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NOTETAKER CHECKLIST FORM

(Complete one for each talk.)

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Speaker's Name: Jeremy Mason

Talk Title: Predictive simulation of grain structure evolution

Time: <u>11</u>:00 and / pm (circle one) Date: 10 /05 /2018

Please summarize the lecture in 5 or fewer sentences:

Expansion the sets of grain boundary topologies and topological transitions to formulate a physical criterion for the selection of a topological transition. Development of equations of motion suitable for arbitrary grain boundary energies and mobilities. Preparation of a front-tracking code able to perform predictive simulations of grain structure evolution.

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MSRI Hot Topics: Shape and Structure of Materials

Predictive simulations of grain structure evolution 5 October 2018

Jeremy Mason Erdem Eren



Grains and Boundaries





An Idealized Model

Studies of this system usually use the following assumptions:

- Boundary mobility and energy are constants
- Boundaries are smooth surfaces
- System energy is proportional to overall boundary area
- Boundary junction lines and vertices do not have any properties except as specified by adjoining boundaries

Mo model system is defined gradient flow of the area function by the store of the area

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K. Brakke, The surface by its mean curvature, 197

C. Mantegazza et al. Ann. Sc. Norm. Super. Pisa Cl. Sci. 5 235 (2004).

A. Magni et al. Ann. Sc. Norm. Super. Pisa Cl. Sci. 5 117 (2016).

T. Ilmanen et al. arXiv:1407.4756 (2014). L. Kim et al. Ann. I. Fourier, **66** 43 (2017).

Grain Growth Structures



Topological properties: Two grains at an edge Three edges at a vertex Geometric properties: Vertex angles go to $2\pi/3$

$$\frac{\mathrm{d}A}{\mathrm{d}t} = \frac{\pi}{3}m\gamma(n-6)$$

Topological properties: Two grains at a face Three faces at an edge Four edges at a vertex $\frac{dV}{dt} =$ Geometric properties: Edge angles go to $2\pi/3$ Vertex angles go to $a\cos(-1/3)$

$$\frac{\mathrm{d}V}{\mathrm{d}t} = \frac{\pi}{3}m\gamma(\mathcal{M} - 6\mathcal{L})$$

Singularities

Simulations suggest that all singular events (topological transitions) are composed of three fundamental operations*:



Numerically convenient to supplement with two other operations:



*requires stability of trajectory around the singularity

Topology of the Structure

Seems to generically converge to a regular pure CW-complex

- CW-complex is a union of i-dimensional cells with disjoint interiors for $1 \le i \le n$
- Regular requires that the attaching maps be homeomorphisms
- Pure requires that every cell is in the closure of some *n*-cell



Excludes cells without lower adjacencies Valence conditions exclude arbitrary subdivisions Dual object is not a triangulation despite four-valent vertices

Self Similar Structure

Conjecture I: For almost all initial conditions, mean curvature flow eventually results in a self-similar structure Conjecture II: For almost all initial conditions with a self-similar structure, the self-similar structures are the same.



Self Similar Structure

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J. K. Mason et al. Phys Rev E 92 063308 (2015).



The Reality of the Situation: Part I

The idealized grain structure is not often observed in practice

- Grain boundary properties are neither uniform nor isotropic
- Surfaces are not even once differentiable
- Cell valence conditions are not satisfied
- Cannot assume well-behaved initial conditions



J. Min et al. J Manuf Sci E-T ASME **138** 054501-1 (2016). S. B. Lee Mater Metall Trans A **31A** 985 (2000). J. Min et al. J Manuf Sci E-T ASME **138** 054501-1 (2016). S. B. Lee Mater Metall Trans A **31A** 985 (2000).

Grain Boundary Misorientation

Grain boundary energy and mobility actually functions on a fivedimensional grain boundary space Three dimensions relate to the relative orientation of crystal lattices, or SO(3) is a 3-manifold



Grain Boundary Inclination

Grain boundary energy and mobility actually functions on a fivedimensional grain boundary space Two dimensions relate to the orientation of the boundary plane, or S^2 is a 2-manifold



Grain Boundary Energy

Early theoretical analysis suggests that function contains logarithmic singularities of the form $E = E_0 \theta [A - \log \theta]$

Most recent analysis is not substantially more complete



W. T. Read et al. Phys Rev **78** 275 (1950).

V. V. Bulatov et al. Acta Mater 65 161 (2014).

3D Microstructures

EBSD-FIB destructively images serial sections to make a reconstruction 3DXRD nondestructively uses synchrotron x-rays (available at ALS) to make a reconstruction

 $[10\overline{1}0]$

[0001]

 $[2\overline{1}\overline{1}0]$



J. Konrad et al. Acta Mater 54 1369 (2006).
G. Johnson et al., J Appl Crystalogr 41, 310 (2008).
P. Reischig et al., J Appl Crystalogr 46, 297 (2013).



Regression of the Energy Function

Can use 3D microstructures to reconstruct grain boundary energy

Junction lines in equilibrium satisfy the Herring equation

$$\sum_{i} \hat{t}_{i} \gamma(\hat{n}_{i}) + \hat{n}_{i} \frac{\partial \gamma}{\partial \phi} \bigg|_{\hat{n}_{i}} = 0$$

- Provides a system of equations for expansion coefficients
- Reduce measurement errors and improve basis functions



P. Reischig et al. J Appl Crystallogr **46** 297 (2013). A. Morawiec, Acta Mater 48 3525 (2000).

H. Beladi et al. Acta Mater 70 281 (2014).

Aside on Weighted Mean Curvature

The Young–Laplace equation states that the driving pressure is proportional to the surface energy and the mean curvature Implies a force exerted on an infinitesimal surface element

$$H = \kappa_1 + \kappa_2$$
 $p = \gamma H$ $\mathrm{d}\bar{F} = \hat{n}p\mathrm{d}A$

The mean curvature is the negative of the rate of change of area with respect to the volume swept out

$$\omega = \left(\gamma + \frac{\partial^2 \gamma}{\partial \theta^2}\right) \kappa_1 + \left(\gamma + \frac{\partial^2 \gamma}{\partial \phi^2}\right) \kappa_2 \qquad \mathrm{d}\bar{F} = \hat{n}\omega\mathrm{d}A$$

The weighted mean curvature is the negative of the rate of change of surface energy with respect to the volume swept out

J.E. Taylor, Acta Metall et Mater 40, 1475 (1992).

Equations of Motion: Part I

Given a 2D triangulation, search for local equations of motion for the general case

$$dF = \hat{n}\omega dA$$
$$\bar{F} = \lambda \sum_{i} \hat{t}_{i}\gamma(\hat{n}_{i}) + \hat{n}_{i}\frac{d\gamma}{d\phi}\Big|_{\hat{n}_{i}}$$
$$0 = \sum_{i} \hat{t}_{i}\gamma(\hat{n}_{i}) + \hat{n}_{i}\frac{d\gamma}{d\phi}\Big|_{\hat{n}_{i}}$$
$$\bar{F} = \lambda \left[\delta_{1}\bar{I} + \frac{1}{2}\sum_{i} \delta_{2}(\hat{n}_{i}) \|\bar{t}_{i}\| \hat{n}_{i} \otimes \hat{n}_{i} \right]$$



This is an equation of motion for arbitrary grain boundary junction lines

 \bar{v}

J.E. Taylor, Acta Metall et Mater **40**, 1475 (1992). J.K. Mason, Acta Mater 125, 286 (2017).

Equations of Motion: Part II

For arbitrary junction vertices, observe that the grain boundary energy has units of force per length \overline{t}

$$\begin{split} \bar{F} &= \sum_{i} \hat{t}_{i} \tau(\hat{t}_{i}) + \frac{1}{2} \left\| \bar{t}_{i} \right\|_{j:\{i,j\} \in \Delta} (\hat{n}_{ij} \times \hat{t}_{i}) \gamma(\hat{n}_{ij}) + \hat{n}_{ij} \frac{\partial \gamma}{\partial \phi_{i}} \right|_{\hat{n}_{ij}} \\ \bar{F} &= \left[\delta_{0} \bar{\bar{I}} + \frac{1}{2} \sum_{i} \delta_{1}(\hat{t}_{i}) \left\| \bar{t}_{i} \right\| (\bar{\bar{I}} - \hat{t}_{i} \otimes \hat{t}_{i}) \\ &+ \frac{1}{6} \sum_{\{i,j\} \in \Delta} \delta_{2}(\hat{n}_{ij}) \left\| \bar{t}_{i} \times \bar{t}_{j} \right\| \hat{n}_{ij} \otimes \hat{n}_{ij} \right] \bar{v} \end{split}$$

This is an equation of motion for arbitrary grain boundary junction vertices

J.K. Mason, Acta Mater 125, 286 (2017).

The Reality of the Situation: Part II

The idealized grain structure is not often observed in practice

- Grain boundary properties are neither uniform nor isotropic
- Surfaces are not even once differentiable
- Cell valence conditions are not satisfied
- Cannot assume well-behaved initial conditions

Some of these difficulties can already be resolved

- Grain boundary properties can be extracted from 3D microstructures imaged by EBSD-FIB or 3DXRD
- Equations of motion can handle facets and relaxed valence conditions (every triangle is considered as a facet)

What is the set of singularities that can be expected to occur? How can the topology of the resulting structures be described?

Relaxed Valence Conditions

Valence conditions should be as permissible as possible while maintaining correspondence to physical system

- 2-cell must have one or more upper adjacencies
- 1-cell must have three or more upper adjacencies
- 0-cell must have three or more upper adjacencies
- No restrictions on number of lower adjacencies



Singularities: Removal

Removal occurs when the Hausdorff measure of a cell vanishes



Implementation additionally requires that removal of mesh entities reduces the energy



Singularities: Creation

Initially assume that creation occurs only around a 0-cell Relaxed valence conditions allow more types of cell creation



Singularities: Creation

Construct adjacency graph of 2- and 3-cells

For the creation of a 1-cell

- Find a cycle that divides the graph into two nontrivial components For the creation of a 2-cell
- Select two 3-cells that do not share a 2-cell
- Construct non-intersecting paths with the 3-cells as endpoints



What is a reasonable criterion to select among allowed events?

Singularities: Energy Criterion

Principle: physical system selects the event that maximizes the rate of energy reduction (driving force)

- Project initial triangulation to a sphere centered on 0-cell, relax vertices to locations where tangential forces vanish
- Force is derivative of energy change with respect to radius



Spurious Cells

Numerical implementation integrates through singularities without substantially disturbing surrounding structure



Observations

- Simulation generated a surface that is not a 2-cell
- Appearance of this surface involved a configuration that violated valence conditions, requires additional topological operation



Conclusions

Ideal grain growth is the evolution of a regular pure CW-complex by gradient flow of the area functional



This is not a good approximation of the physical system where boundary properties are not uniform, surfaces are not smooth, etc.

Experimental limitations being resolved, require more accurate descriptions of these structures



If these structures are not cell complexes, what is the correct description of the allowed topologies? What other topological operations must be implemented to simulate evolution of the physical system?