

From Contexts to Competencies A K-12 to Post-Secondary Viewpoint Critical Issues in Mathematics Education







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TEDX









PADMANABHAN SESHAIYER

EDUCATION FOR ALL



















Padhu Seshaiyer

The M in STEM



https://www.youtube.com/watch?v=Ybxnfv2O3k4

Padhu Seshaiyer





What are some of the fundamental <u>competencies</u> needed for mathematical problem solving?

Respond at **PollEv.com/pseshaiyer217**

Text PSESHAIYER217 to 37607 once to join, then text your message

What are some of the fundamental <u>competencies</u> needed for mathematical problem solving?





Padmanabhan Seshaiyer George Mason University How many of the 16 movies can you find?





$$e^{i\pi} + 1 = 0$$

and
$$\frac{\partial u}{\partial t} - \alpha \nabla^2 u = 0$$
$$\left| \frac{ds}{dt} \right|$$
2.7182818284590452...
2.7182818284590452...

Padmanabhan Seshaiyer George Mason University How many of the 16 movies can you find?



What is "e" ?







2.7182818284590452



Fail early and often



"I have not failed, I've just found 10,000 ways that won't work"



- Thomas Edison



Use each circle and create an idea. Generate as many as you can (1 min)



Fluency



Fail Early and Fail Often

"I have not failed, I've just found 10,000 ways that won't work"



Failure doesn't mean you are a failure, it just means you have not succeeded yet.



nothing, it just means you have accomplished something.



Failure doesn't mean you will never be able to do it, it just means you have to do it in a different way.



Failure doesn't mean you have wasted your life, it just means you have to start afresh.



Failure doesn't mean you will never achieve, it just means it takes a little longer.



It's fine to celebrate success but it is more important to heed the lessons of failure.



What do you NOTICE?



- Not symmetric
- Grouping
- Orange wings
- Color patterns
- Beauty
- Wings like tiger
- Boundaries

What do you WONDER?



- Defense mechanism
- Where is it going
- Speed
- Fractal
- Alive
- Body weight

Monarch Butterfly Migration



Butterfly Life Cycle Coloring Sheet





CANADA

Eastern Migratio

Wintering sites Monarch breeding in U.S.& Canada

- Northern range of

United States

MEXICO

All ABout Monarchs!

Western Migration



BE-STREAMING Suriname South America

STEM STEAM STREAM



https://www.youtube.com/watch?v= uXf1sKiros&feature=youtu.be

We STREAM Movies We STREAM Audios We STREAM Videos

Let's start **STREAMING** Education!

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Try Typing this in Google



education makes me

Google Search

I'm Feeling Lucky

Here is what you will see...

education makes	s me		Ŷ
education makes education makes education makes	me depressed me me high		
	Google Search	I'm Feeling Lucky	
		Rep	ort inappropriate predictions Learn more







Students as Producers



Students as peer-reviewers

What are the 21st Century Skills?









Padhu Seshaiyer



A new philosophy: From Context to Competency





R E F E C Ι 0 N S

Modeling Division



Modeling Division



Modeling Division – Another Try



Modeling Division – Another Try



How many halves are in 4?

Padmanabhan Seshaiyer George Mason University Understanding Learning Styles

Passagiers in de Bus

⅓ deel van de passagiers stappen bij de eerste halte uit de bus. ⅓ deel van de rest gaan bij tweede halte uit de bus. Nu zijn er 5 passagiers in de bus. Hoeveel passagiers waren er in het begin in de bus? BE-STREAMING Videos

VISUAL See to Learn

Geheel = $\frac{3}{3}$ deel $\frac{3}{3}$ deel stapt uit Over/rest $\frac{3}{3} - \frac{1}{3} = \frac{2}{3}$ deel $\frac{3}{2}$ deel van de rest $\frac{3}{2} \times \frac{2}{3} = \frac{1}{3}$ deel Over is $\frac{2}{3} - \frac{1}{3} = \frac{1}{3}$ deel Over 5 passagiers = $\frac{1}{3}$ deel Geheel $\frac{3}{3}$ deel dus 3 x 5 = 15

s = 1/3 deer us 3 x 5 = 15 Correction 7/3 1

5 5 5 3 x 5 = 15



BREUKEN



KINESTHETIC Move to Learn

AUDITORY Hear to Learn
Which dog grew more?

 If one dog grows from 5 kg to 8 kg and another dog grows from 3 kg to 6 kg, which dog grew more?



Which is a better investment?

Pat: Invest \$300 → Receive \$600 Aaron: Invest \$500 → Receive \$800



Why?



Why the numbers matter?

RELATIVE RISK

EATING PROCESSED MEAT INCREASES THE RISK OF COLON CANCER 18% (5.9/5.0 = 1.18) RELATIVE RISK FOR SMOKING & CANCER IS 2300%

ABSOLUTE RISK

EATING PROCESSED MEAT INCREASED ASSOCIATED COLON CANCER INCIDENCE FROM 5 PER 100 TO 5.9 PER 100 (0.9% INCREASE)

RELATIVE RISK

"New wonder drug reduces heart attack risk 50%"

ABSOLUTE RISK

"New wonder drug reduced heart attacks from from 2 per 100 to 1 per 100"

Finding Dress Cost

• Four shirts and three pants cost \$37. Three shirts and four pants cost \$33. Find the cost of one shirt.



Finding Dress Cost

Four shirts and three pants cost \$37. Three shirts and four pants cost \$33. Find the cost of one shirt.



4S + 3P = 373S + 4P = 33

Finding Dress Cost

Four shirts and three pants cost \$37. Three shirts and four pants cost \$33. Find the cost of one shirt.



3S + 4P = 33

- Substitution
- Linear Addition
- Graphing
- Matrix Inverse
- Cramer's Rule
- Gaussian
 Elimination
- More...

Modeling dress cost

• Four shirts and three pants cost \$37. Three shirts and four pants cost \$33. Find the cost of one shirt.



4S + 3P = 375S + 2P = 416S + P = 457S = 49S = 7

How many squares do you see?



Teaching Moment



Padmanabhan Seshaiyer George Mason University How many squares do you see?

Padmanabhan Seshaiyer George Mason University How many squares do you see?



Padmanabhan Seshaiyer George Mason University How many squares do you see?







 $1^{2} + 2^{2} + 3^{2} + \dots + n^{2} = \frac{n(n+1)(2n+1)}{2n+1}$



Ε F F E C T I V Ε Ρ R A C T I C E S

SINGAPORE Teach less, Learn More

- Teacher-directed
- Direct Instruction
- Knowledge
- Content
- Basic Skills
- Facts and Principles
- Theory
- Curriculum
- Time-slotted
- One-size-fits-all
- Competitive
- Classroom
- Text-based
- Summative Tests
- Learning for School

- Learner-Centered
- Interactive exchange
- Skills
- Process
- Applied Skills
- Questions and Problems
- Practice
- Projects
- On-demand
- Personalized
- Collaborative
- Global Community
- Web-based
- Formative evaluations
- Learning for Life

FINLAND Learning by Doing



Finland's school system accomplishes some impressive feats:



JAPAN

Teachers' Activities to Improve Instruction



Experiential Learning



Innovative Learning







Innovative Learning







Inquiry-based Learning



Why do roofs fly?



Bernoulli's Principle





Learning by Doing



Collaborative Learning



Active Learning



Integrated Teaching



Padmanabhan Seshaiyer George Mason University Performance based Assessment Avaliação

FORMATIVE SUMMATIVE



WHEN THE GUESTS TASTE THE SOUP

@bryanMMathers

FROM STEVE WHEELER'S BLOG "THE AFL TRUTH ABOUT ASSESSMENT"

Differentiated Instruction Aprendizado diferenciado







Padmanabhan Seshaiyer George Mason University Problem Based Learning Rube-Goldberg Project Self-Operating Napkin



Padmanabhan Seshaiyer George Mason University Save the Turtles



Challenge Based Learning



Make solar energy economical



Provide energy from fusion



Develop carbon sequestration methods



Manage the nitrogen cycle



Provide access to clean water



Restore and improve urban infrastructure

Advance health informatics



Engineer better medicines



Reverse-engineer the brain



Prevent nuclear terror



Secure cyberspace

Enhance virtual reality



Advance personalized learning



Engineer the tools of scientific discovery



Challenge Based Learning








Disease Dynamics Modeling Identifying the threshold or tipping point (Kermack and McKendrick, 1927, 1932, 1933)

- Individuals are found in three stages
 - -Susceptible
 - –Infected
 - –Recovered



Susceptible

Mathematics of Spread of Disease





Padmanabhan, P., Seshaiyer, P., & Castillo-Chavez, C. (2017). Mathematical modeling, analysis and simulation of the spread of Zika with influence of sexual transmission and preventive measures. *Letters in Biomathematics*, *4*(1), 148-166.







George Mason University George Mason University

- Location: Houston, TX $\frac{dm_i^{\alpha}(t)}{dt} = \sum_{j=i,j\neq i}^s m_j^{\alpha}(t)w_{ij}^{\alpha}(t) m_i^{\alpha}(t)w_{ji}^{\alpha}(t) + P_i$
- Problem: Social Dynamics











Parameter Estimation





Posters on the Hill

Seshaiyer, P. (2017). Leading Undergraduate Research Projects in Mathematical Modeling. PRIMUS, 27(4-5), 476-493.

Global Problem Solving

- Location: Houston, TX
- Problem: Gang Recruitment

60



Age of Gang Members by Area Type, 2011 100 90 80 70 60 Percent 50 40 30 20 10 0 Larger Cities Suburban Counties Smaller Cities **Rural Counties** Juvenile (Under 18) Adult (18 and Over)

Rivera-Castro, M., Padmanabhan, P., Caiseda, C., Seshaiyer, P., & Boria-Guanill, C. (2019). Mathematical modelling, analysis and simulation of the spread of gangs in interacting youth and adult populations. Letters in Biomathematics, 1-19.

Global Problem Solving

- Location: Tanzania
- Problem: Poaching







Padmanabhan, P., Baez, A., Caiseda, C., McLane, K., Ellanki, N., Seshaiyer, P., Kwon, B. & Massawe, E. Design thinking and computational modeling to stop illegal poaching. In 2017 IEEE Integrated STEM Education Conference (ISEC) (pp. 175-181). IEEE.

Drones and Mathematics



credit: norunway.com





Why is this a rich STEM Problem?

- Dynamics and Mechanics
- Search Algorithms
- Sensors and Electronics
- Control Systems and Feedback
- Communications
- Swarming
- Mapping Algorithms
- Machine Learning





 Applications: Anti-poaching, Remote Sensing, Agriculture, Transporting materials, Oil-gas-mineral exploration, Search & Rescue, Surveillance and many more!

Studying Drone Dynamics using Design Thinking and Computational Mathematics https://sinews.siam.org/Details-Page/applying-design-thinking-to-mathematics-research-2

Drones and Mechanics



 $\begin{bmatrix} \ddot{x} \\ \ddot{y} \\ \ddot{z} \end{bmatrix} = \sum \frac{\mathbf{F}}{m} = \frac{1}{m} f_T \mathbf{R} \begin{bmatrix} 0 \\ 0 \\ \frac{4}{\sum_{i=1}^{4} \gamma_i^2} \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ g \end{bmatrix} + \frac{1}{m} f_D \begin{bmatrix} \dot{x} \\ \dot{y} \\ \dot{z} \end{bmatrix}$ $\begin{bmatrix} \dot{\omega}_{\phi} \\ \dot{\omega}_{\theta} \\ \dot{\omega}_{\theta} \\ \dot{\omega}_{\theta} \end{bmatrix} = \begin{bmatrix} I_{xx} & 0 & 0 \\ 0 & I_{yy} & 0 \\ 0 & 0 & I_{zz} \end{bmatrix}^{-1} \begin{bmatrix} \tau_{\phi} - (I_{zz} - I_{yy})\omega_{\theta}\omega_{\psi} \\ \tau_{\theta} - (I_{xx} - I_{zz})\omega_{\psi}\omega_{\phi} \\ \tau_{\psi} - (I_{yy} - I_{xx})\omega_{\phi}\omega_{\theta} \end{bmatrix}$



PD Control = $K_p e(t) + K_d \frac{d}{dt} e(t) \rightarrow \gamma = [\gamma_1, \gamma_2, \gamma_3, \gamma_4,]$







Drones and Target Detection





Target Detection

$$d_{a_i}^t = \left\{ egin{array}{ccc} 0 & ext{if } x_ au
eq a_i ext{ at time } t \ 1 & ext{if } x_ au = a_i ext{ at time } t \end{array}
ight.$$

Measurement Error

- β = missed detection (missing the poacher)
- α = false alarm (detecting something that's not there; a ranger. a cat, etc)

$$Bel(x_{\tau}) = Pr(x_{\tau} = a_k | D^t) = \frac{Pr(d_k^t | x_{\tau} = a_k, D^{t-1})Pr(x_{\tau} = a_k | D^{t-1})}{Pr(d_k^t | D^{t-1})}$$

Theorem

For a uniform distribution, the belief function:

$$Pr(x_{\tau} \in A | D^{t} = \mathbf{0}) = \frac{t\beta\delta + (1-\alpha)(|A|-t)\delta}{t\beta\delta + (1-\alpha)(|A|-t\delta)}$$

converges to the prior belief, δ .

	0.5		Belief Fur	nction alpha=0.1,	beta=0.2		
Bellef Function, B	0.45 -	-					-
	0.4 -						-
	0.35	(-
	0.3 -	1					-
	0.25						-
	0.2 -						-
	0.15						-
	0.1						-
	0.05 -						-
	0	5	10	15	20	25	30
				Gridsize			



Padmanabhan Seshaiyer George Mason University Innovation to Entrepreneurship Zika-Gangs-Opioids-Wearables





Multidisciplinary Approach to Engage Diverse Learner in Applied Mathematics Education

- As concluded by the National Research Council: Undergraduate education will not change in a permanent way through the efforts of "Lone Rangers." Change requires ongoing interaction among communities of people and institutions that will reinforce and drive reform.
- Research that happens across traditional STEM disciplines and at the edges of traditional disciplines.
- Here is the problem,

find the Mathematics to solve it!



Virtual Event

CINA Distinguished Speaker Series

Mathematics for Solving Global Challenges Involving Criminal Activities

Date: Thursday April 30rd, 2020 Time: 12:00-1:30pm Location: Virtual Event



Featuring:

RSVP and livestream link at cina.gmu.edu/cinaseries

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https://www.youtube.com/watch?v=Ybxnfv2O3k4