIT)

#### MSRI, Lecture 3, Jan 2017

David Jerison Compactness and Singular Limits of Free Boundaries

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# What else do we learn from minimal surface theory?

Theorems of Colding-Minicozzi

### **C-M** Removable Singularities Theorem

 $\forall \delta > 0, \exists C$ , such that every minimal annulus

 $M \subset B_1 \setminus B_{\varepsilon}$ ;  $\partial M =$ two loops in  $\partial B_{\varepsilon} \cup \partial B_1$ ,

satisfies

M is a  $\delta$ -Lipschitz graph in  $B_{1/C} \setminus B_{C\epsilon}$ (Proof inserts stable surfaces) Thm 1. (J-, Kamburov) Let  $A^+ := \{u > 0\}$  be simply-connected in

annulus 
$$A=\{x\in {f R}^2: {f \epsilon}<|x|<1\},$$

and assume that the two strands of F connecting  $\partial D_1$  to  $\partial D_{\varepsilon}$  don't get close to each other.

Then  $\forall \delta > 0$ ,  $\exists C$  such that

*F* is a  $\delta$ -Lipschitz graph on  $C\epsilon < |x| < 1/C$ 

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*F* is a  $\delta$ -Lipschitz graph on  $C\epsilon < |x| < 1/C$ 

Significance: rules out spirals.

In particular,

### Flat implies Lipschitz

is valid for 2-dimensional, simply-connected phases with a small hole.

C-M Dichotomy for embedded minimal annuli.
a) curvature is bounded, or
b) near points of high curvature, they resemble catenoids: C-M Dichotomy for embedded minimal annuli.
a) curvature is bounded, or
b) near points of high curvature, they resemble catenoids:

If  $M \subset B_1 \subset \mathbf{R}^3$   $(\partial M = \text{two loops in } \partial B_1)$ 

has neck size  $\epsilon > 0$  near the origin, then

 $M \approx$  standard catenoid in  $|x| < \sqrt{\epsilon}$ .

**Thm 2. J-, Kamburov** There is c > 0 such that if  $0 \in \partial D^+$  and  $D^+$  is simply-connected, then either

 $B_c(0) \cap \partial D^+$  has one strand of bounded curvature or it resembles a piece of a double hairpin HHP

#### Hauswirth, Hélein, Pacard 2012

$$S = \{\zeta = \xi + i\eta : |\eta| \le \pi/2\}$$
  
 $\Omega := \varphi(S), \qquad \varphi(\zeta) = i(\zeta + \sinh \zeta).$ 

$${\it H}(z)={\sf Re}\ {\sf cosh}(\phi^{-1}(z))=({\sf cosh}\,\xi)({\sf cos}\,\eta)$$

#### Hauswirth, Hélein, Pacard 2012

$$S = \{\zeta = \xi + i\eta : |\eta| \le \pi/2\}$$
$$\Omega := \varphi(S), \qquad \varphi(\zeta) = i(\zeta + \sinh\zeta).$$
$$H(z) = \operatorname{Re} \cosh(\varphi^{-1}(z)) = (\cosh\xi)(\cos\eta)$$
$$H_a(z) = aH(z/a); \qquad \Omega_a = a\Omega$$

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Thm 3 (J-, Kamburov, Rigidity).  $\forall \delta > 0$ ,  $\exists c > 0$  such that if "neck size" is  $\varepsilon > 0$  near 0, then there is  $a \approx \varepsilon$ ,  $\psi : \Omega_a \cap B_c(0) \to D^+$ Near isometry: If |z| < c, then

 $|\psi'(z)-1|\leq \delta, \,\, z\in \Omega_{a}; \quad |\psi'(z)|=1, \,\, z\in \partial\Omega_{a}$ 

Thm 3 (J-, Kamburov, Rigidity).  $\forall \delta > 0$ ,  $\exists c > 0$  such that if "neck size" is  $\varepsilon > 0$  near 0, then there is  $a \approx \varepsilon$ ,  $\Psi : \Omega_a \cap B_c(0) \to D^+$ **Near isometry:** If |z| < c, then  $|\psi'(z)-1| \leq \delta, \ z \in \Omega_a; \quad |\psi'(z)| = 1, \ z \in \partial \Omega_a$ **Curvature bounds:** If |z| < c, then  $|\Psi''(z)| < \delta, z \in \Omega_a; \quad |\kappa(\Psi(z)) - \kappa_a(z)| < \delta; z \in \partial \Omega_a$ 

Colding-Minicozzi: Embedded minimal annulus

 $M \subset B_1 \subset \mathbf{R}^3$  with neck size  $\varepsilon > 0$ ,

satisfies  $M \approx$  standard catenoid,  $|x| < \sqrt{\epsilon}$ 

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 $\sqrt{\varepsilon} \leq |x| < 1/C.$ 

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 $\sqrt{\varepsilon} \leq |x| < 1/C.$ 

Traizet correspondence: free boundary solutions  $\leftrightarrow$  minimal surfaces with reflection symmetry The two theorems overlap in an easy, but illustrative special case.

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# **TRAIZET CORRESPONDENCE** $dX_1 + idX_2 = \frac{1}{2}d\bar{z} - 2\left(\frac{\partial u}{\partial z}\right)^2 dz$ $z \mapsto (X_1, X_2, \pm u(z))$

The image is an immersed minimal surface with symmetry  $x_3 \leftrightarrow -x_3$ . Moreover,

$$|
abla u| < 1 \iff \mathsf{embedded}$$

### **Open Questions.**

### Suppose that $u: \mathbf{R}^3 \to \mathbf{R}, f \in C^\infty_0(\mathbf{R}),$ $\Delta u = f(u).$

### What do the level sets of *u* look like?

### **Open Questions.**

Suppose that  $u: \mathbf{R}^3 \to \mathbf{R}, f \in C_0^{\infty}(\mathbf{R}),$  $\Delta u = f(u).$ 

#### What do the level sets of *u* look like?

**Conjecture 1.** If  $\{u > 0\}$  and  $\{u \le 0\}$  are contractible, then  $u = w(a \cdot x)$ .

**Conjecture 2.** (De Giorgi/Calabi-Yau type): Suppose  $\Delta u = f(u)$  in  $\mathbb{R}^3$ ,  $\nabla u \neq 0$ , and/or u has finite topology level sets. If one level set is contained in a half space,

$$\{u=0\} \subset \{x_3>0\},\$$

then

$$u(x)=w(x_3)$$

### What estimates work for all *n*?

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## What estimates work for all *n*? Bombieri-Giusti/Almgren, De Giorgi Quantitative connectivity:

$$\left(\int_{B(cr)} |f-\bar{f}|^p \, d\sigma\right)^{1/p} \leq C \int_{B(r)} |\nabla f| \, d\sigma$$

## **Bombieri-Giusti** 1972 **Scale-invariant Harnack:**

$$\sup_{B(r)} u \le C \inf_{B(r)} u$$

for positive solutions to Laplace-Beltrami

$$\Delta u = 0.$$

## Bombieri-Giusti 1972 Scale-invariant Harnack:

$$\sup_{B(r)} u \le C \inf_{B(r)} u$$

for positive solutions to Laplace-Beltrami

$$\Delta u = 0.$$

**Corollary.** A global area-minimizing surface in a half-space is a hyperplane. (Miranda)

**Conjecture 3.** Isoperimetric subsets of symmetric convex bodies are contractible: bounded by smooth graphs in all dimensions.

**Conjecture 3.** Isoperimetric subsets of symmetric convex bodies are contractible: bounded by smooth graphs in all dimensions.

Neumann boundary condition implies no Simons cone!

#### **Sternberg-Zumbrun** 1990-92 **Connectivity in isoperimetric case**

$$\left(\int_{B(r)} |f|^2 d\sigma\right)^{1/p} \leq C(r) \int_{B(r)} |\nabla f|^2 d\sigma,$$

 $f \in C_0^{\infty}(B(r))$ , using stability.

## **G. David, DJ** (work in progress) **Another version of connectivity:** Intrinsic distance $\approx$ extrinsic distance

**G. David, DJ** (work in progress) **Another version of connectivity:** Intrinsic distance  $\approx$  extrinsic distance

The embedding is proper = key step in CM proof of Calabi-Yau conjecture.

#### Why does connectivity help?

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**Bombieri, De Giorgi, Miranda** 1969: The  $L^{\infty}$  bound on a minimal graph implies a Lipschitz bound (hence a  $C^{\infty}$  bound).

#### Why does connectivity help?

**Bombieri, De Giorgi, Miranda** 1969: The  $L^{\infty}$  bound on a minimal graph implies a Lipschitz bound (hence a  $C^{\infty}$  bound).

2006 proof using Harnack by De Silva, J-. Also valid in free boundary setting **Conjecture 4.** There is c < 1 such that if  $\Omega$  is convex, symmetric and  $E \subset \Omega$  has least perimeter for  $|E| = |\Omega|/2$ , then

$$\Omega \cap \partial E \subset \{-a < x_n < a\},\$$
$$|\Omega \cap \{-a < x_n < a\}| \le c |\Omega|.$$

**C. Borell** 1975. Isoperimetric subsets of gauss space are half spaces for all *n*.

**S. G. Bobkov** 1999. Isoperimetric subsets for log-concave densities on the real line are half lines.

# Hot spots conjecture of J. Rauch. The hottest spot of an insulated region tends to the boundary as $t \rightarrow \infty$ .

Hot spots conjecture of J. Rauch. The hottest spot of an insulated region tends to the boundary as  $t \rightarrow \infty$ . My favorite version: The first nontrivial Neumann eigenfunction of a symmetric convex domain is monotone in some direction.

**KLS Conjecture** A least perimeter bisector of a convex set has area comparable to the best bisecting hypersurface.

December 2016 progress by Lee and Vempala

**KLS Conjecture** A least perimeter bisector of a convex set has area comparable to the best bisecting hypersurface.

December 2016 progress by Lee and Vempala Our Conjecture 3 is that the extremal interface is a Lipschitz graph, that is, it resembles a hyperplane.